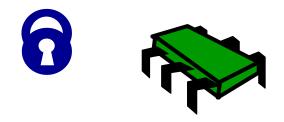


FOUNDATIONS OF CONCURRENT AND DISTRIBUTED SYSTEMS - LINKED LISTS: LOCKING, LOCK-FREE, AND BEYOND -

Prof. Christof Fetzer TU Dresden

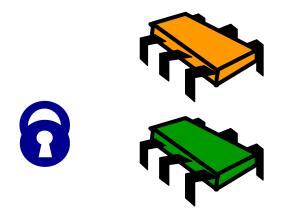
► Adding threads...

- Should not lower throughput
 - Contention effects
 - Mostly fixed by queue locks
 - > Overhead to acquire the lock:



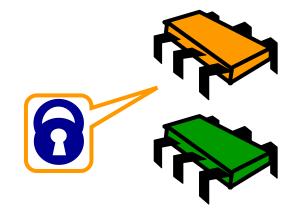
- ➤ we look at **futex** a later lecture and briefly discuss queue locks.
- Should increase throughput
 - Not possible if inherently sequential
 - Surprising things are parallelizable

- ► Adding threads...
- Should not lower throughput
 - Contention effects
 - Mostly fixed by queue locks
 - > Overhead to acquire the lock:



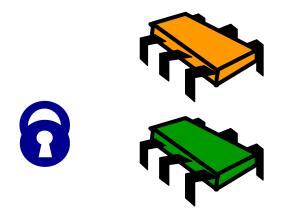
- ➤ we look at **futex** a later lecture and briefly discuss queue locks.
- ► Should increase throughput
 - Not possible if inherently sequential
 - Surprising things are parallelizable

- ► Adding threads...
- Should not lower throughput
 - Contention effects
 - Mostly fixed by queue locks
 - > Overhead to acquire the lock:



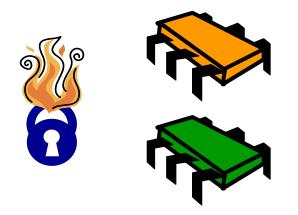
- ➤ we look at **futex** a later lecture and briefly discuss queue locks.
- ► Should increase throughput
 - ► Not possible if inherently sequential
 - Surprising things are parallelizable

- ► Adding threads...
- Should not lower throughput
 - Contention effects
 - Mostly fixed by queue locks
 - > Overhead to acquire the lock:



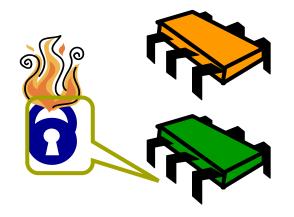
- ➤ we look at **futex** a later lecture and briefly discuss queue locks.
- ► Should increase throughput
 - Not possible if inherently sequential
 - Surprising things are parallelizable

- ► Adding threads...
- Should not lower throughput
 - Contention effects
 - Mostly fixed by queue locks
 - > Overhead to acquire the lock:



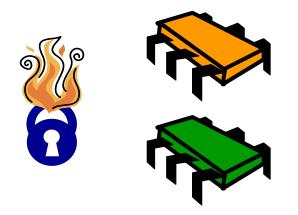
- ► we look at **futex** a later lecture and briefly discuss queue locks.
- ► Should increase throughput
 - Not possible if inherently sequential
 - Surprising things are parallelizable

- ► Adding threads...
- Should not lower throughput
 - Contention effects
 - Mostly fixed by queue locks
 - > Overhead to acquire the lock:



- > we look at **futex** a later lecture and briefly discuss queue locks.
- ► Should increase throughput
 - ► Not possible if inherently sequential
 - Surprising things are parallelizable

- ► Adding threads...
- Should not lower throughput
 - Contention effects
 - Mostly fixed by queue locks
 - > Overhead to acquire the lock:



- ► we look at **futex** a later lecture and briefly discuss queue locks.
- ► Should increase throughput
 - Not possible if inherently sequential
 - Surprising things are parallelizable

Coarse-Grained Synchronization

- ► Each method locks the object
 - Avoid contention using queue locks
 - ► Easy to reason about
 - ► In simple cases
 - Standard Java model
 - Synchronized blocks and methods
- ► So, are we done?

Coarse-Grained Synchronization

Sequential bottleneck

- ► All threads "stand in line"
- ► Adding more threads
 - Does not improve throughput
 - Struggle to keep it from getting worse
- ► So why even use a multiprocessor?
 - ► Well, some applications inherently parallel...

This Lecture

- ► Introduce four "patterns"
 - ► Bag of tricks
 - Methods that work more than once
- ► For highly-concurrent objects
- ≻ Goal
 - Concurrent access
 - More threads, more throughput

1. Fine-Grained Synchronization

- ► Instead of using a single lock...
- Split object into independently-synchronized components
- ➤ Methods conflict when they access
 - ➤ The same component...
 - ► At the same time

2. Optimistic Synchronization

- Object = linked set of components
- Search without locking...
- ► If you find it, lock and check...
 - ► OK, we are done
 - ► Oops, try again
- ► Evaluation
 - Cheaper than locking
 - Mistakes are expensive

3. Lazy Synchronization

- Postpone hard work
- Removing components is tricky
 - Logical removal
 - Mark component to be deleted
 - Physical removal
 - Do what needs to be done

4. Lock–Free Synchronization

- ► Do not use locks at all
 - ► Use compareAndSet() and relatives...

► Advantages

- Robust against asynchrony
- ► Disadvantages
 - ► Complex
 - Sometimes high overhead

Wait-Free Implementations

Definition: An object implementation is wait-free if every thread completes a method in a finite number of steps

No mutual exclusion➤ Thread could halt in critical section

Lock–Free Implementations

Definition: An object implementation is lockfree if in an infinite execution infinitely often some method call finishes (obviously, in a finite number of steps)

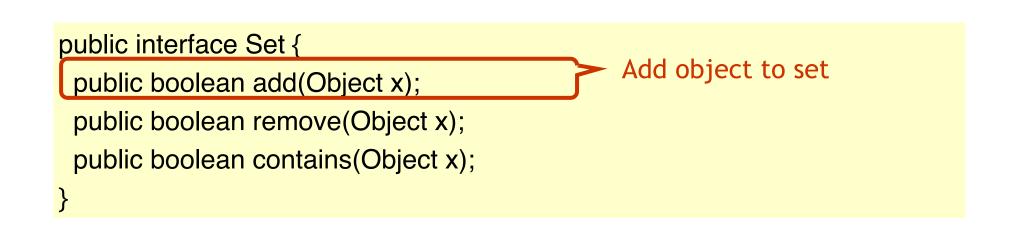
No difference between lock-free and waitfree for finite executions

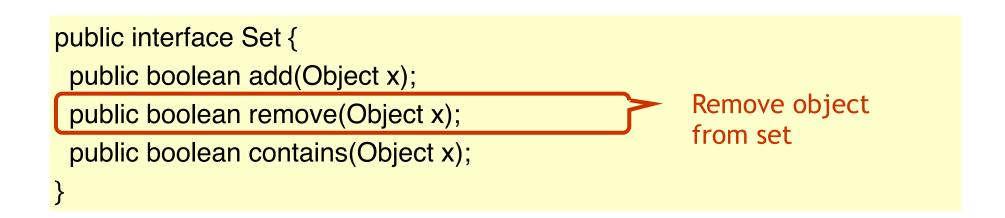
© Herlihy and Shavit

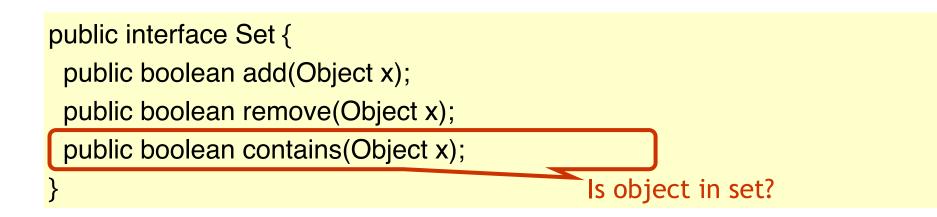
Example: Set Properties

- Collection of objects
- ► No duplicates
- ► Methods
 - > add() a new object
 - > remove() an object
 - ➤ Test if set contains() object

public interface Set {
 public boolean add(Object x);
 public boolean remove(Object x);
 public boolean contains(Object x);
}



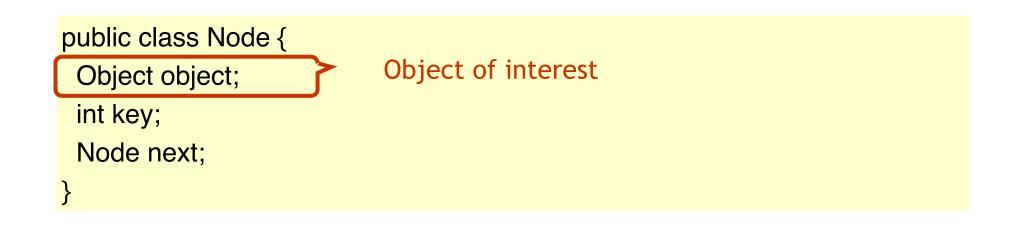




Linked List

- ► Illustrate these patterns...
- ► Using a list-based Set
 - Common data structure
 - Building block for other apps

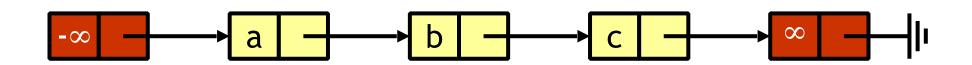
public class Node {
 Object object;
 int key;
 Node next;
}



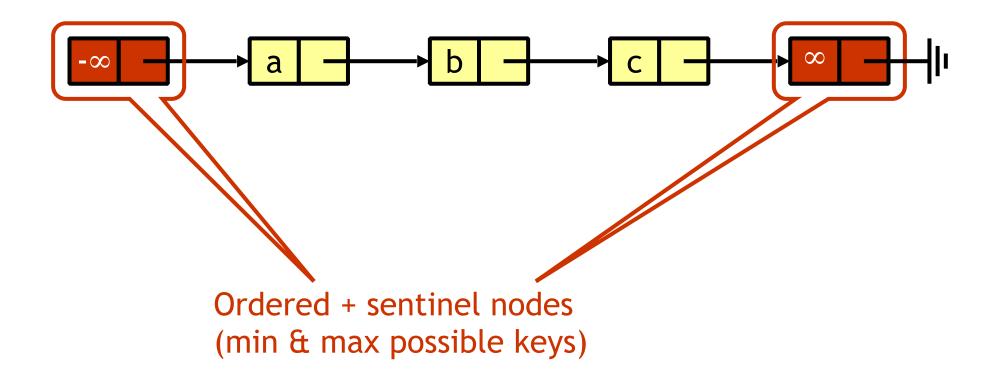




The List-Based Set



The List-Based Set



Reasoning about Concurrent Data Structures

- ► Identify invariants
 - Properties that always holds
- ► True when object is created
- ► Truth preserved by each method
 - > add(), remove(), contains()
 - Each step of each method
- ► Most steps are trivial
 - Usually one step tricky
 - Often linearization point

Interference

- Proof that invariants are preserved works if methods considered are the only modifiers
- Language encapsulation helps
 - List nodes not visible outside class
- Freedom from interference needed even for removed nodes
 - Some algorithms traverse removed nodes
 - Careful with malloc() and free()!
 - Garbage-collection helps here

Blame Game

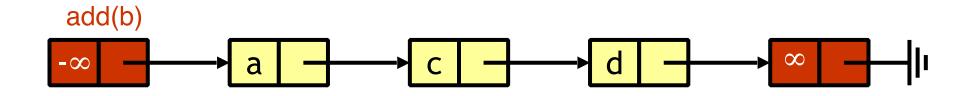
≻ Suppose

- ► add() leaves behind 2 copies of x
- remove() removes only 1
- ► Which one is incorrect?
 - ► If invariant says no duplicates
 - add() is incorrect
 - ► Otherwise
 - remove() is incorrect

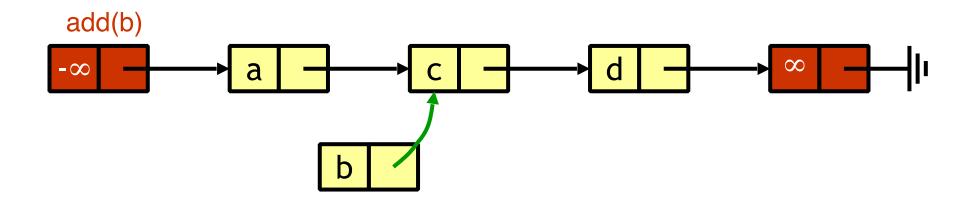
Set Invariant (Partly)

- ► Sentinel nodes
 - ➤ Tail reachable from head
- ► Sorted
- ► No duplicates

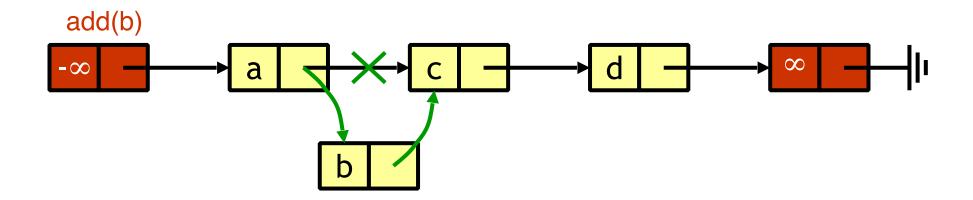
Sequential List Based Set



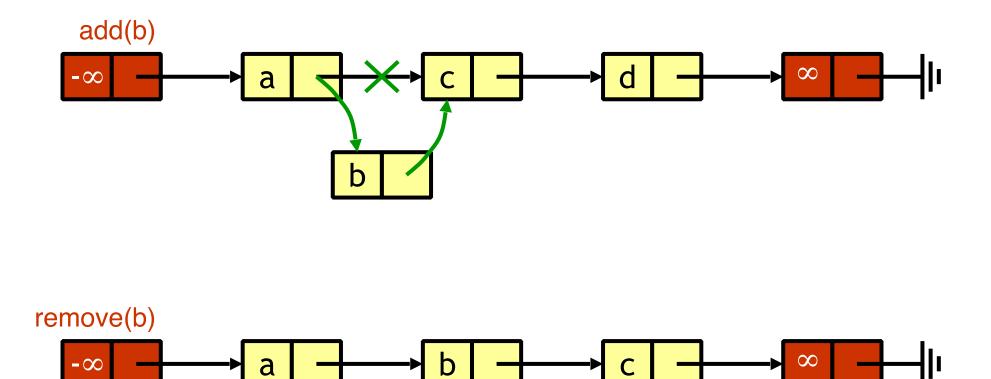
Sequential List Based Set



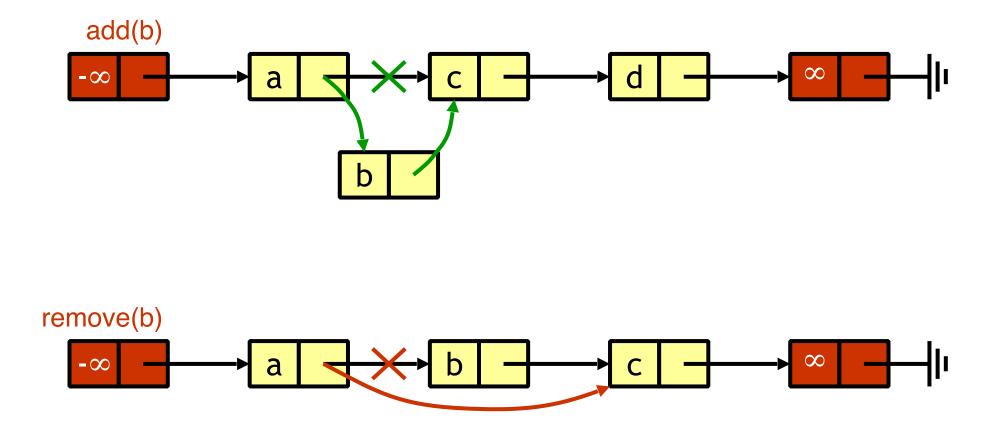
Sequential List Based Set

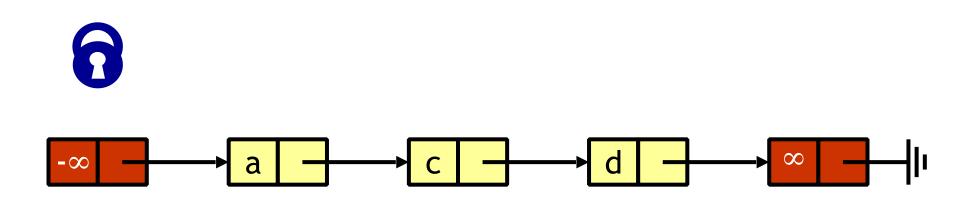


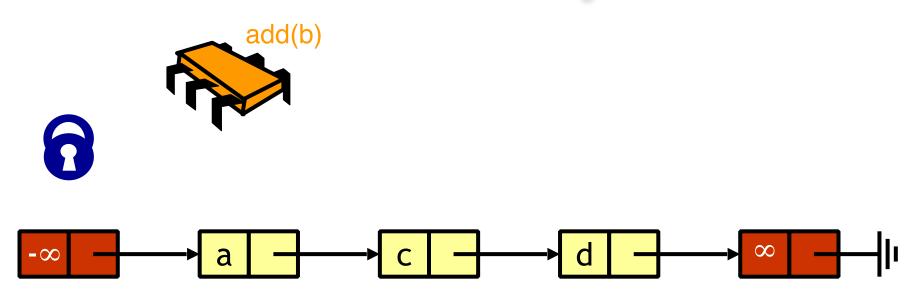
Sequential List Based Set

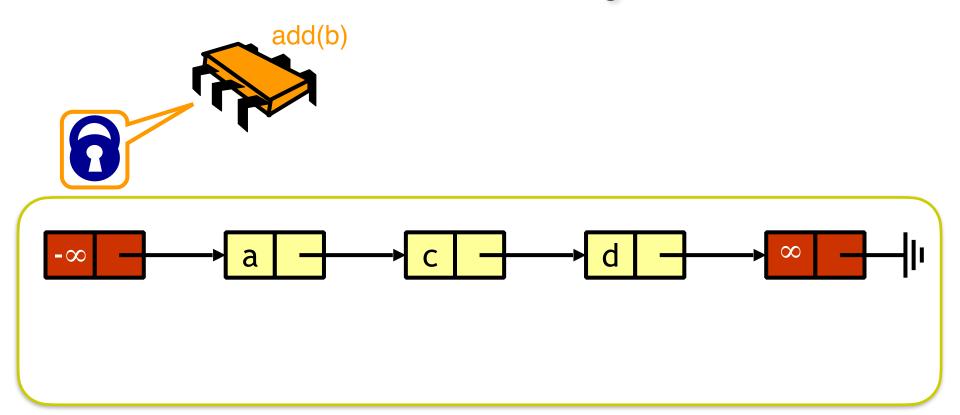


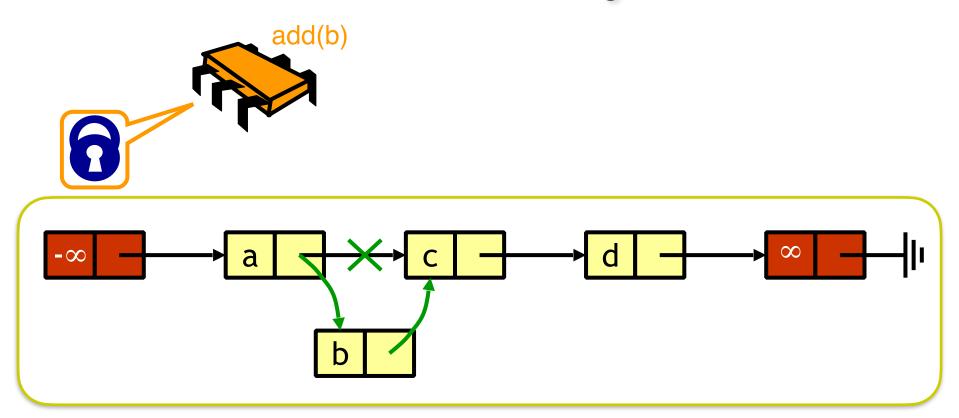
Sequential List Based Set

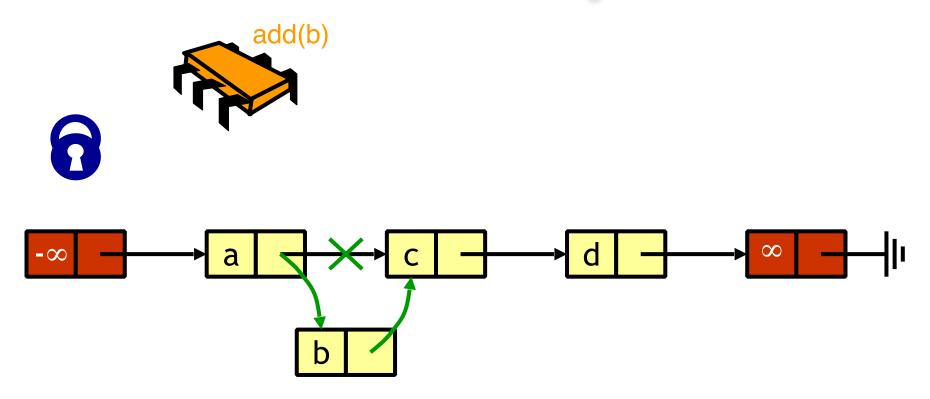


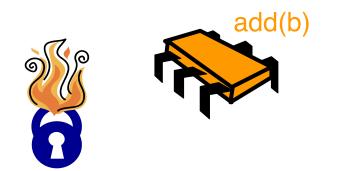


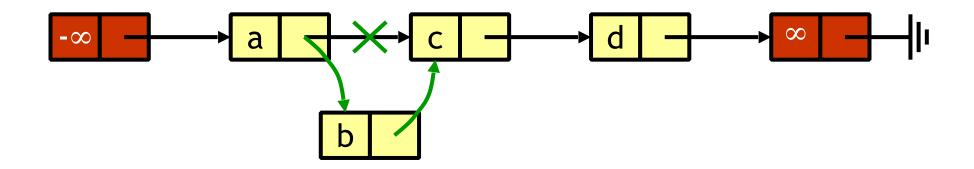












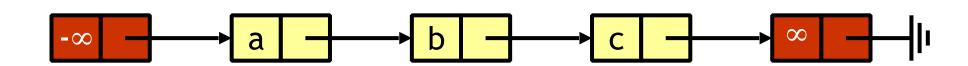
Simple but hotspot + bottleneck

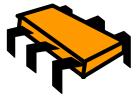
► Easy, same as synchronized methods

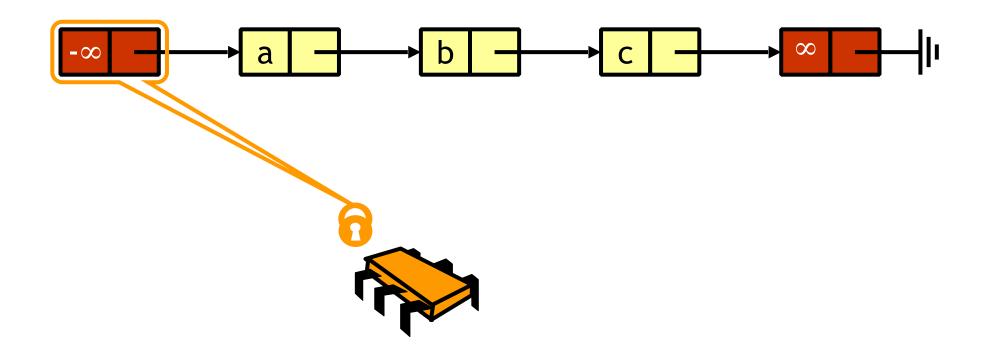
- "One lock to rule them all..."
- ➤ Simple, clearly correct
 - ➤ Deserves respect!
- ► Works poorly with contention
 - ► Queue locks help
 - But bottleneck still an issue

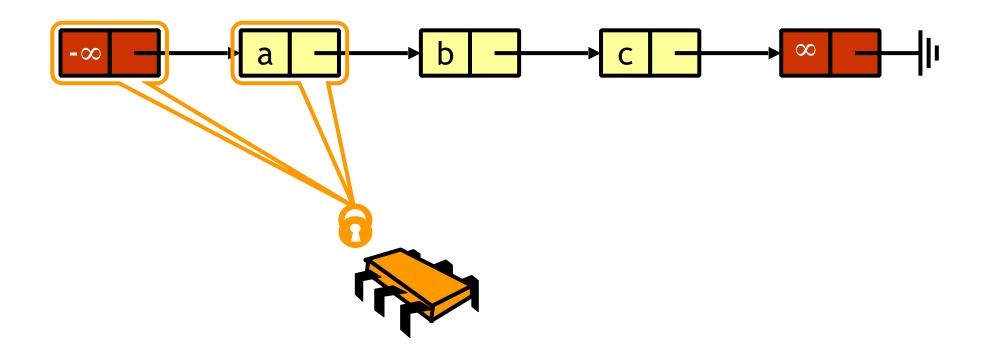
2. Fine-grained Locking

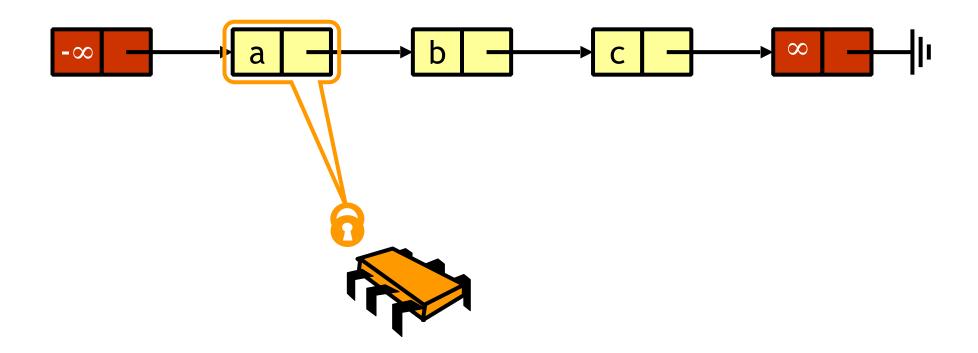
- Requires careful thought
 - "Do not meddle in the affairs of wizards, for they are subtle and quick to anger"
- ➤ Split object into pieces
 - ► Each piece has own lock
 - Methods that work on disjoint pieces need not exclude each other

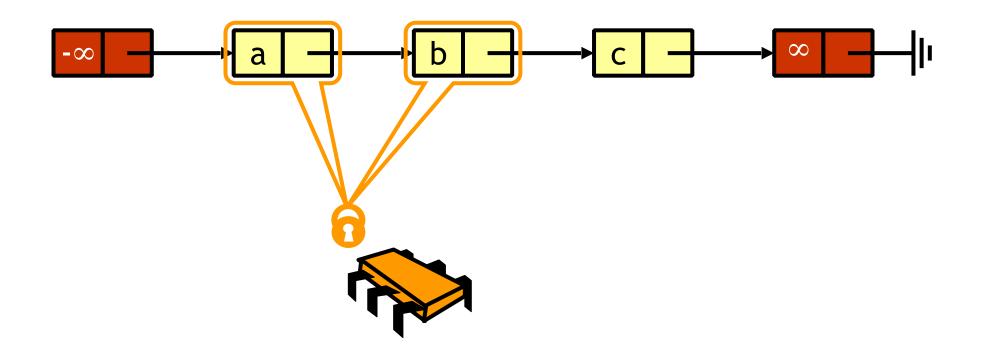


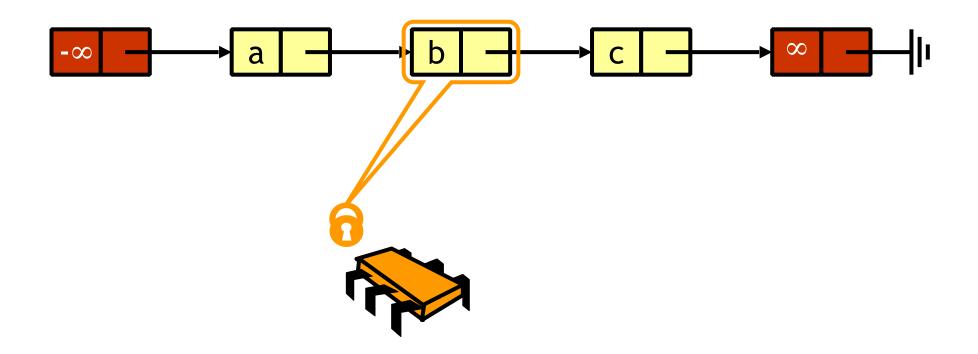


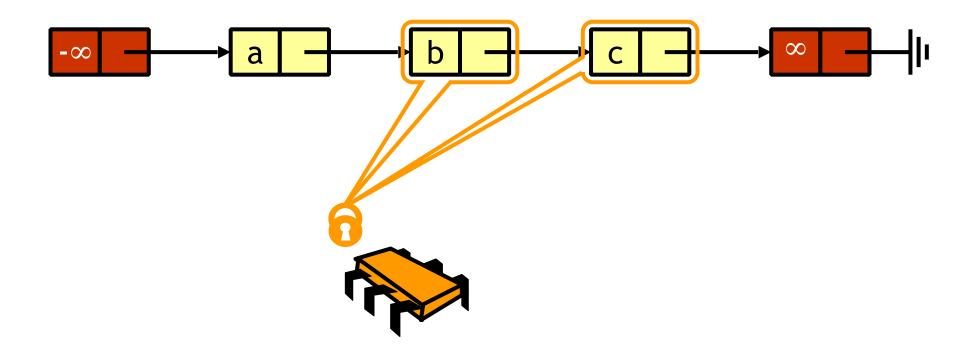


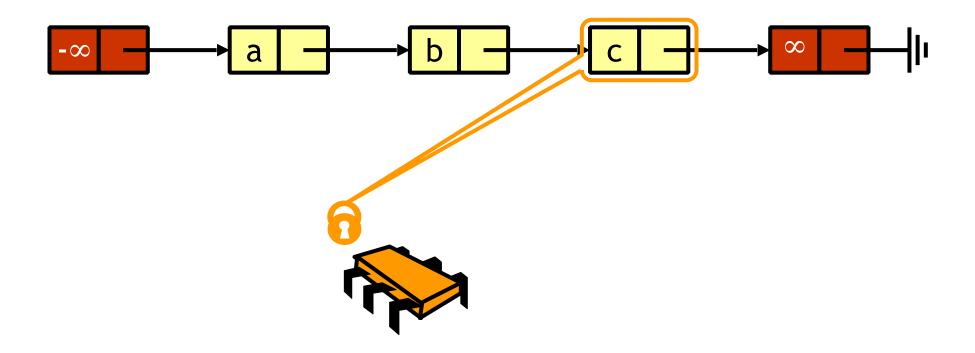


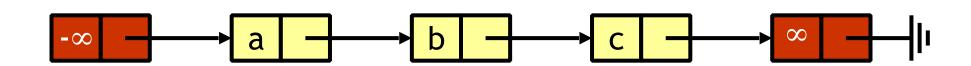


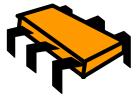


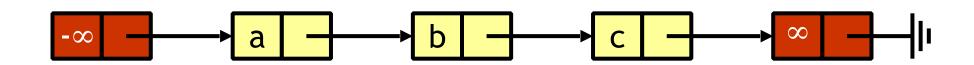




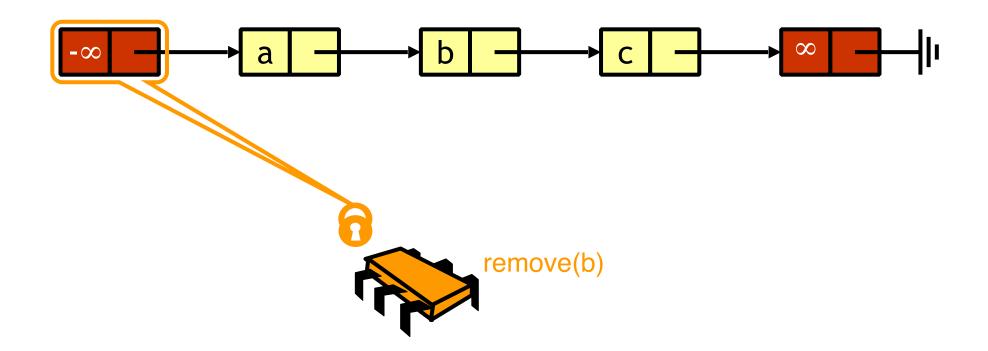


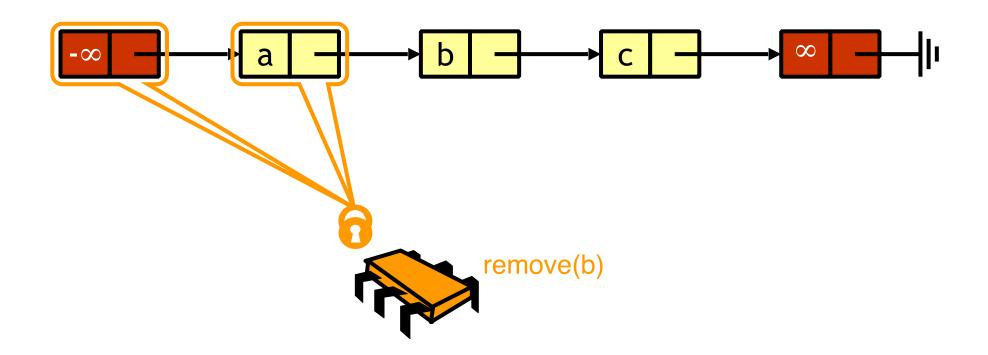


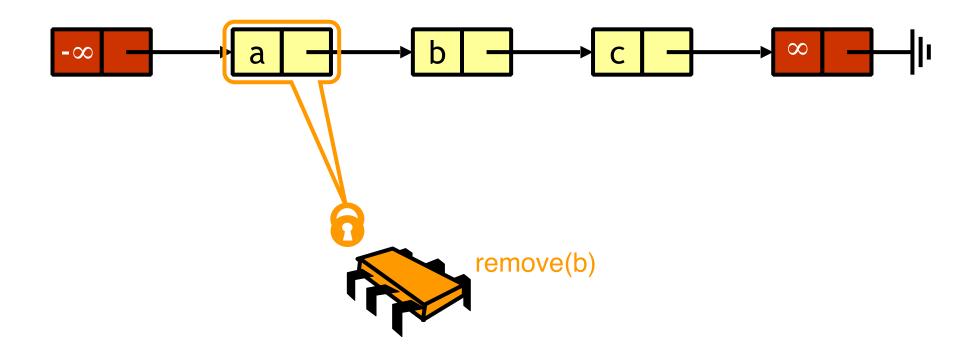


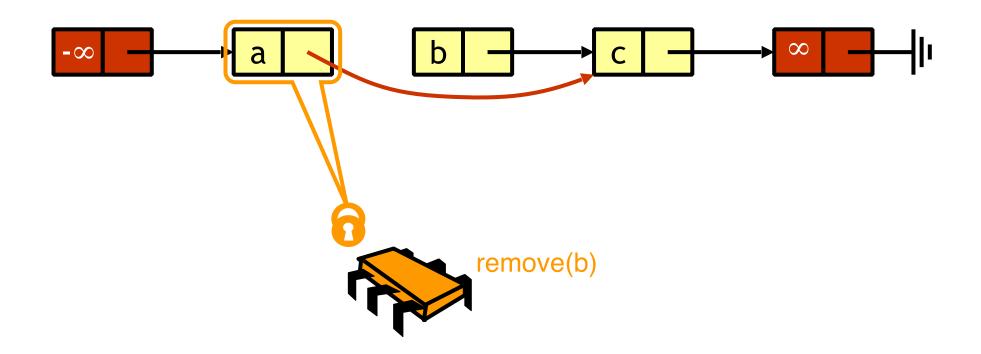


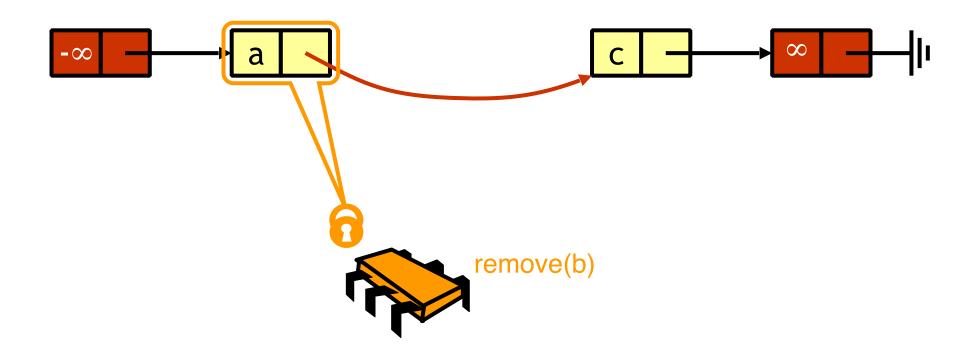








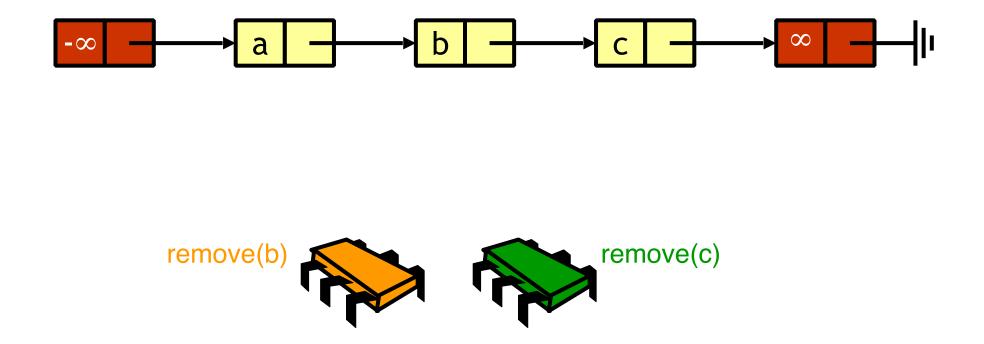


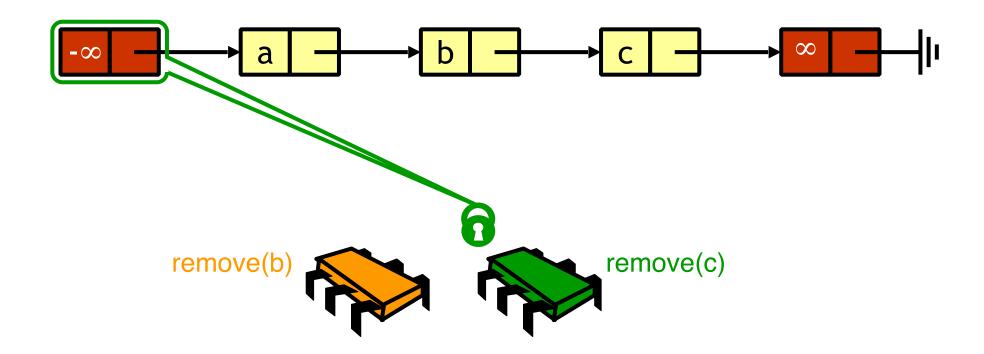


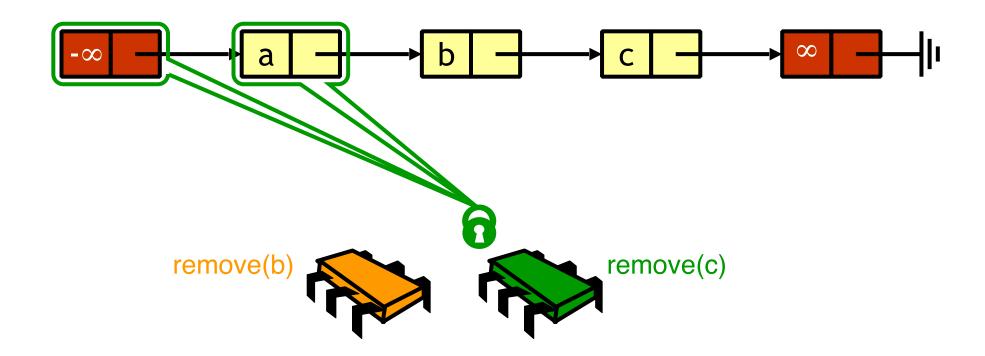


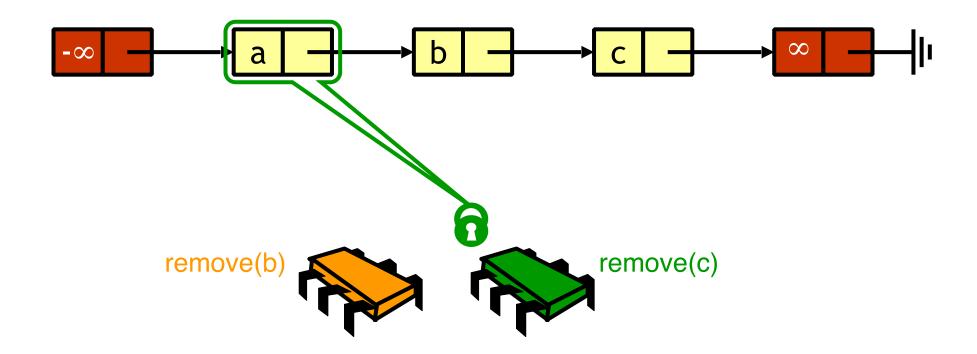


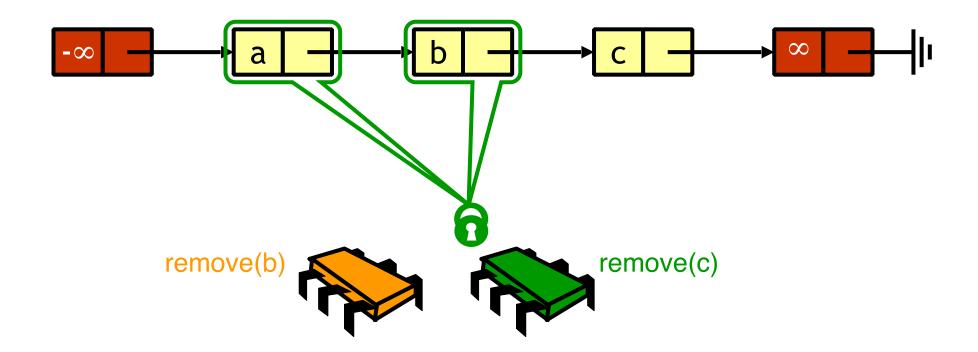
Concurrency: Foundations and Algorithms -

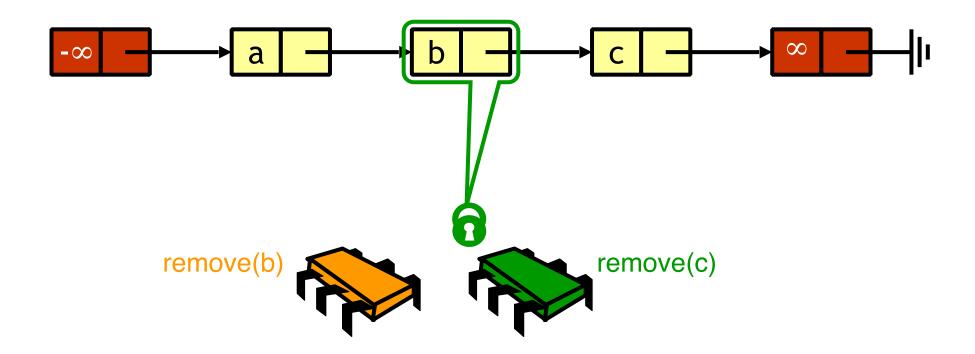


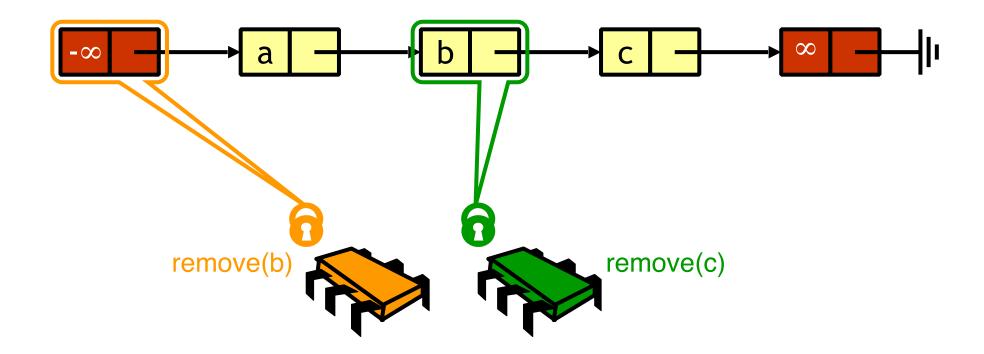


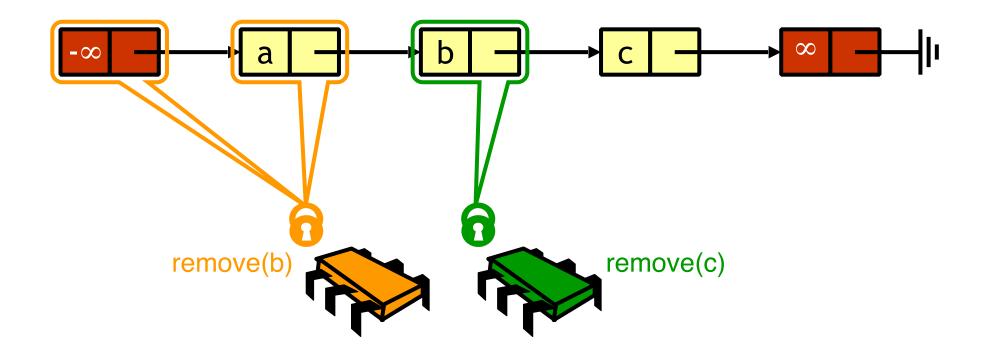


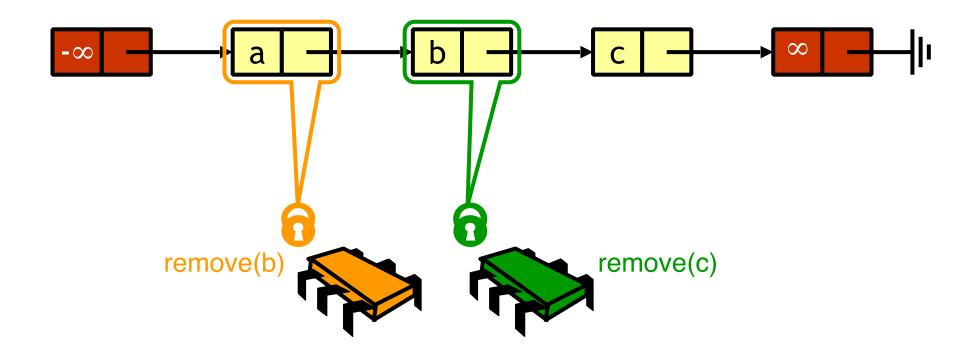


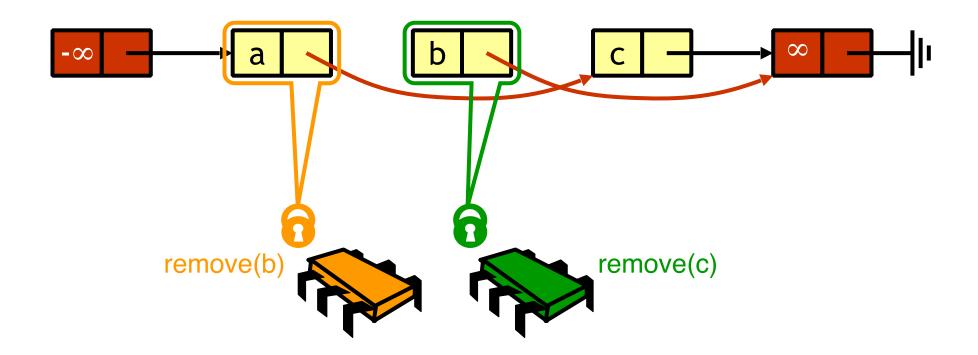




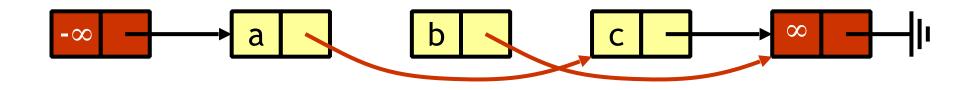


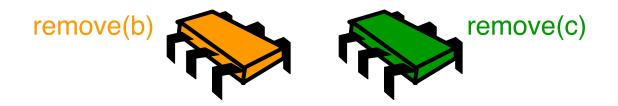




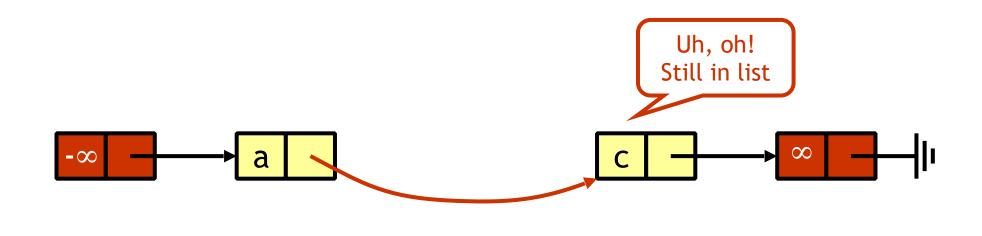


Removing a Node





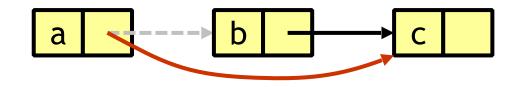
Removing a Node





Problem

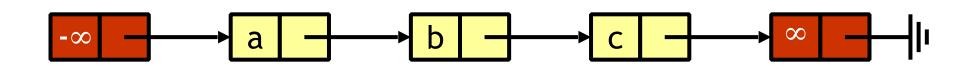
- ► To delete node b
 - Swing node a's next field to c

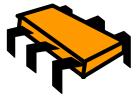


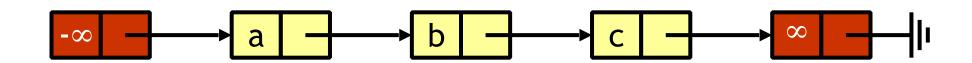
- ► Problem is
 - Someone could delete c concurrently

Insight

- ► If a node is locked
 - ➤ No one can delete node's successor
- ► If a thread locks
 - ➤ The node to be deleted
 - And its predecessor
 - ► Then it works

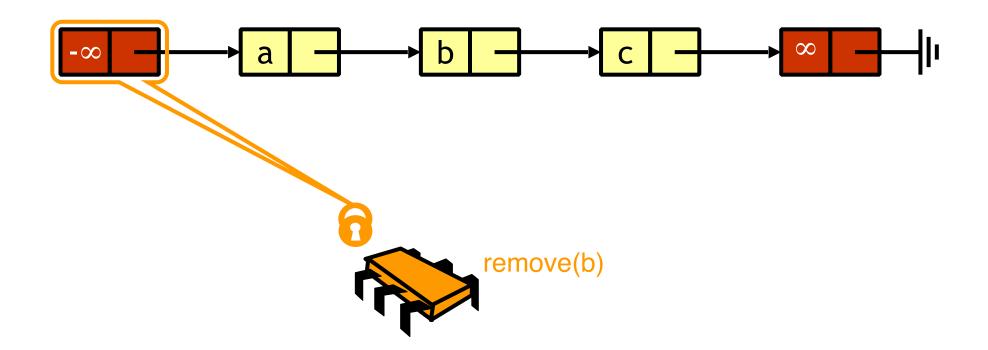


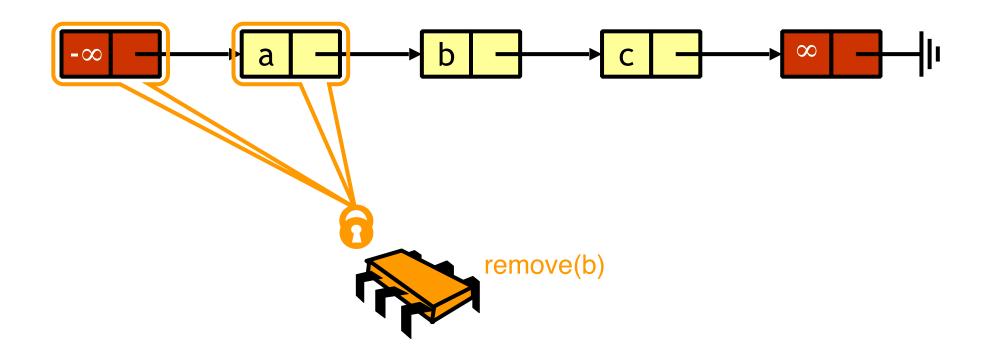


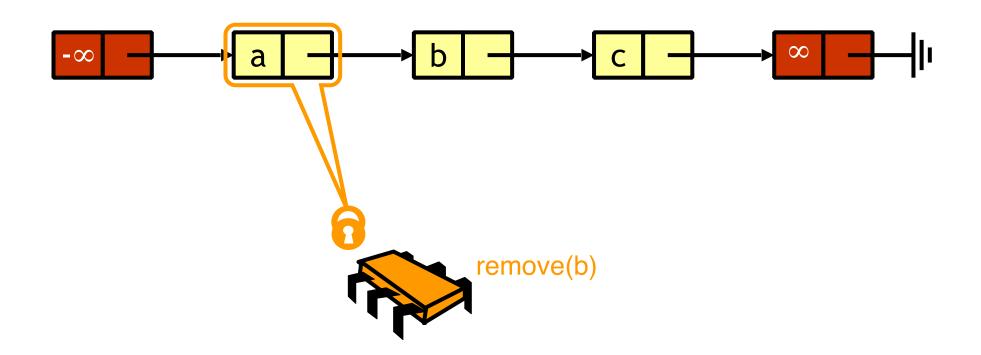


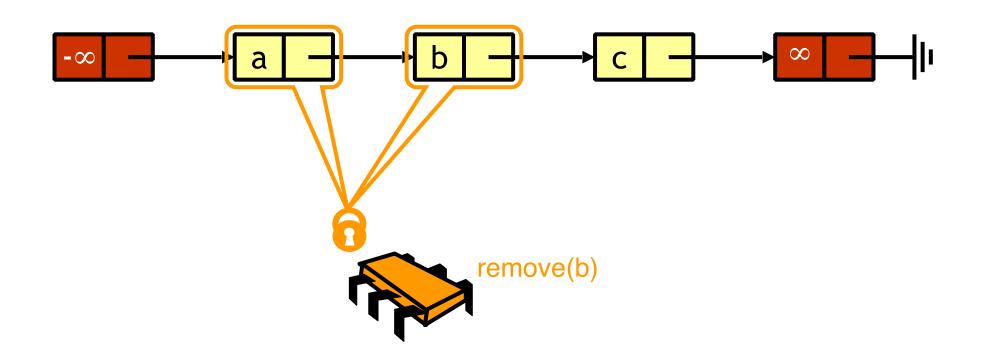


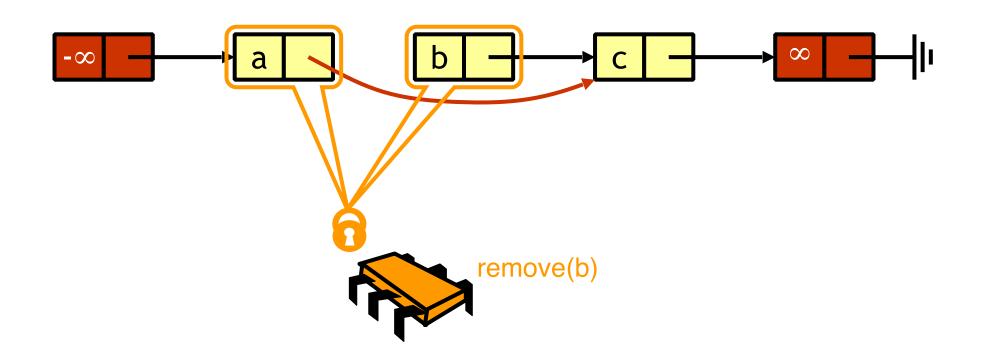
Concurrency: Foundations and Algorithms -







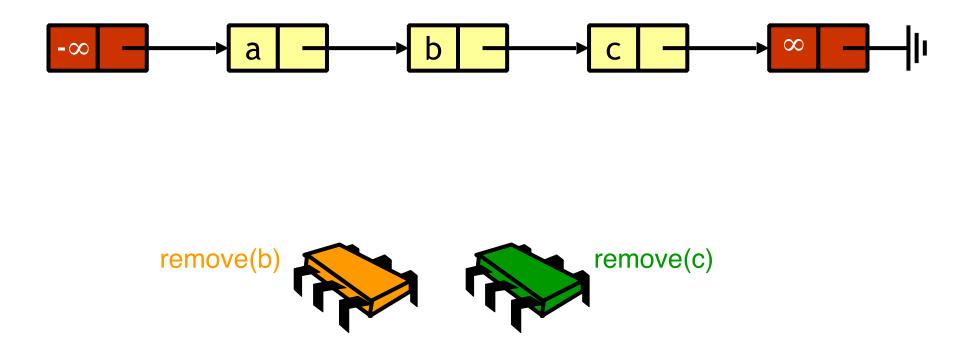


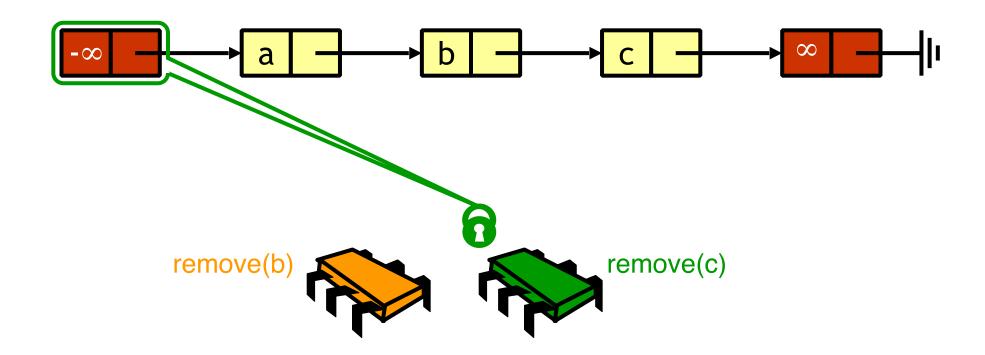


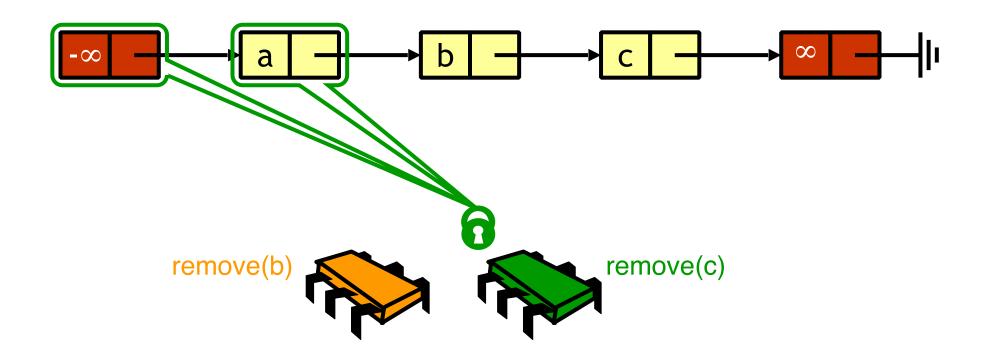


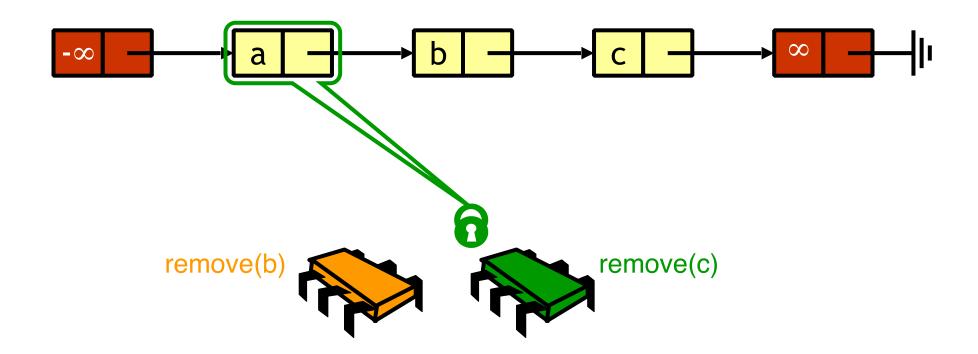


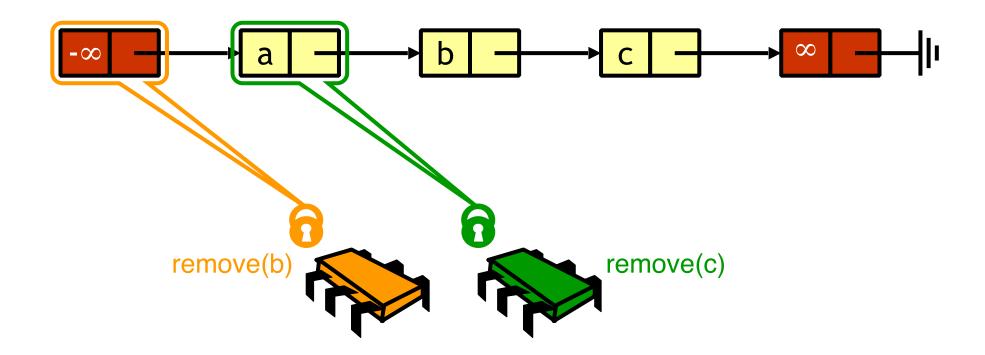
Concurrency: Foundations and Algorithms -

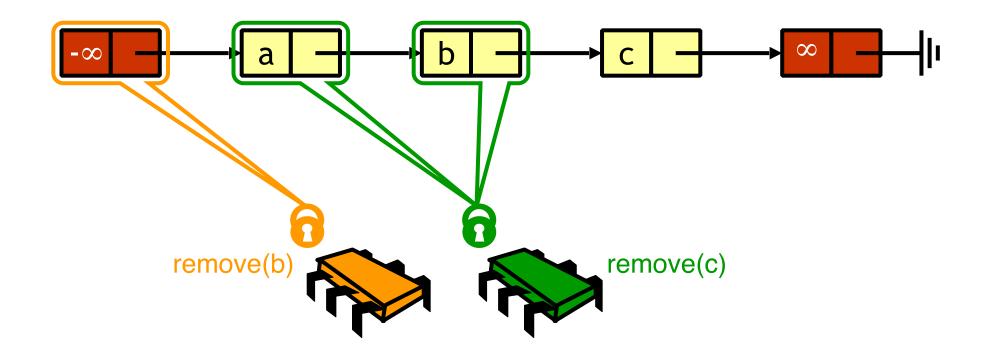


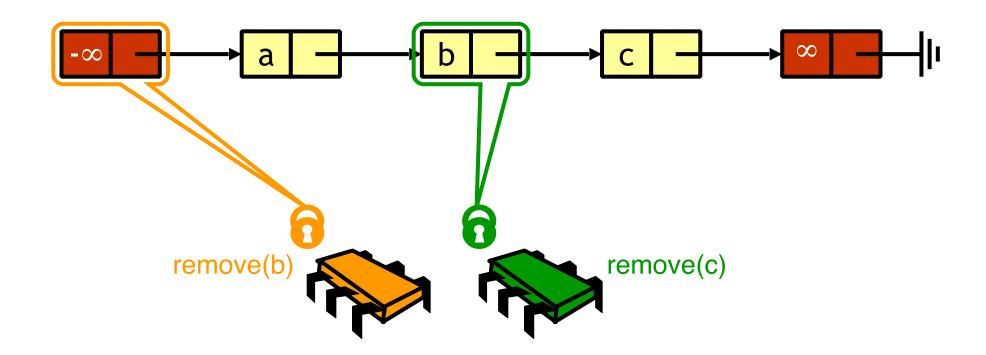


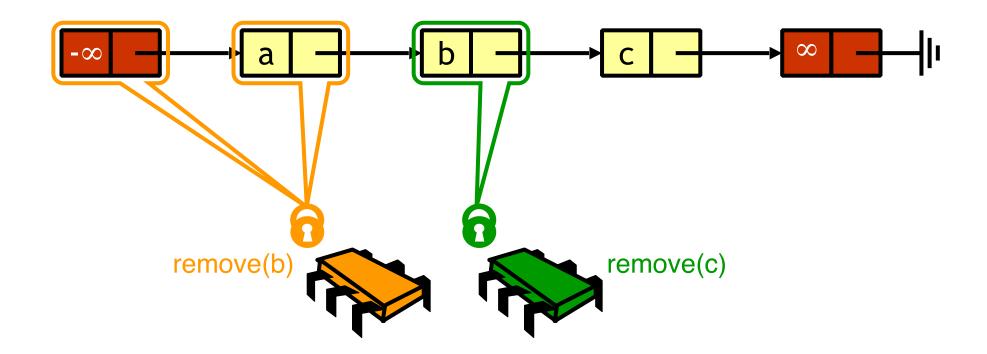


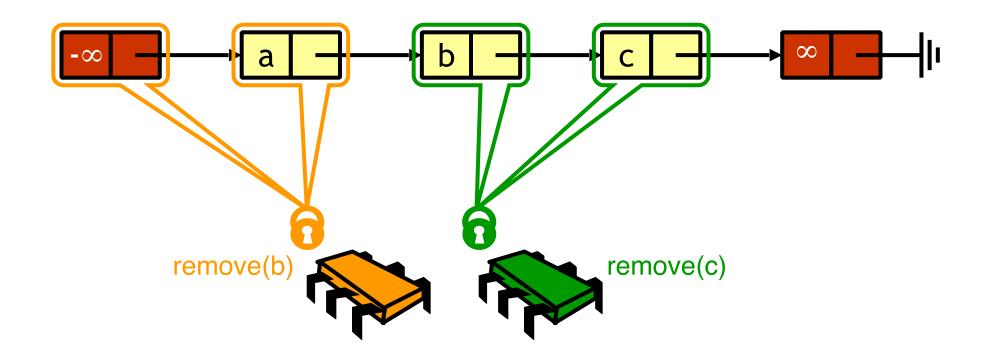


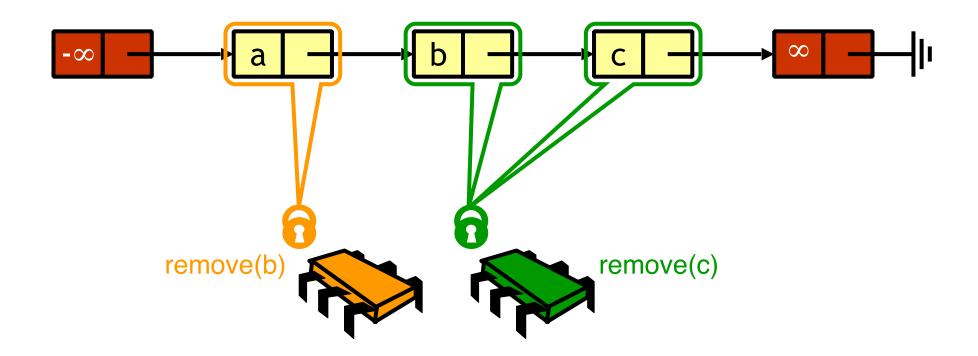


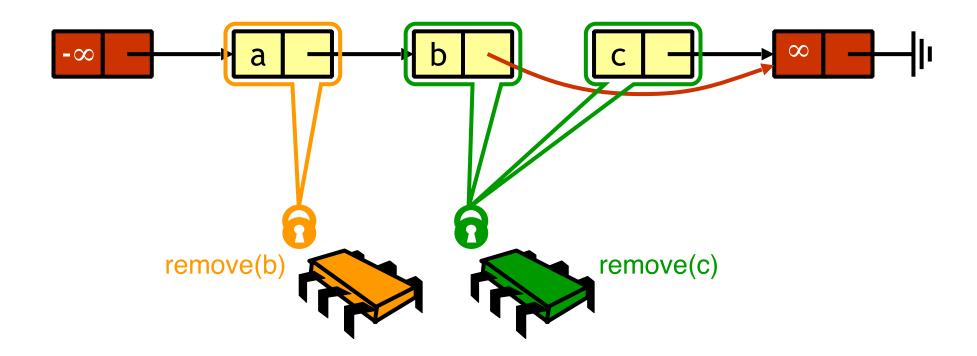


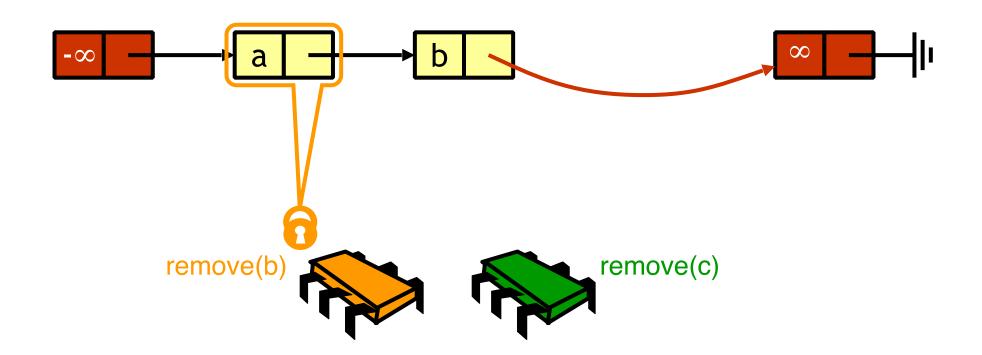


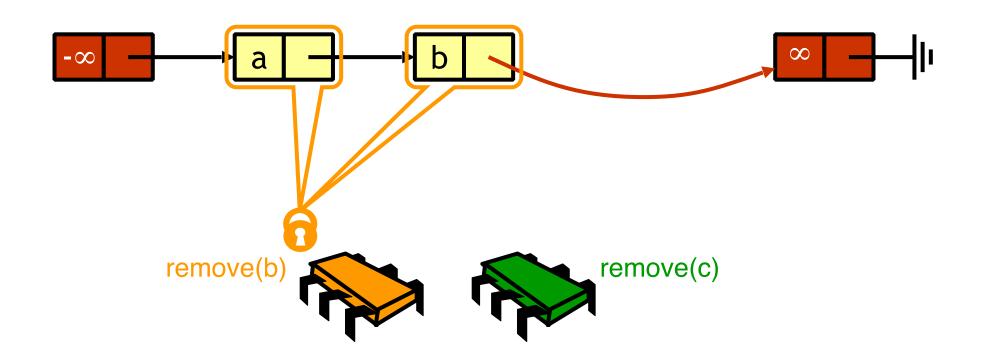


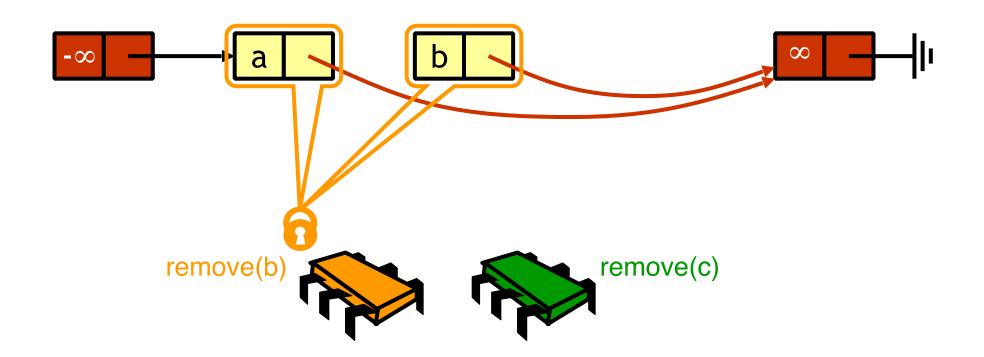


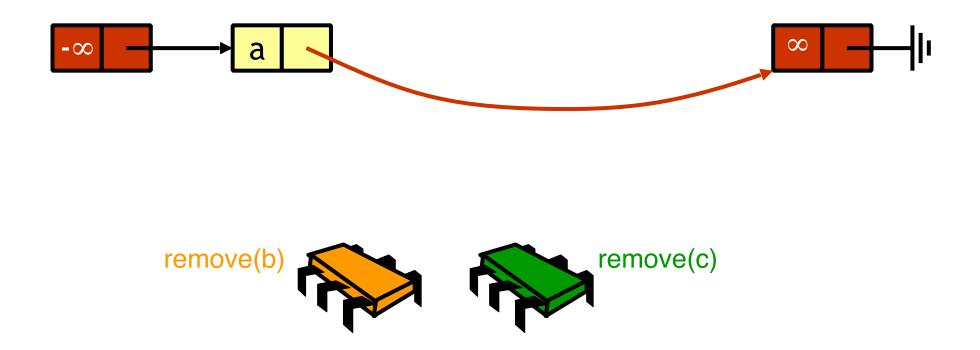




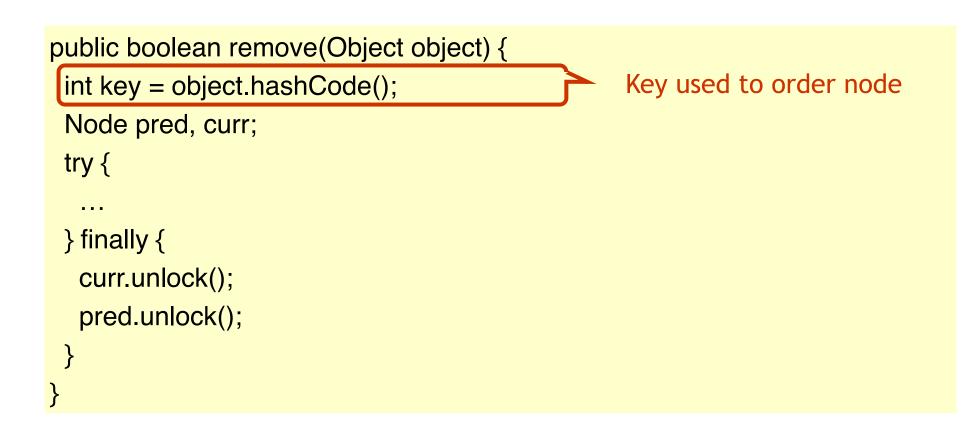








```
public boolean remove(Object object) {
    int key = object.hashCode();
    Node pred, curr;
    try {
        ...
    } finally {
        curr.unlock();
        pred.unlock();
    }
```



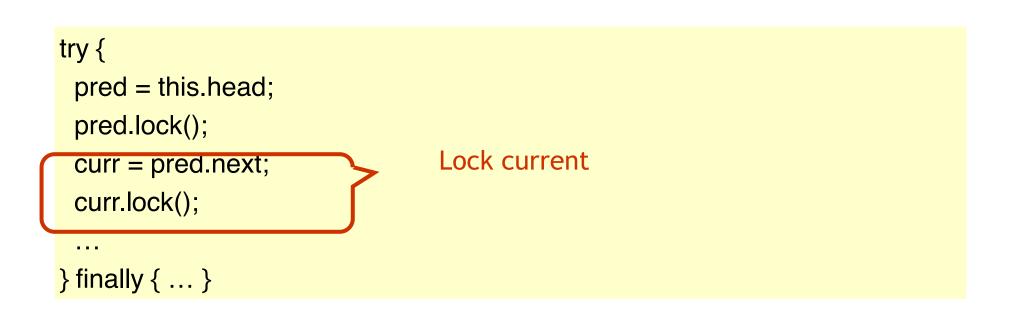
```
public boolean remove(Object object) {
 int key = object.hashCode();
 Node pred, curr;
                              Predecessor and current nodes
 try {
   . . .
 } finally {
  curr.unlock();
  pred.unlock();
 }
```

```
public boolean remove(Object object) {
 int key = object.hashCode();
 Node pred, curr;
 try {
   . . .
 } finally {
                               Make sure locks released
  curr.unlock();
  pred.unlock();
```

```
public boolean remove(Object object) {
 int key = object.hashCode();
 Node pred, curr;
 try {
             Everything else
 } finally {
  curr.unlock();
  pred.unlock();
 }
```

```
try {
   pred = this.head;
   pred.lock();
   curr = pred.next;
   curr.lock();
   ....
} finally { ... }
```



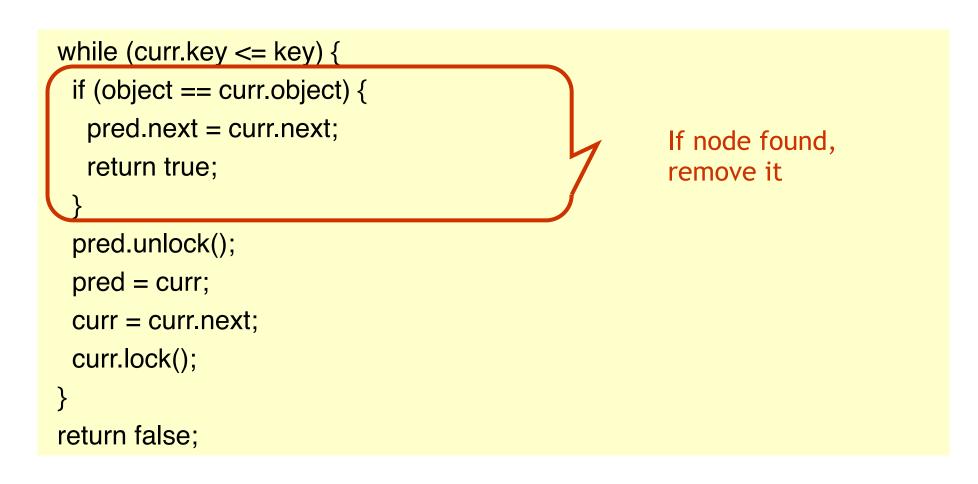


try {
pred = this.head;
pred.lock();
curr = pred.next;
curr.lock();
Traverse the list
<pre>} finally { }</pre>

```
while (curr.key <= key) {</pre>
 if (object == curr.object) {
  pred.next = curr.next;
  return true;
 }
 pred.unlock();
 pred = curr;
 curr = curr.next;
 curr.lock();
}
return false;
```

```
while (curr.key <= key) {</pre>
 if (object == curr.object) {
   pred.next = curr.next;
   return true;
 }
 pred.unlock();
 pred = curr;
 curr = curr.next;
 curr.lock();
}
return false;
```

Search key range (curr and pred locked)



```
while (curr.key <= key) {</pre>
 if (object == curr.object) {
  pred.next = curr.next;
  return true;
 }
 pred.unlock();
 pred = curr;
 curr = curr.next;
 curr.lock();
}
return false;
```

Unlock predecessor and demote current (only one node locked!)

```
while (curr.key <= key) {</pre>
 if (object == curr.object) {
  pred.next = curr.next;
  return true;
 }
 pred.unlock();
 pred = curr;
 curr = curr.next;
                                      Find and lock new current
 curr.lock();
return false;
```

```
while (curr.key <= key) {</pre>
 if (object == curr.object) {
  pred.next = curr.next;
  return true;
 }
 pred.unlock();
 pred = curr;
 curr = curr.next;
 curr.lock();
return false;
                          Otherwise not present
```

Adding Nodes

- ► To add node b
 - Lock predecessor
 - Lock successor
- ► Neither can be deleted

Drawbacks

- ► Better than coarse-grained lock
 - ➤ Threads can traverse in parallel
- ► Still not ideal
 - Long chain of acquire/release
 - Threads cannot overtake one another
 - ► Inefficient

Linked List Lecture

► Five approaches to concurrent data structure design:

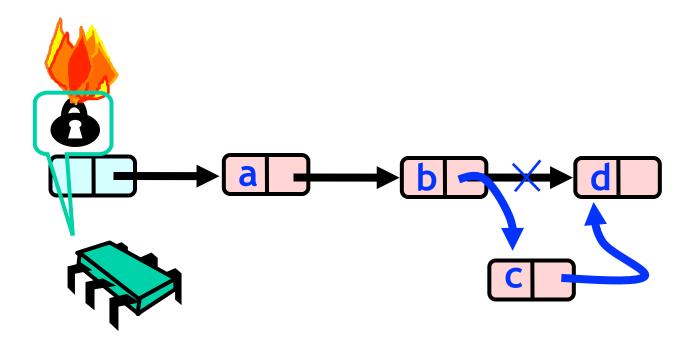
- Coarse-grained locking
- Fine-grained locking
- Optimistic synchronization
- Lazy synchronization
- Lock-free synchronization

List-based Set

► We used an ordered list to implement a Set:

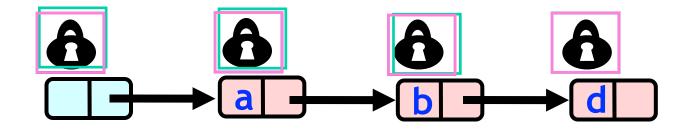
- An unordered collection of objects
- ➤ No duplicates
- ➤ Methods:
 - > add() a new object
 - > remove() an object
 - > Test if set contains() object

Course Grained Locking



Simple but hotspot + bottleneck

Fine Grained Locking

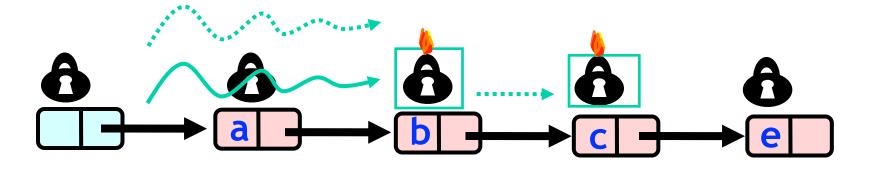


Allows concurrency but everyone always delayed by front guy = bottleneck

Lock acquisition overhead

© Herlihy-Shavit

Optimistic List



- Limited Hotspots (Only at locked Add(), Remove(), Contains() destination locations, not traversals)
- But two traversals
- > Yet traversals are wait-free!

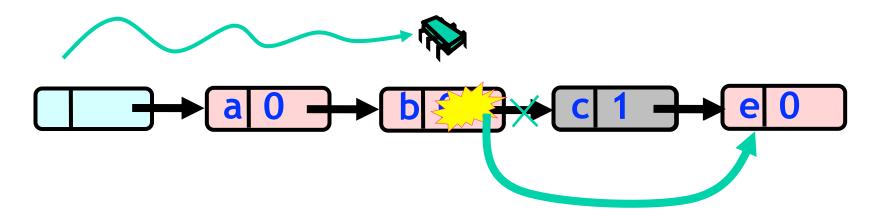
© Herlihy-Shavit

Lazy List

Lazy Add() and Remove() + Wait-free Contains()

© Herlihy-Shavit

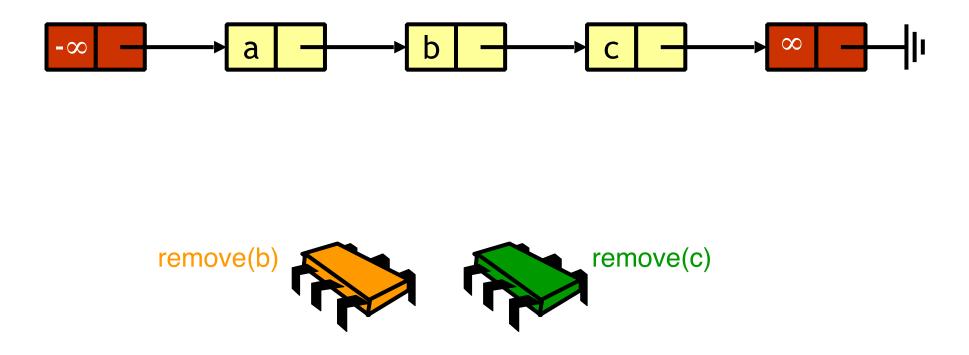
Lock-free List

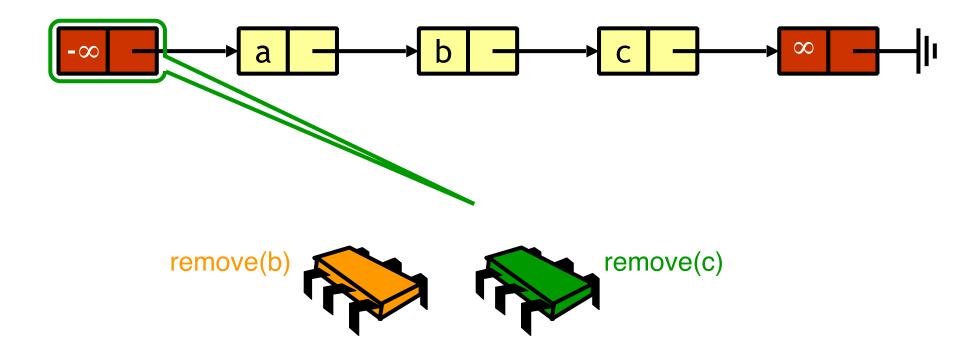


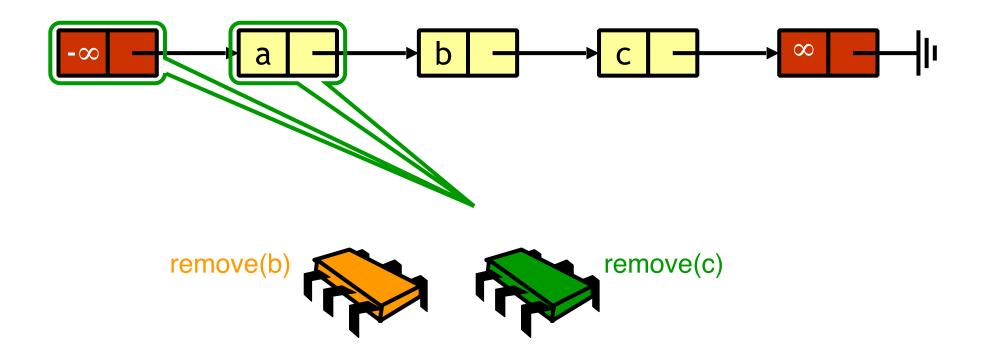
- >Add() and Remove() physically remove marked nodes
- Wait-free contains() traverses both marked and removed nodes

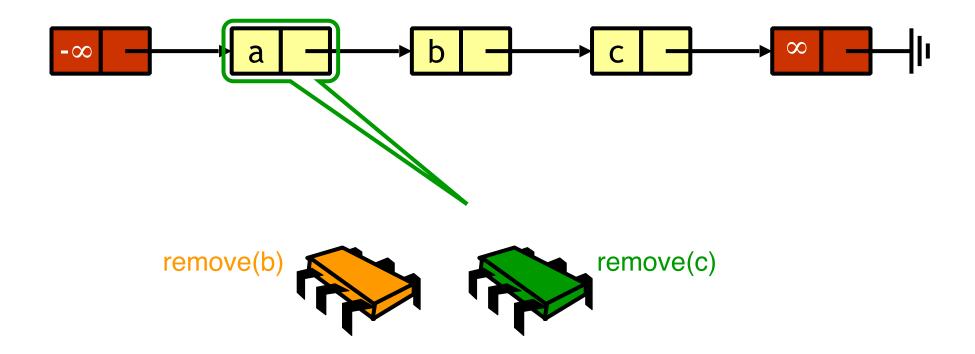
3. Optimistic Synchronization

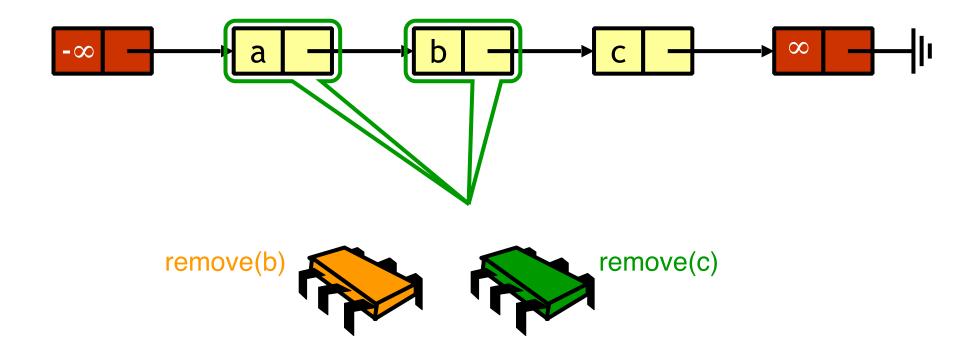
- Find nodes without locking
- ► Lock nodes
- ► Check that everything is OK

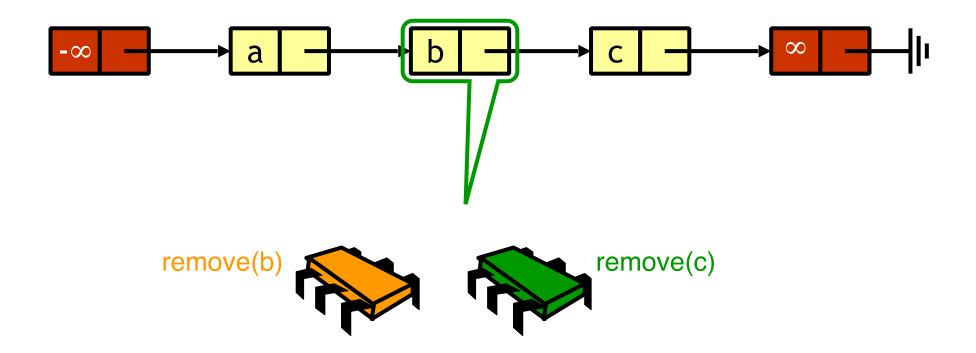


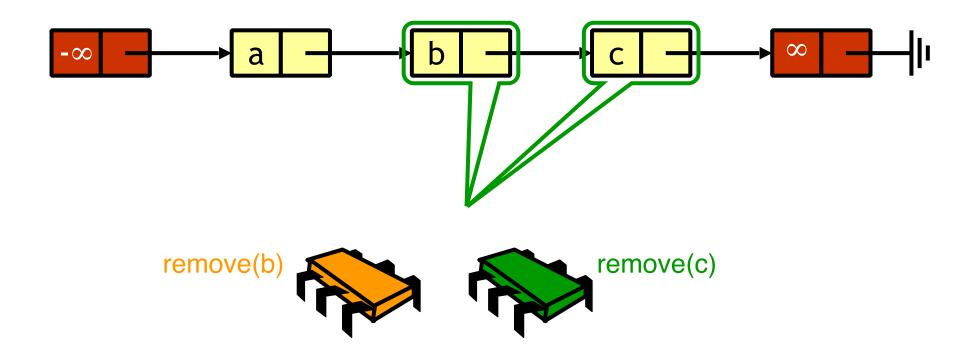


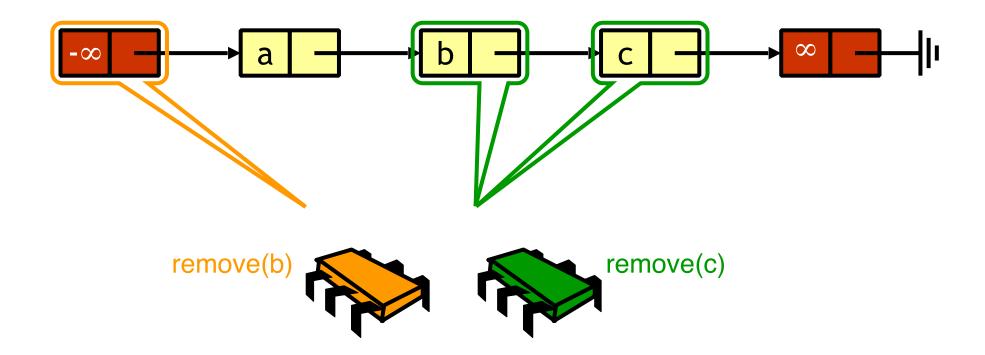


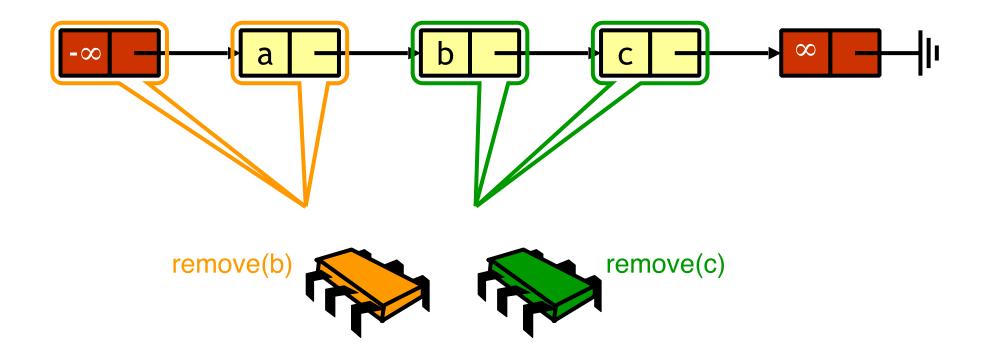


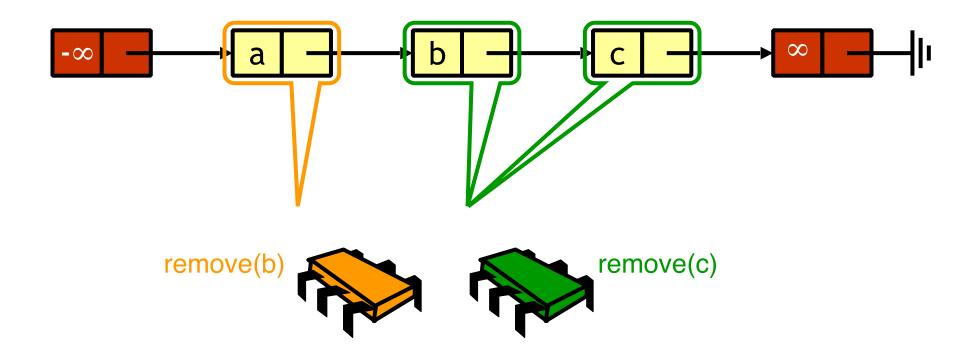


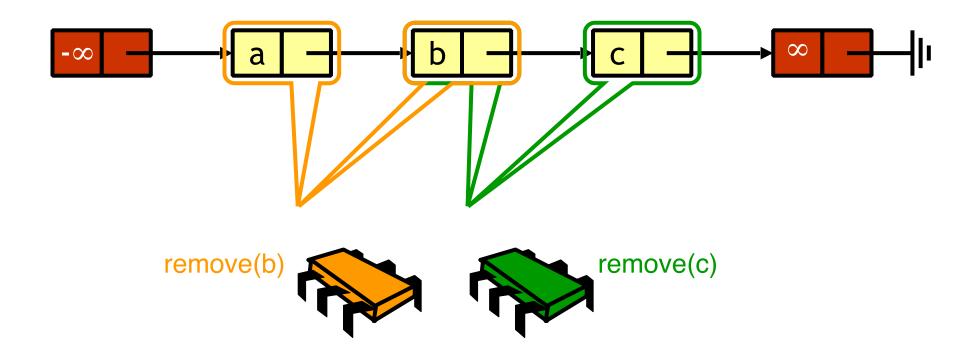


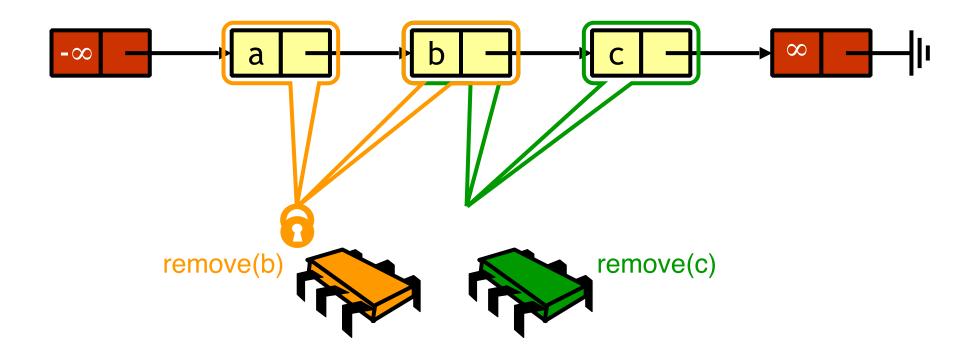


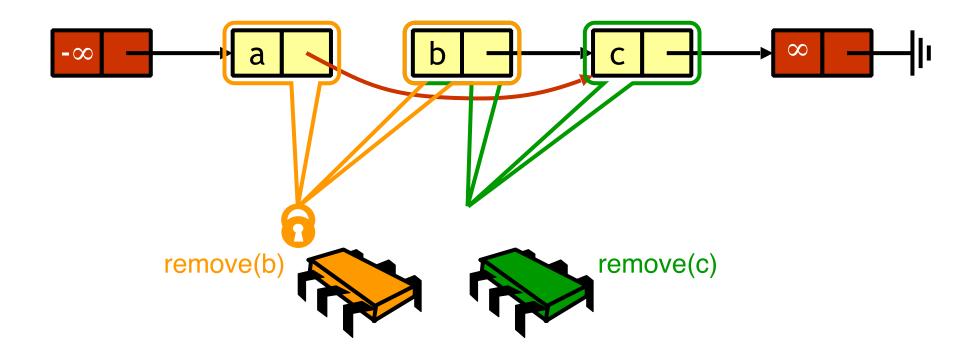


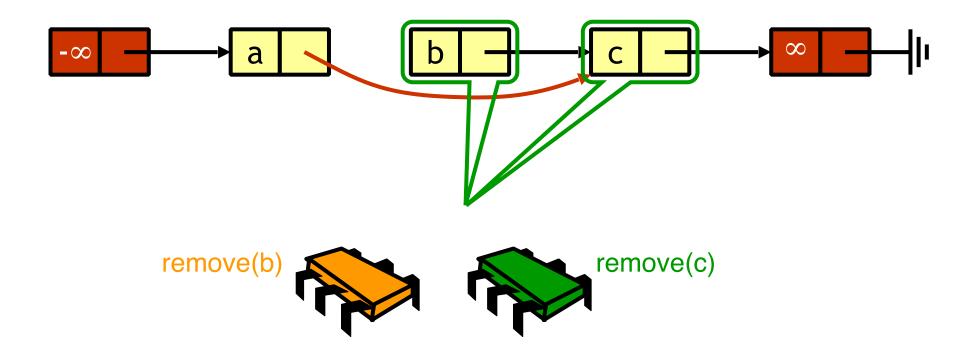


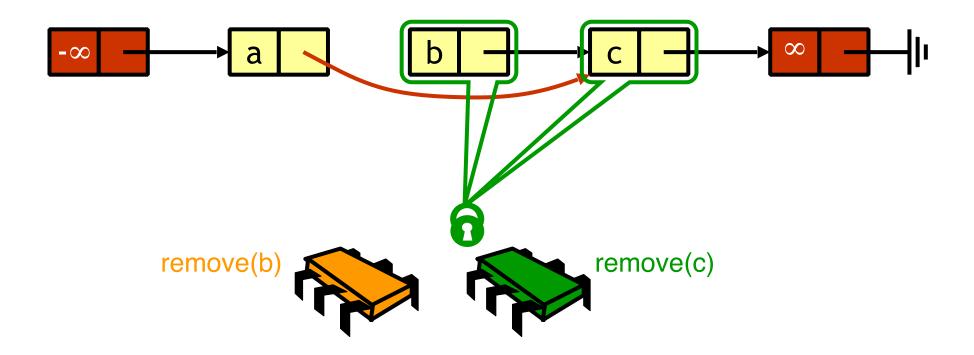


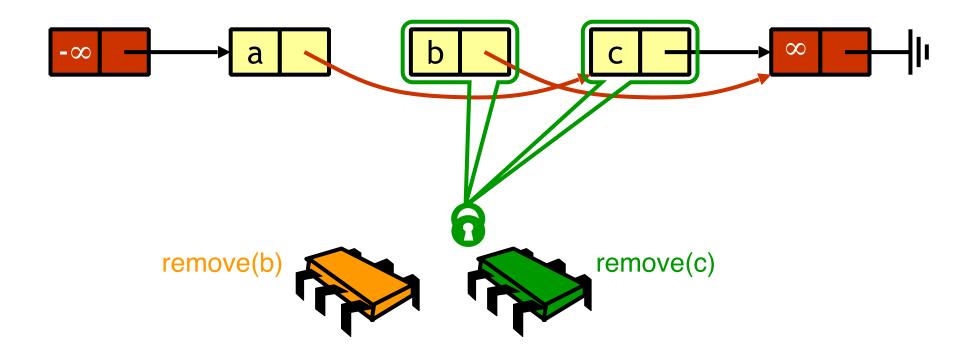


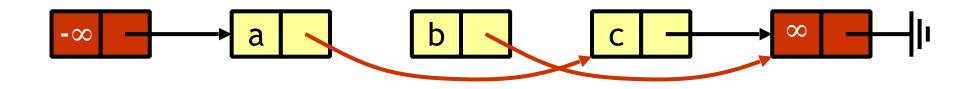


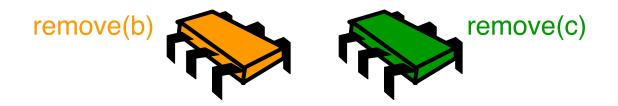


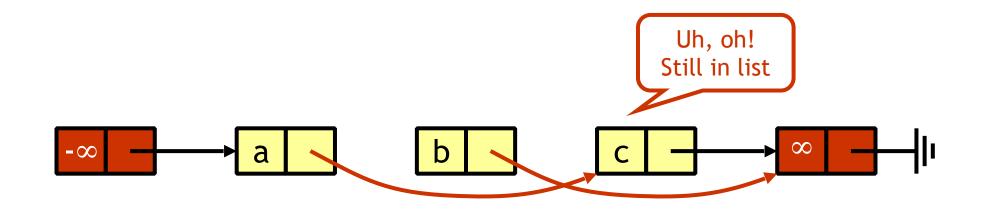




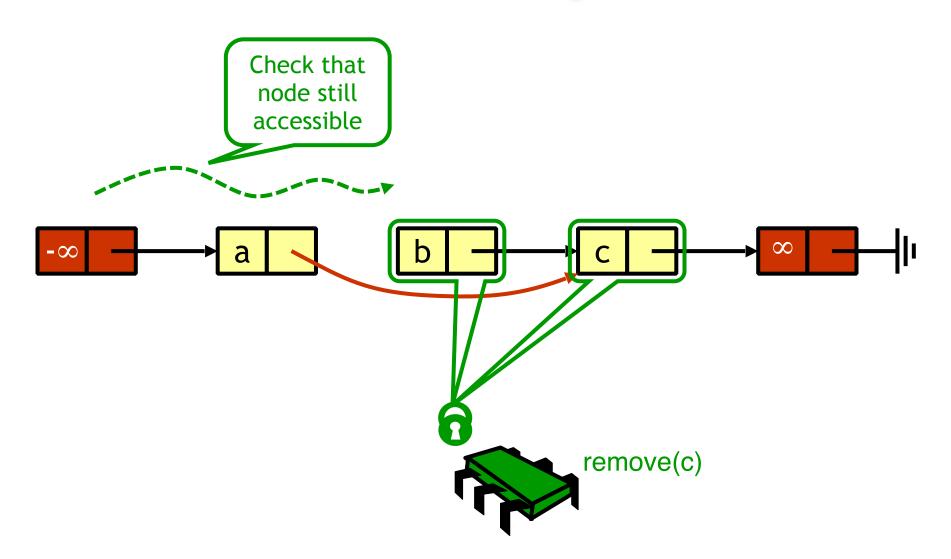


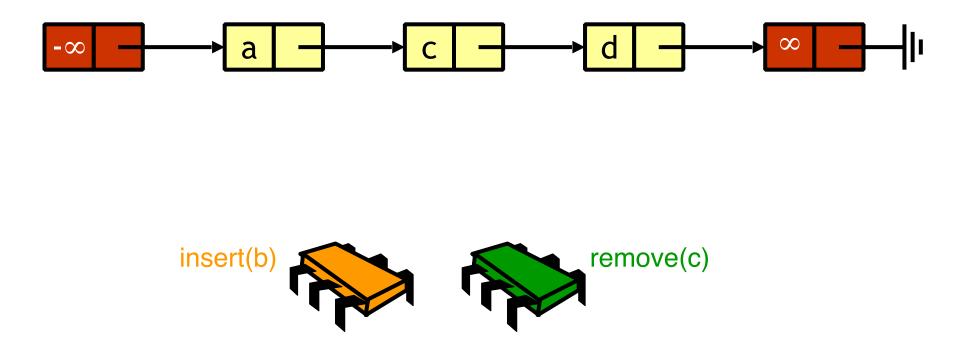




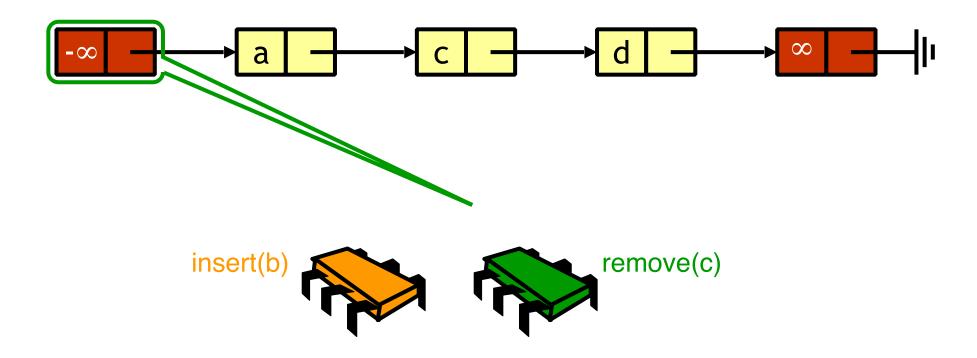


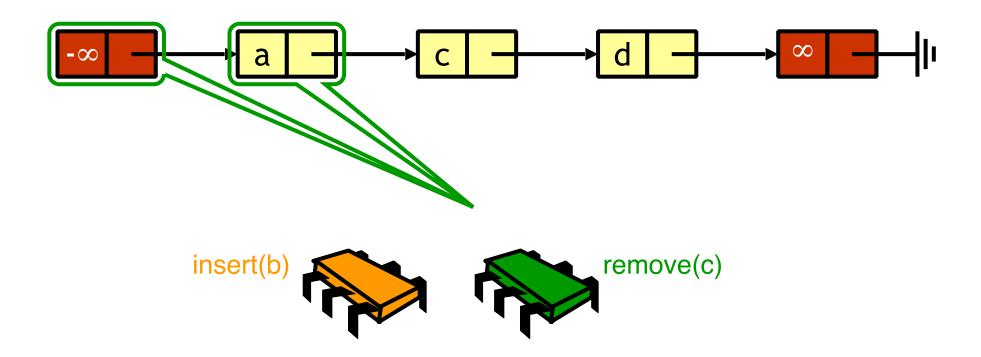


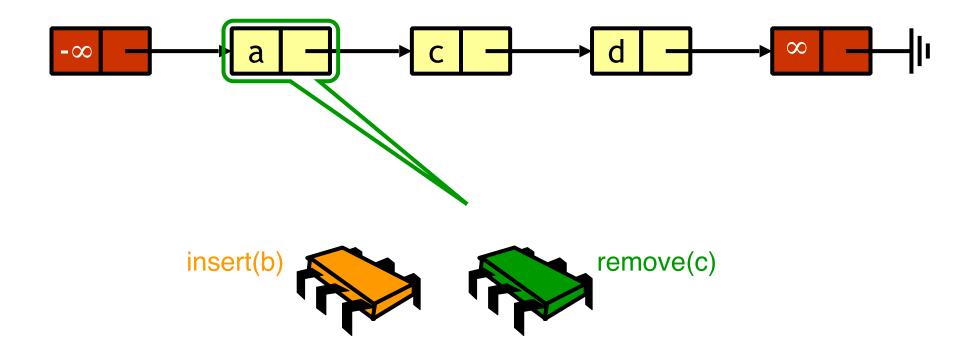


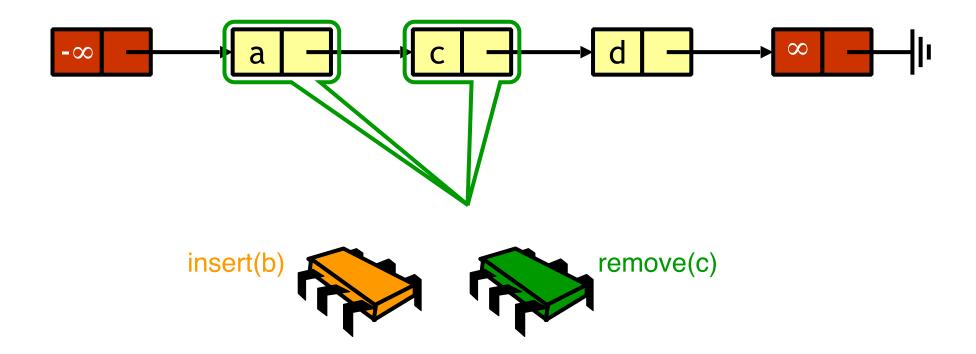


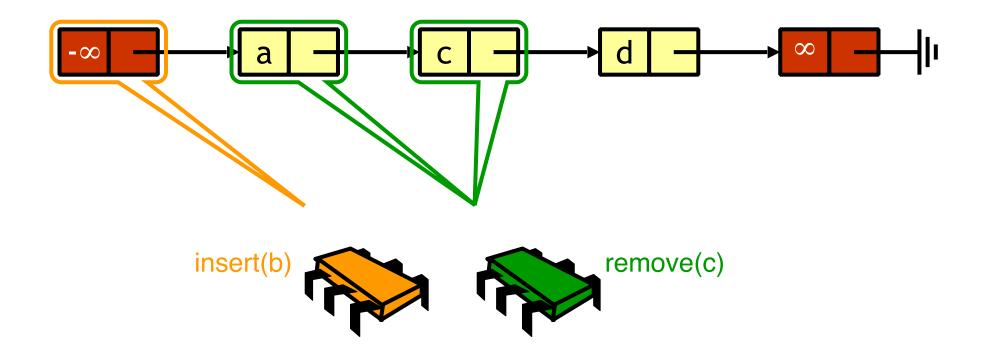
Concurrency: Foundations and Algorithms -

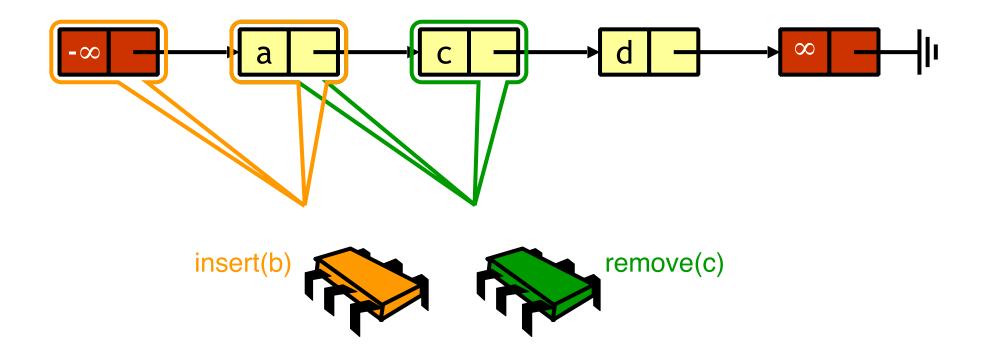


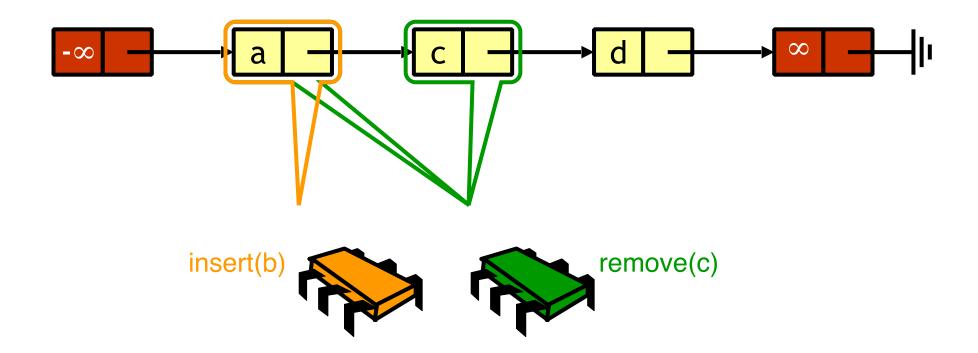


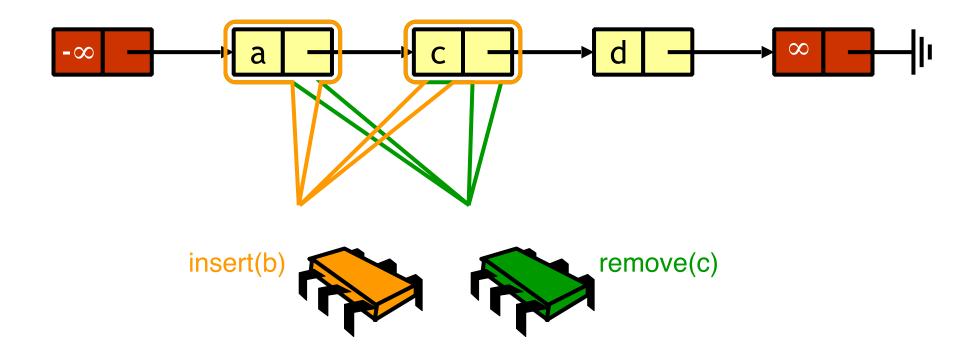


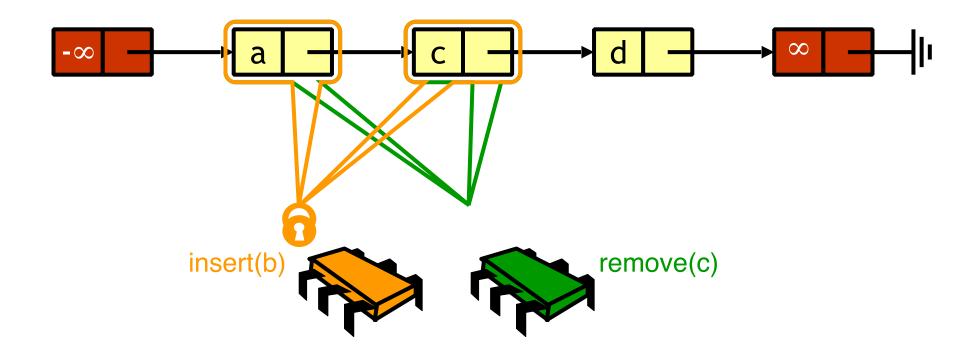


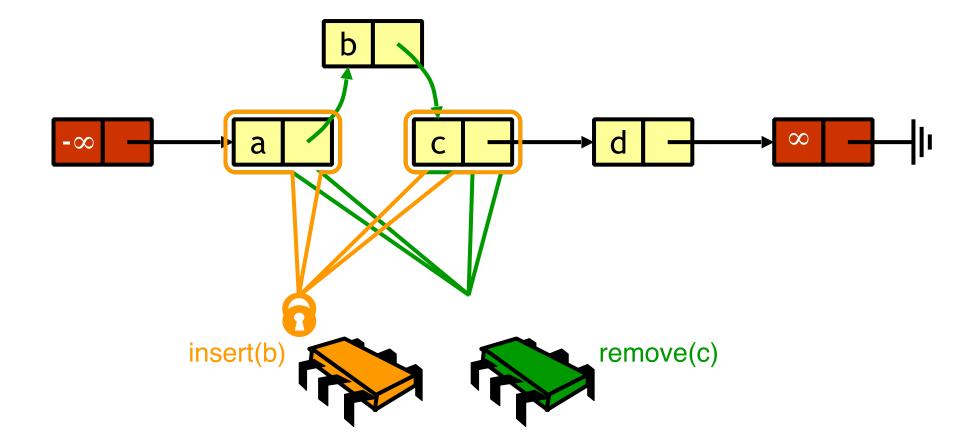


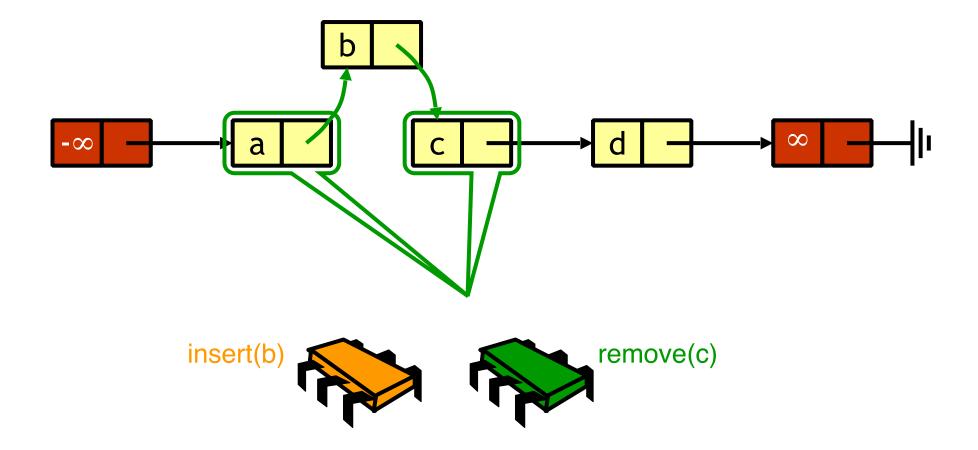


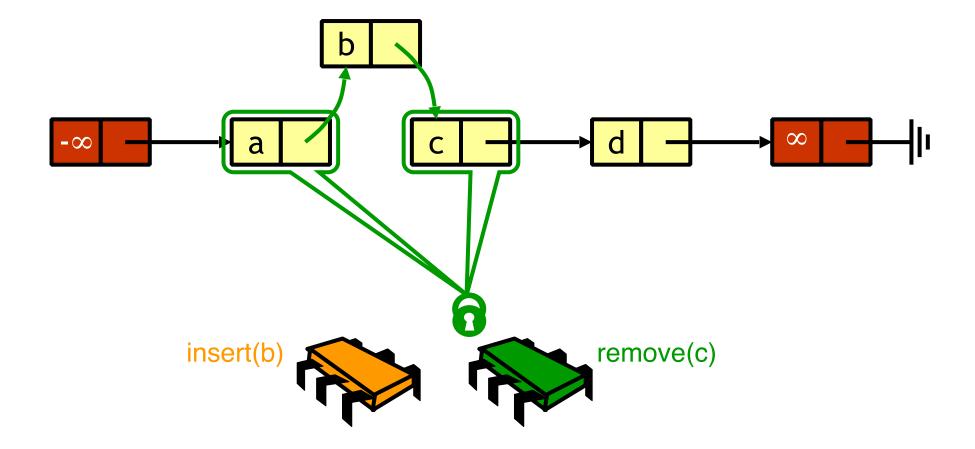


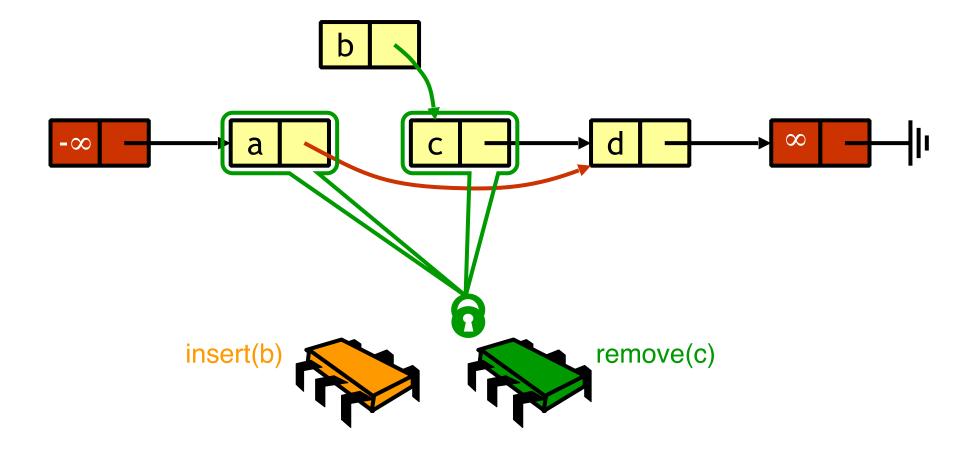


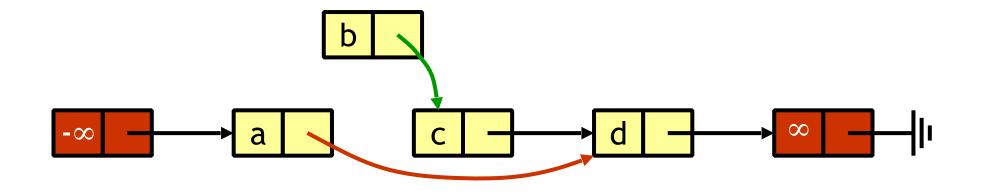




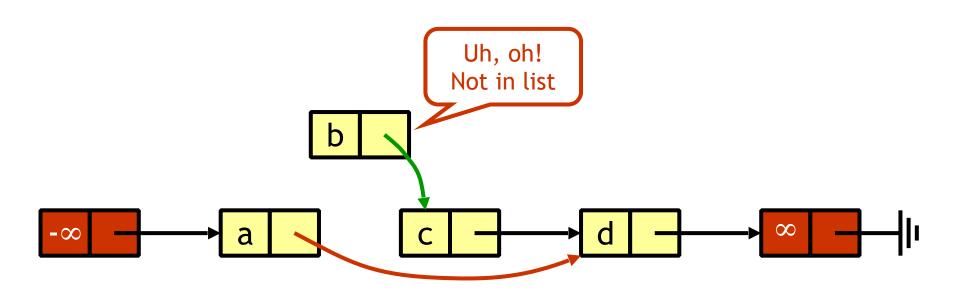




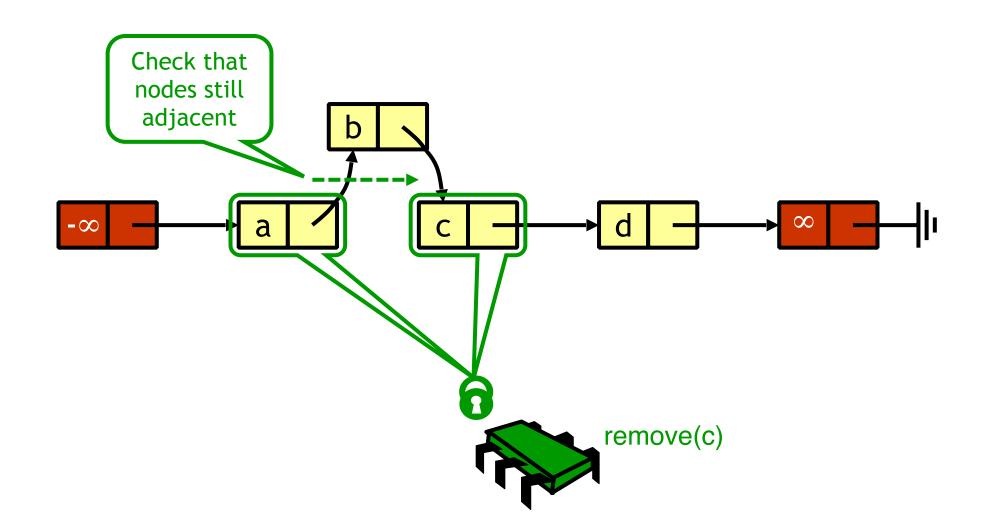


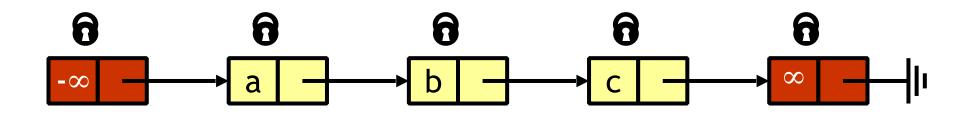






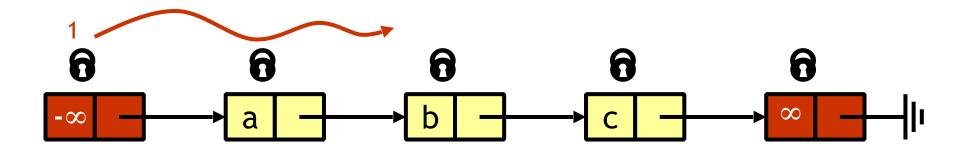






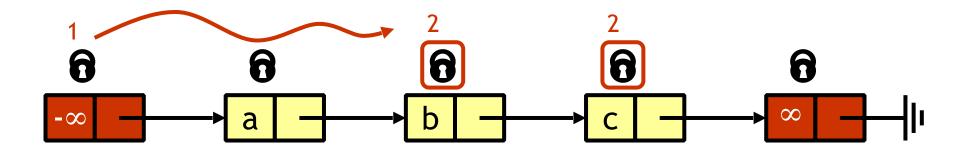
≻ To remove **C**

- Optimistically traverse list to find c
- Lock c.pred then lock c.curr
- ► Re-Traverse list to find **c** and verify that **c.pred** precedes **c.curr**
- Perform removal and release locks



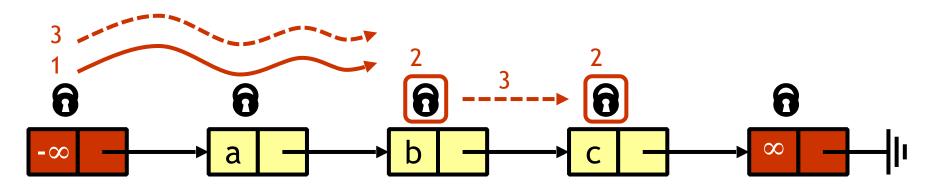
► To remove C

- Optimistically traverse list to find c
- Lock c.pred then lock c.curr
- ► Re-Traverse list to find **c** and verify that **c.pred** precedes **c.curr**
- Perform removal and release locks



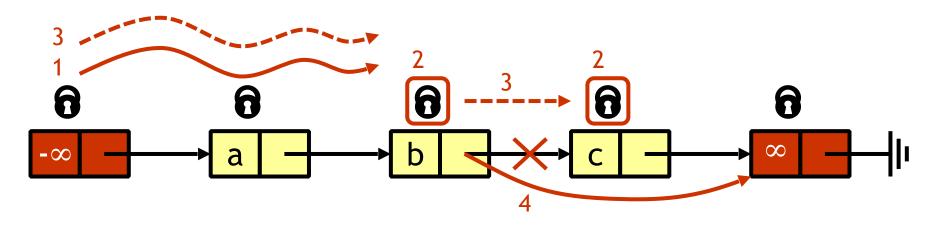
≻ To remove **C**

- Optimistically traverse list to find c
- Lock c.pred then lock c.curr
- ► Re-Traverse list to find **c** and verify that **c.pred** precedes **c.curr**
- Perform removal and release locks



► To remove C

- Optimistically traverse list to find c
- Lock c.pred then lock c.curr
- ► Re-Traverse list to find **c** and verify that **c.pred** precedes **c.curr**
- Perform removal and release locks



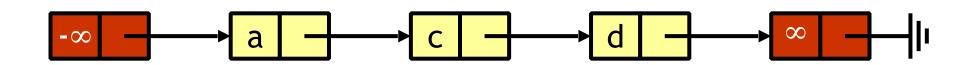
≻ To remove **C**

- Optimistically traverse list to find c
- Lock c.pred then lock c.curr
- ► Re-Traverse list to find **c** and verify that **c.pred** precedes **c.curr**
- Perform removal and release locks

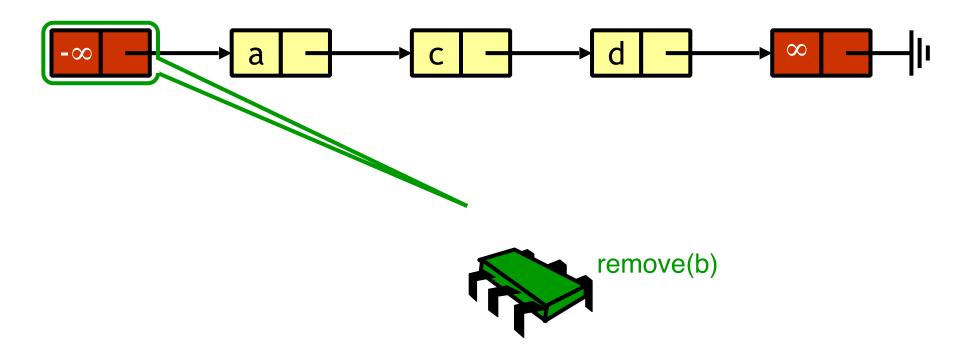
Correctness

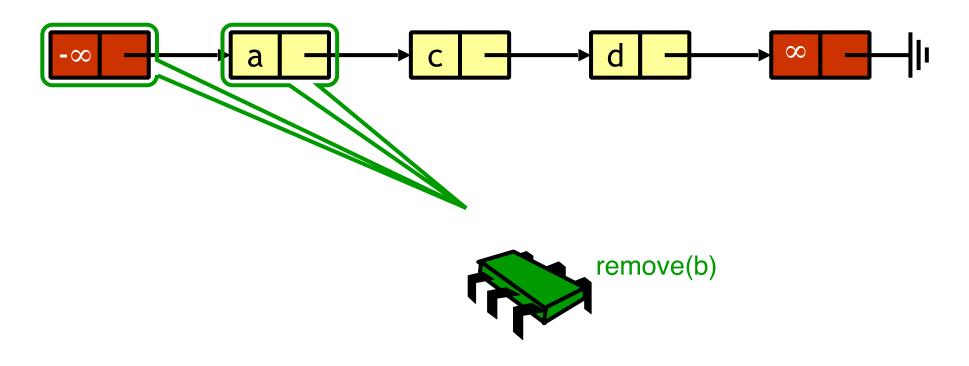
≻If

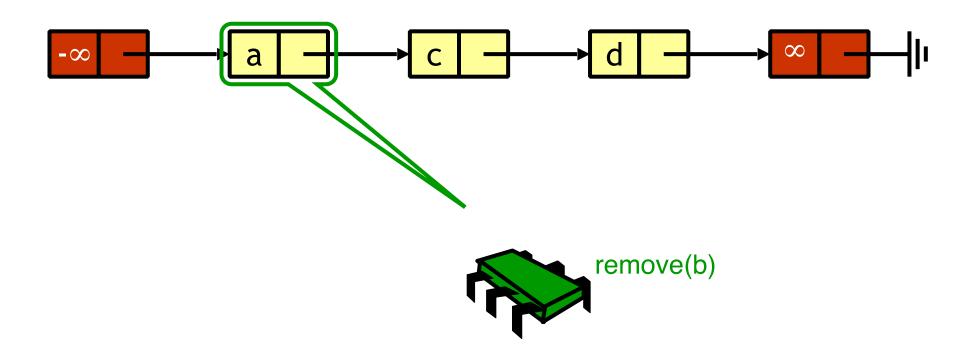
- ➤ Nodes **b** and **c** both locked
- Node b still accessible
- Node c still successor to b
- ≻ Then
 - Neither has been deleted
 - ► OK to delete c and return **true**

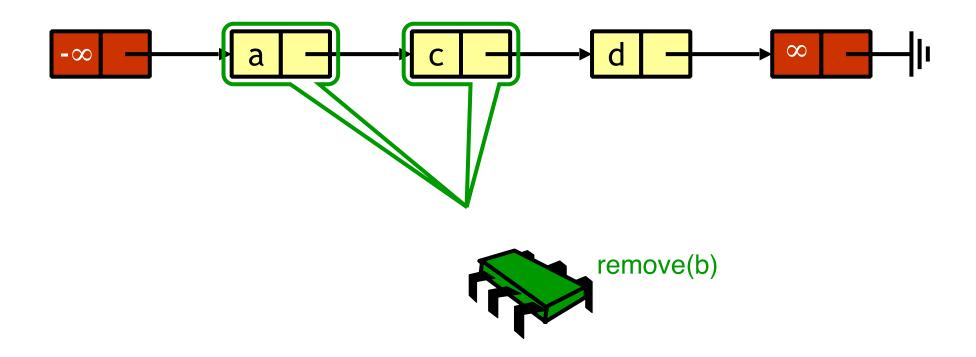


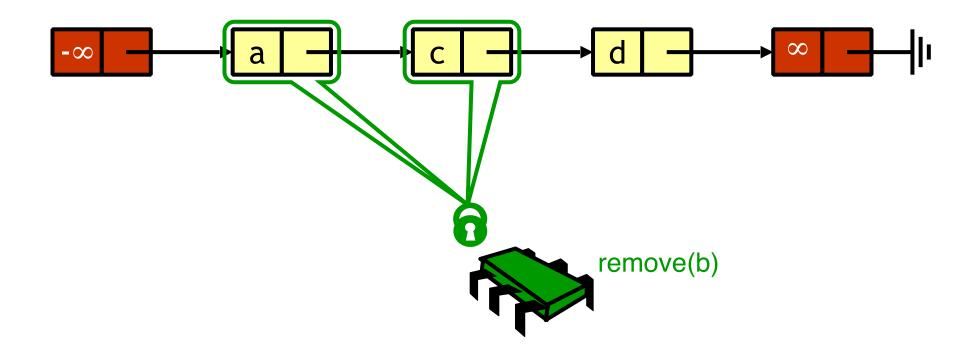


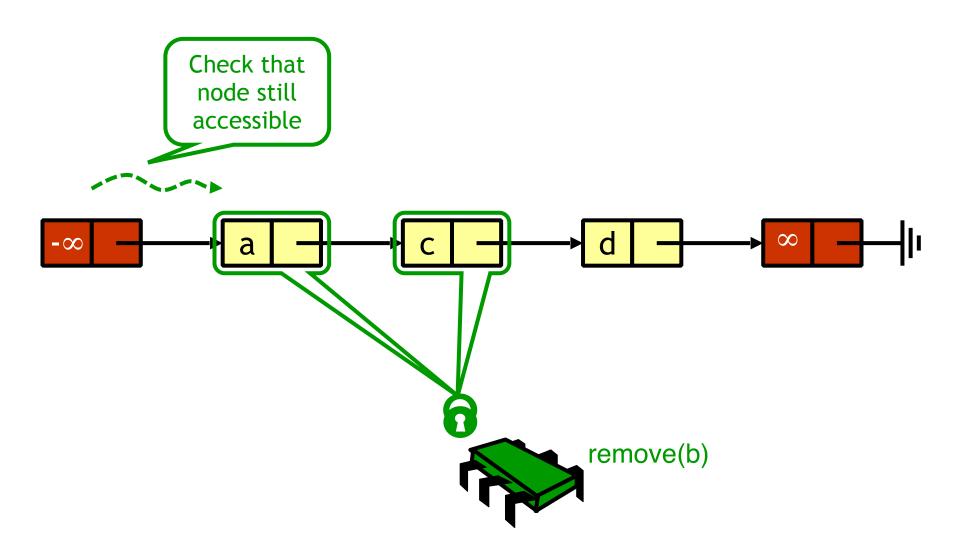


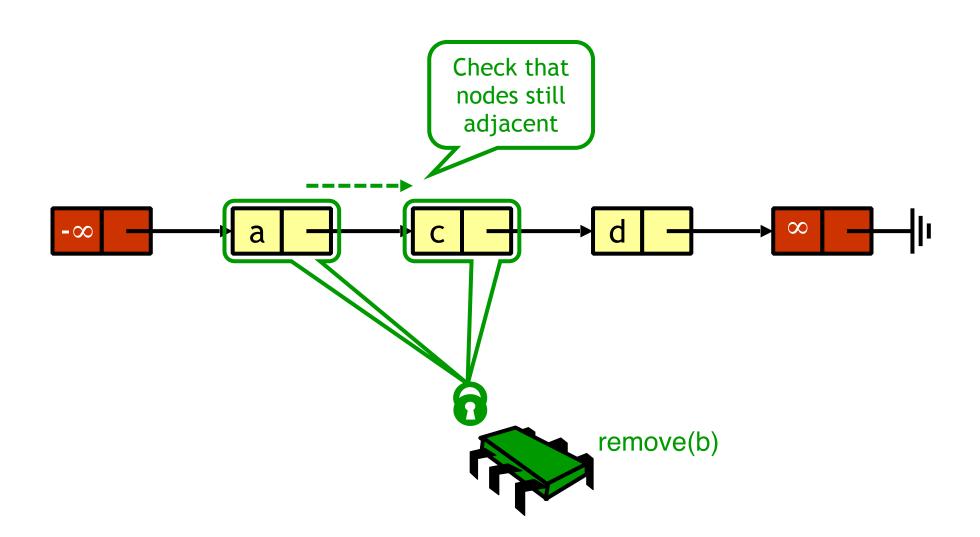


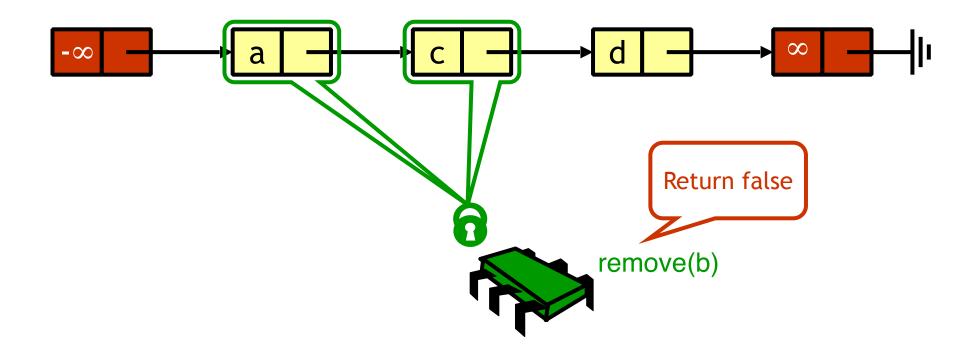


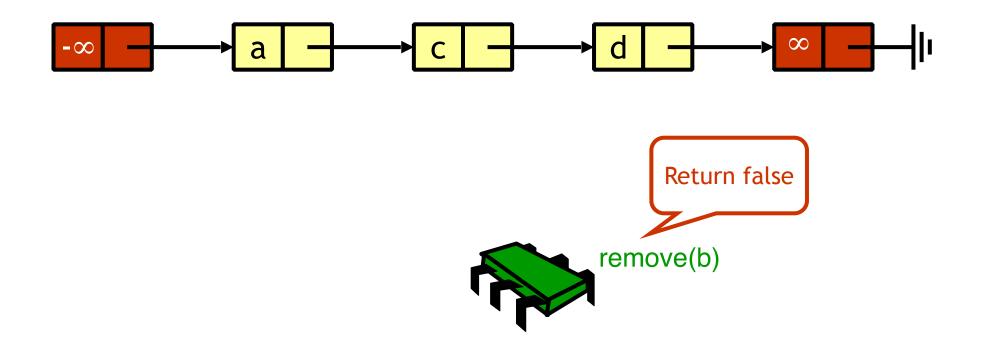












Correctness

≻If

- ► Nodes **a** and **c** both locked
- ► Node **a** still accessible
- ► Node **c** still successor to **a**

≻ Then

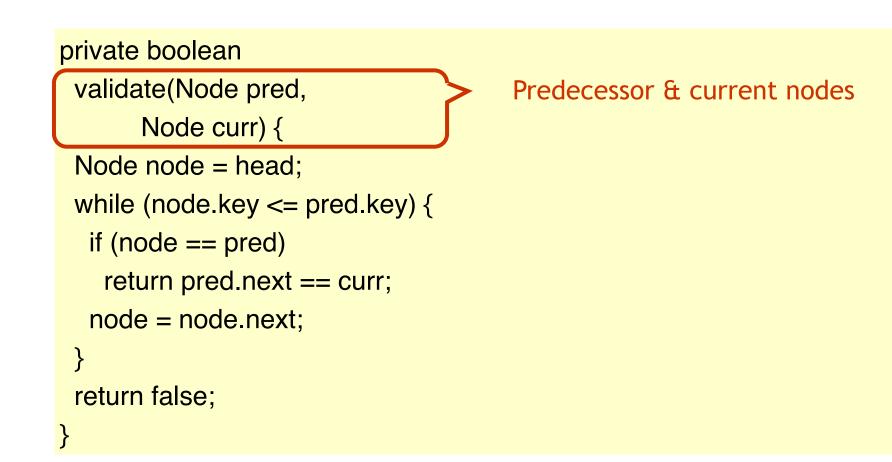
- Neither has been deleted
- ► No thread can add **b** after **a** while **a** is locked
- ► OK to return false

Validation

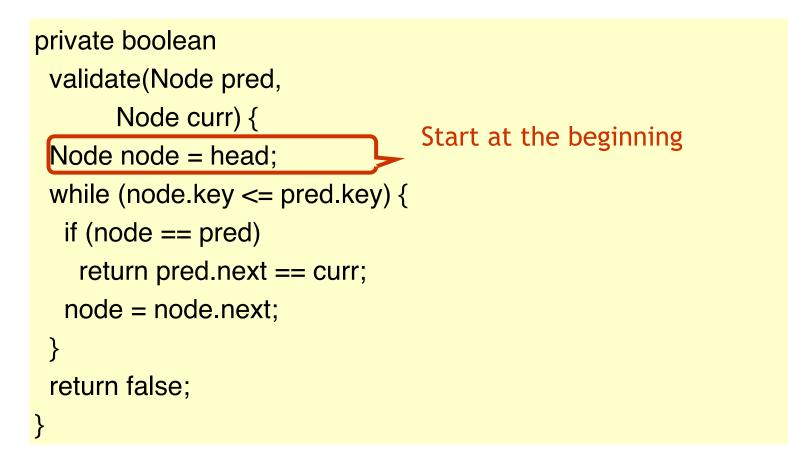
```
private boolean
 validate(Node pred,
       Node curr) {
 Node node = head;
 while (node.key <= pred.key) {</pre>
  if (node == pred)
   return pred.next == curr;
  node = node.next;
 }
 return false;
```

}

Validation



Validation



private boolean		
validate(Node pred,		
Node curr) {		
Node node = head;		Soarch range of kovs
while (node.key <= pred.key) {	َ ح	Search range of keys
if (node == pred)		
return pred.next == curr;		
node = node.next;		
}		
return false;		
}		

private boolean validate(Node pred, Node curr) { Node node = head; while (node.key <= pred.key) {</pre> if (node == pred) Predecessor reachable? return pred.next == curr; node = node.next; } return false; }

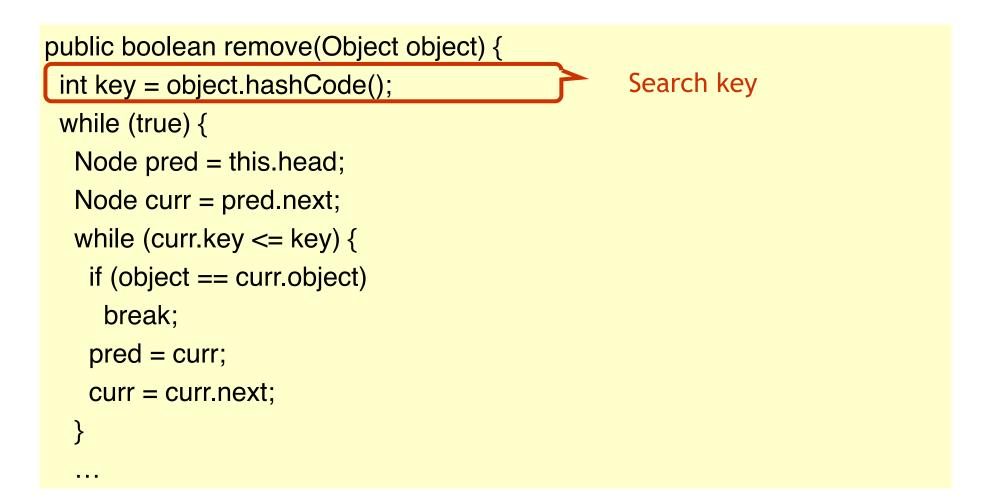
```
private boolean
 validate(Node pred,
       Node curr) {
 Node node = head;
 while (node.key <= pred.key) {</pre>
  if (node == pred)
   return pred.next == curr;
  node = node.next;
 }
 return false;
}
```

Current node next?

```
private boolean
 validate(Node pred,
       Node curr) {
 Node node = head;
 while (node.key <= pred.key) {</pre>
  if (node == pred)
   return pred.next == curr;
                                  Otherwise move on
  node = node.next;
 return false;
}
```

```
private boolean
 validate(Node pred,
       Node curr) {
 Node node = head;
 while (node.key <= pred.key) {</pre>
  if (node == pred)
   return pred.next == curr;
  node = node.next;
 }
 return false;
                           Predecessor not reachable
```

```
public boolean remove(Object object) {
 int key = object.hashCode();
 while (true) {
  Node pred = this.head;
  Node curr = pred.next;
  while (curr.key <= key) {</pre>
   if (object == curr.object)
     break;
   pred = curr;
   curr = curr.next;
  }
```



```
public boolean remove(Object object) {
 int key = object.hashCode();
 while (true) {
                              Retry on synchronization conflict
  Node pred = this.head;
  Node curr = pred.next;
  while (curr.key <= key) {</pre>
   if (object == curr.object)
     break;
   pred = curr;
   curr = curr.next;
  }
```

```
public boolean remove(Object object) {
 int key = object.hashCode();
 while (true) {
                                           Examine predecessor and
  Node pred = this.head;
                                           current nodes
  Node curr = pred.next;
  while (curr.key <= key) {</pre>
   if (object == curr.object)
     break;
   pred = curr;
   curr = curr.next;
  }
```

```
public boolean remove(Object object) {
 int key = object.hashCode();
 while (true) {
  Node pred = this.head;
  Node curr = pred.next;
                                                  Search by key
  while (curr.key \leq key) {
   if (object == curr.object)
     break;
   pred = curr;
   curr = curr.next;
  }
```

```
public boolean remove(Object object) {
 int key = object.hashCode();
 while (true) {
  Node pred = this.head;
  Node curr = pred.next;
  while (curr.key <= key) {</pre>
                                                      Stop if we find object
   if (object == curr.object)
     break;
   pred = curr;
   curr = curr.next;
  }
```

```
public boolean remove(Object object) {
 int key = object.hashCode();
 while (true) {
  Node pred = this.head;
  Node curr = pred.next;
  while (curr.key <= key) {</pre>
   if (object == curr.object)
     break:
                                       Move along
   pred = curr;
   curr = curr.next;
  }
```

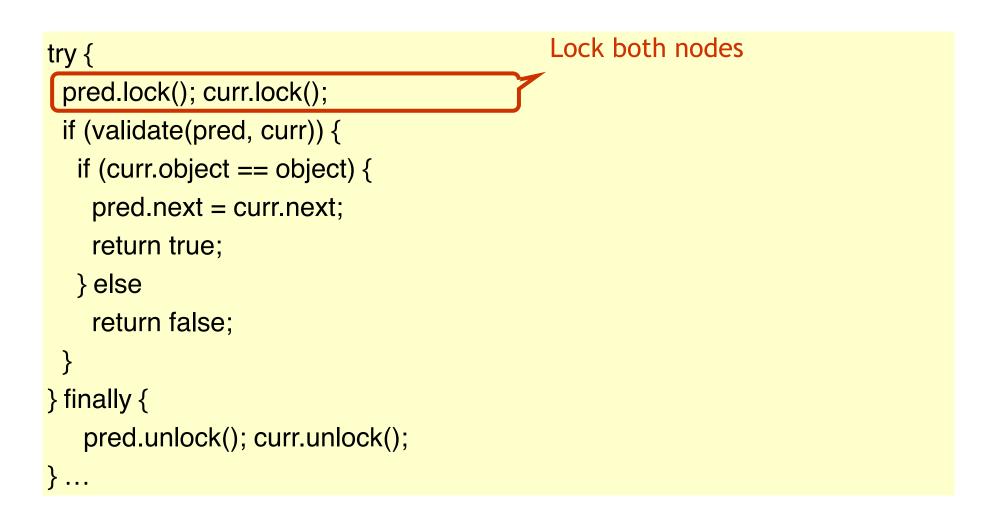
On Exit from Loop

- ► If object is present
 - curr holds object
 - pred just before curr
- ► If object is absent
 - ► curr has first higher key
 - pred just before curr

► Assuming no synchronization problems

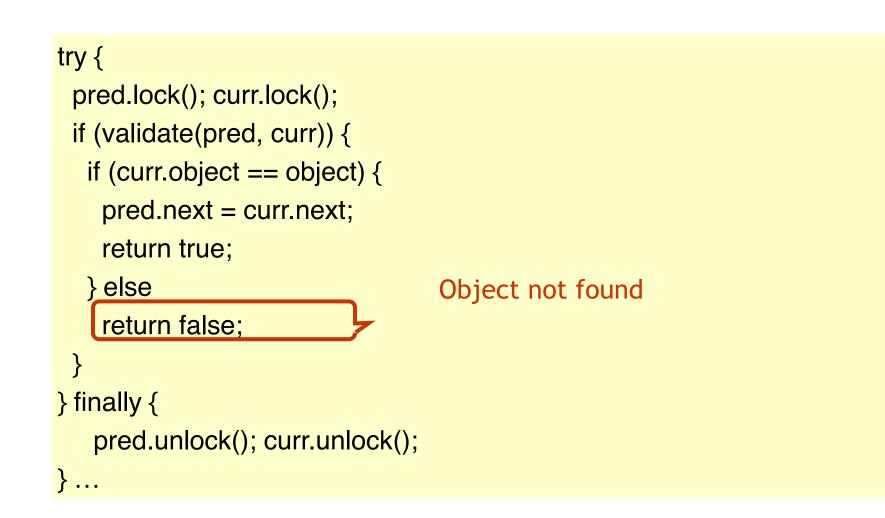
```
try {
 pred.lock(); curr.lock();
 if (validate(pred, curr)) {
  if (curr.object == object) {
    pred.next = curr.next;
    return true;
  } else
    return false;
 }
} finally {
   pred.unlock(); curr.unlock();
} ...
```

try {	
pred.lock(); curr.lock();	
if (validate(pred, curr)) {	
if (curr.object == object) {	
pred.next = curr.next;	
return true;	
} else	
return false;	
}	
} finally {	Always unlock
pred.unlock(); curr.unlock();	
}	



try {	
pred.lock(); curr.lock();	Check for synchronization
if (validate(pred, curr)) {	conflicts
if (curr.object == object) {	
pred.next = curr.next;	
return true;	
} else	
return false;	
}	
} finally {	
pred.unlock();	
}	

try {	
pred.lock(); curr.lock();	
if (validate(pred, curr)) {	
if (curr.object == object) {	Object found
pred.next = curr.next;	Object found, remove node
return true;	
} else	
return false;	
}	
<pre>} finally {</pre>	
pred.unlock(); curr.unlock();	
}	



Summary: Optimistic List

► Wait-free traversal

- ► May traverse removed nodes
- Must have non-interference (natural in languages with GC like Java)
- Limited hotspots
 - Only at locked add(), remove(), contains() destination locations, not traversals
- ► But two traversals
 - ► Yet traversals are wait-free

So Far, So Good

- ► Much less lock acquisition/release
 - ► Performance
 - ► Concurrency
- ➤ Problems
 - Need to traverse list twice
 - contains() acquires locks
 - ► Most common method call (90% in many applications)

► Optimistic works if

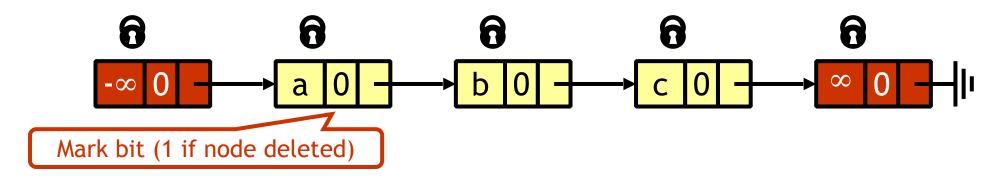
Cost of scanning twice without locks < cost of scanning once with locks</p>

Lazy List

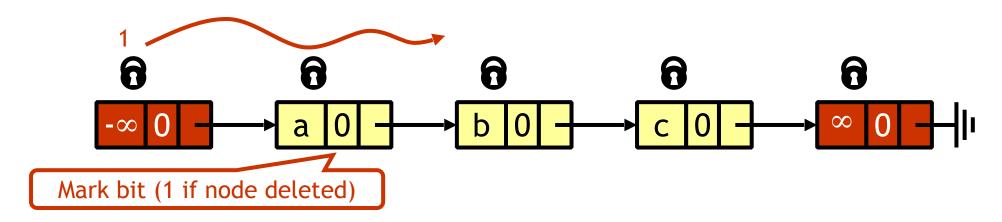
- Like optimistic, except
 - ► Scan once
 - contains() never locks
- ► Key insight
 - Removing nodes causes trouble
 - ► Do it "lazily"

Lazy List

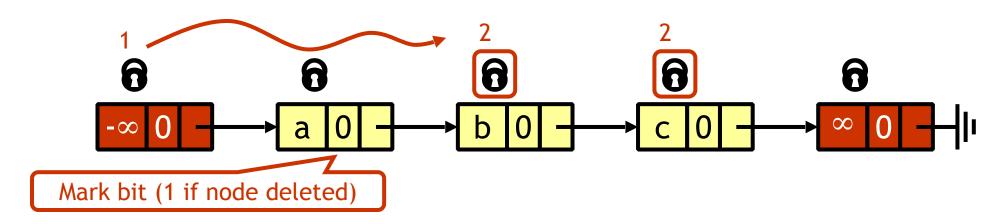
- ► Remove Method
 - Scans list (as before)
 - Locks predecessor & current (as before)
- ► Logical delete
 - Marks current node as removed (new!)
 - Use additional mark bit in node
- ► Physical delete
 - Redirects predecessor's next (as before)



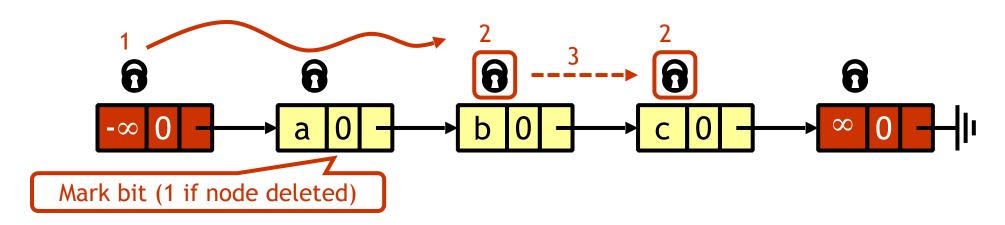
- Optimistically traverse list to find c
- Lock c.pred then lock c.curr
- Verify marks and that c.pred precedes c.curr
- Set mark bit (logical removal)
- Perform physical removal and release locks



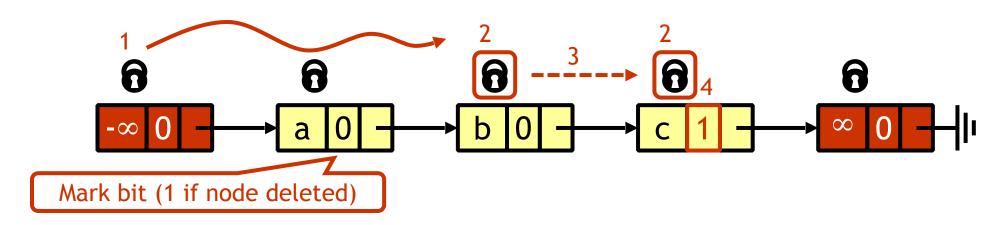
- Optimistically traverse list to find c
- Lock c.pred then lock c.curr
- Verify marks and that c.pred precedes c.curr
- Set mark bit (logical removal)
- Perform physical removal and release locks



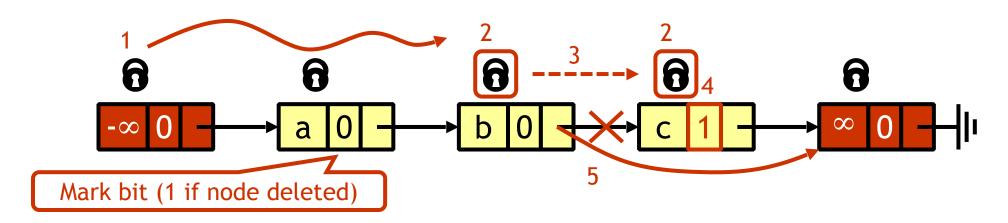
- Optimistically traverse list to find c
- Lock c.pred then lock c.curr
- Verify marks and that c.pred precedes c.curr
- Set mark bit (logical removal)
- Perform physical removal and release locks



- Optimistically traverse list to find c
- Lock c.pred then lock c.curr
- Verify marks and that c.pred precedes c.curr
- Set mark bit (logical removal)
- Perform physical removal and release locks



- Optimistically traverse list to find c
- Lock c.pred then lock c.curr
- Verify marks and that c.pred precedes c.curr
- Set mark bit (logical removal)
- Perform physical removal and release locks



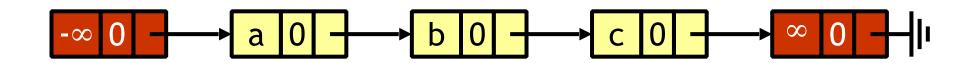
- Optimistically traverse list to find c
- Lock c.pred then lock c.curr
- Verify marks and that c.pred precedes c.curr
- Set mark bit (logical removal)
- Perform physical removal and release locks

Lazy List

- ► All Methods
 - Scan through locked and marked nodes
 - ► Removing a node does not slow down other method calls...
 - Must still lock pred and curr nodes

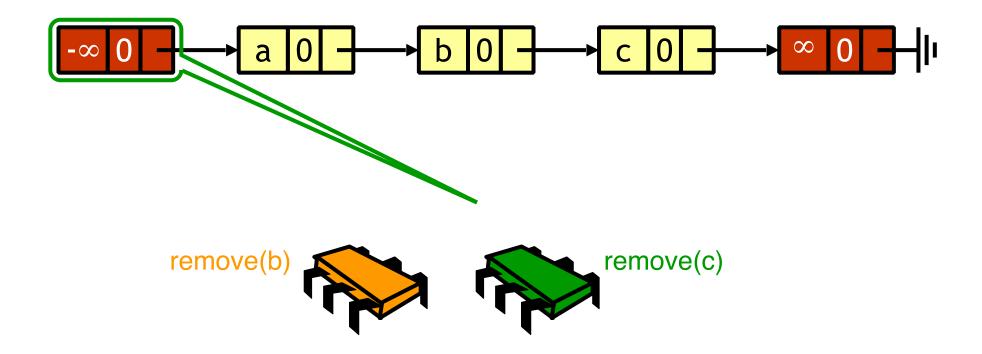
► Validation

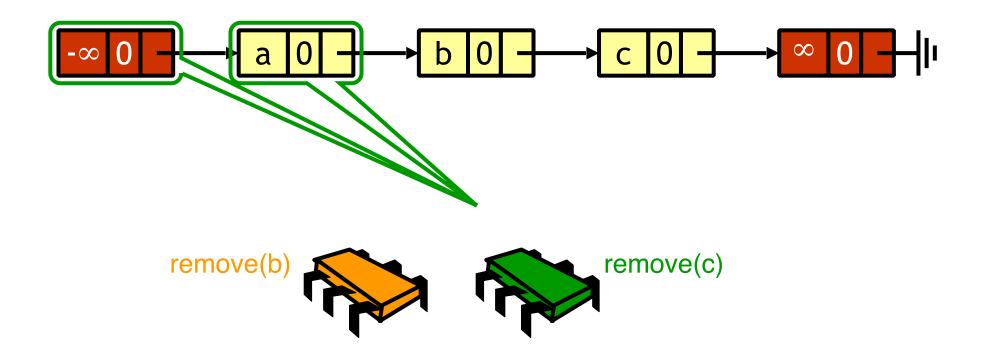
- ► No need to rescan list!
- Check that pred is not marked
- Check that curr is not marked
- Check that pred points to curr

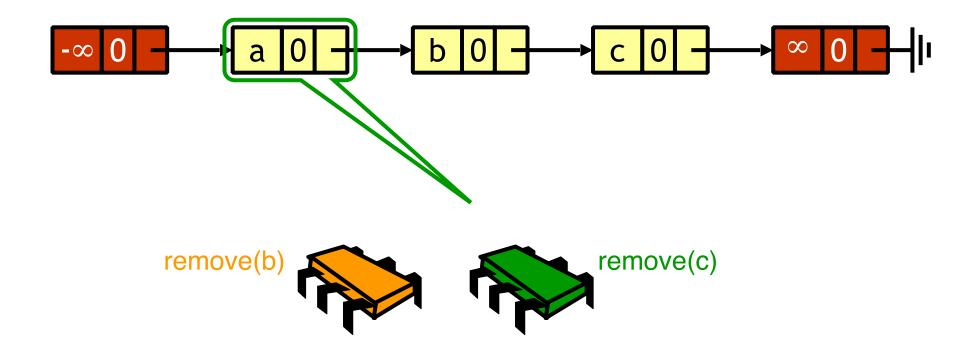


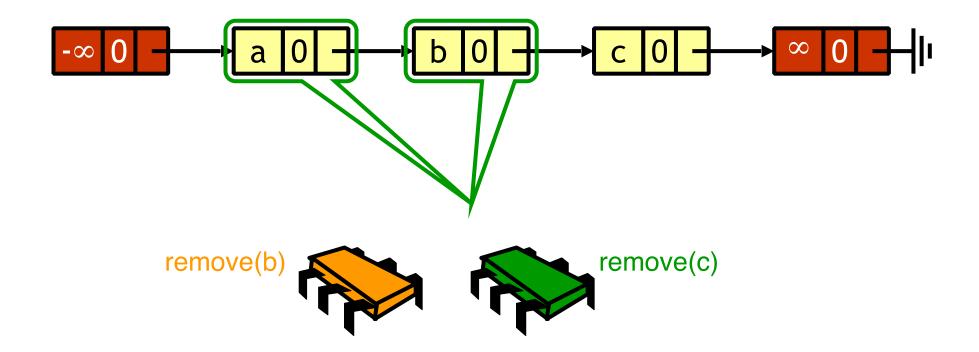


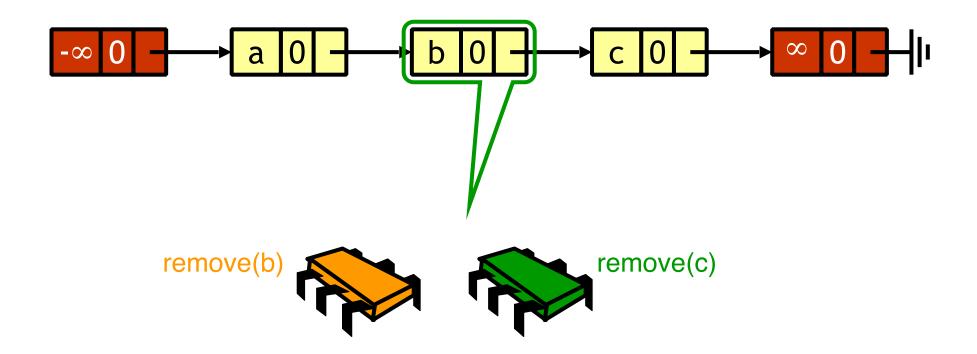
Concurrency: Foundations and Algorithms -

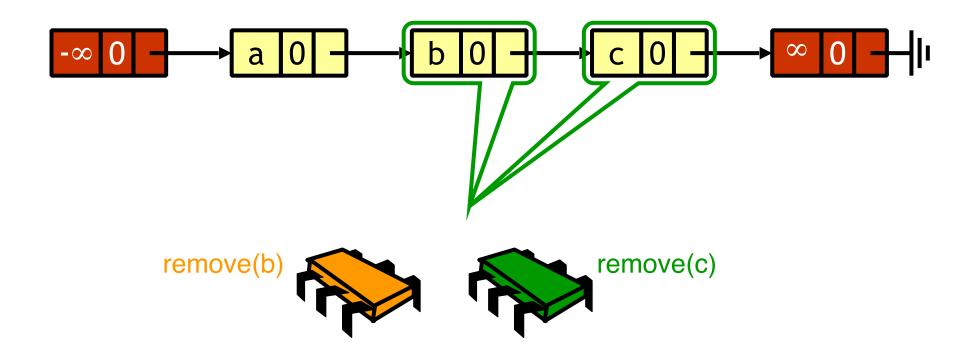


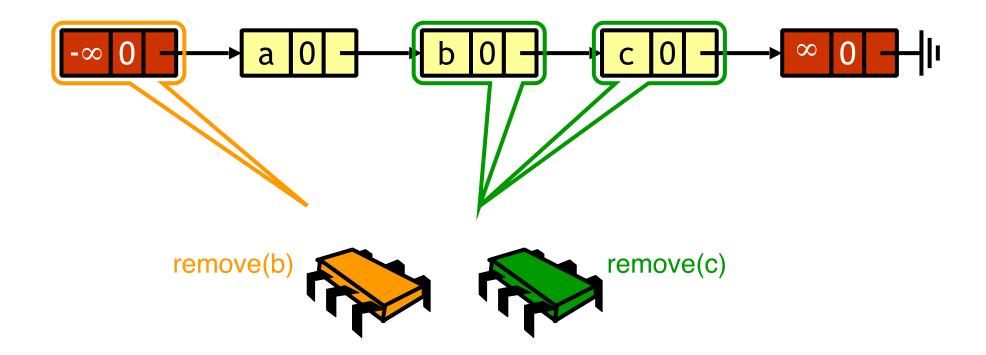


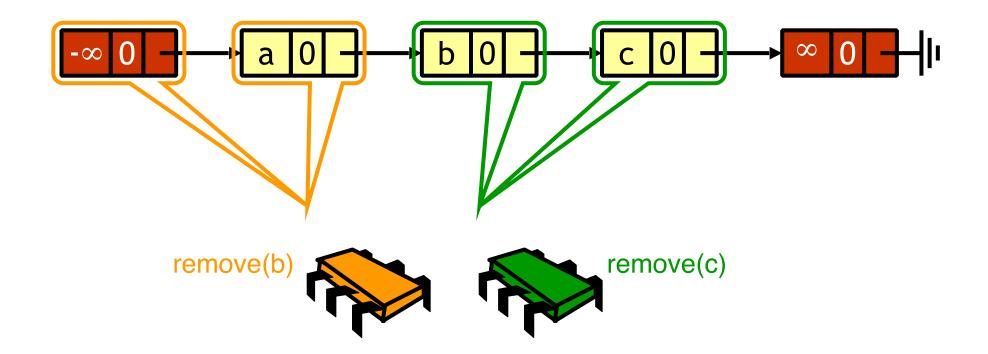


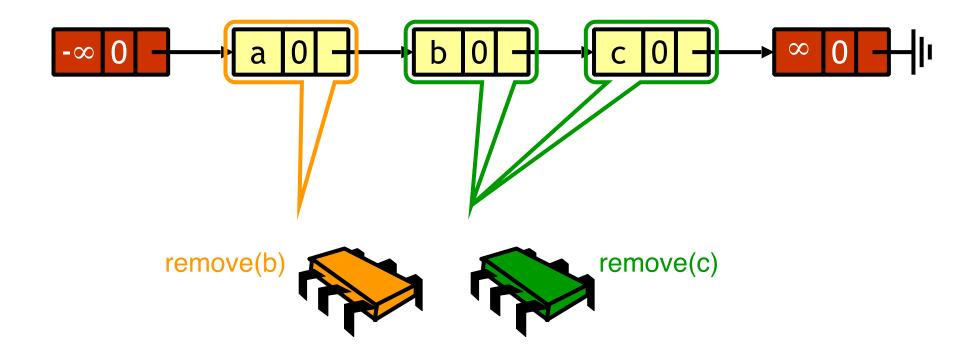


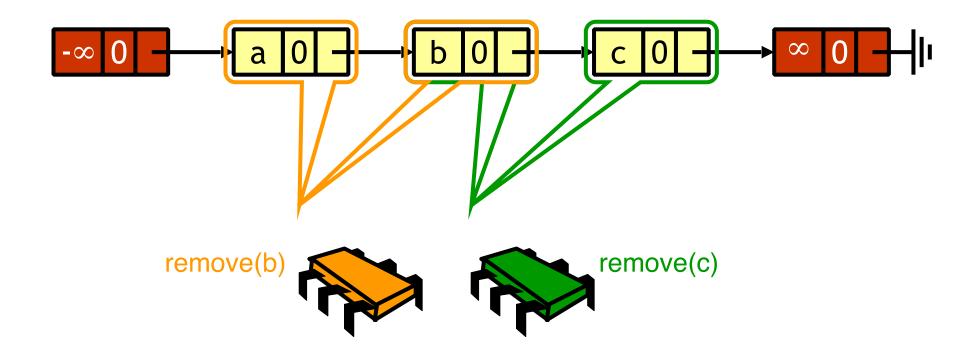


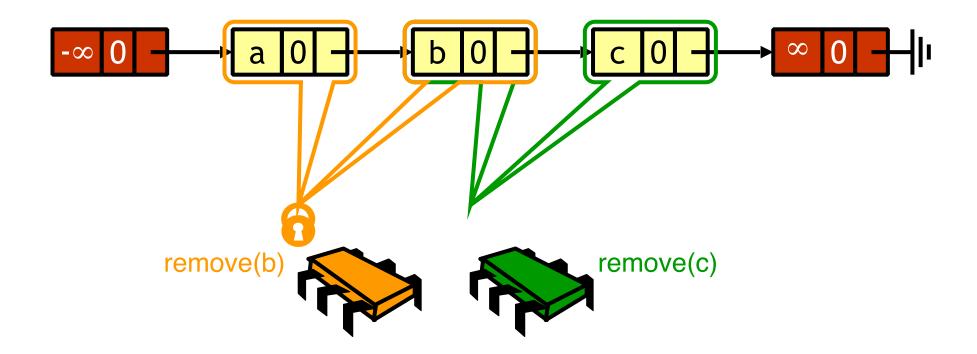


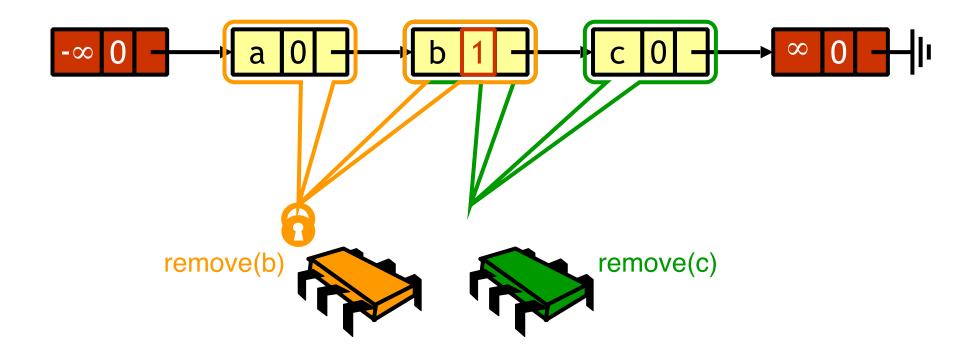


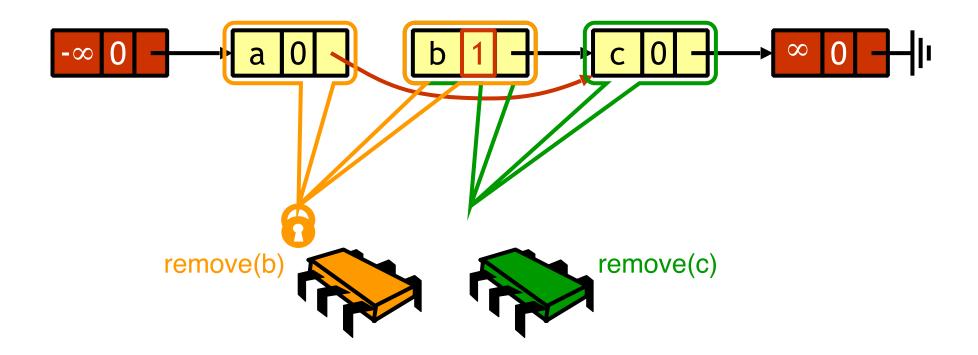


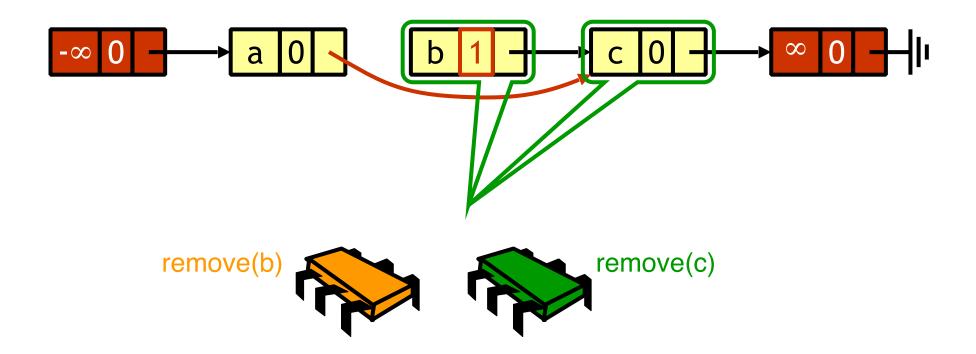


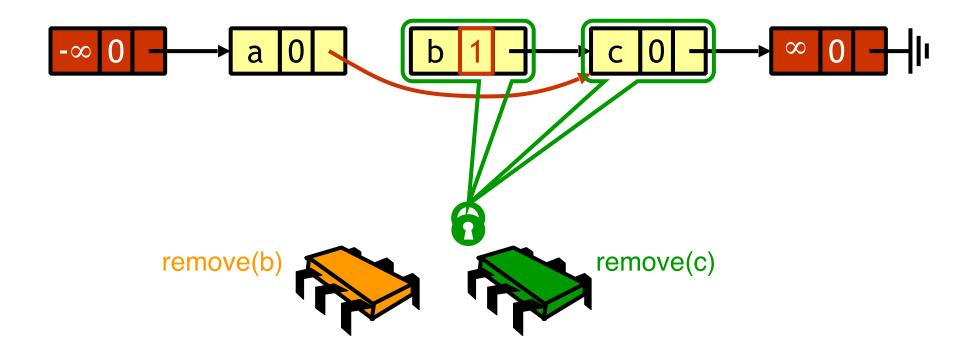


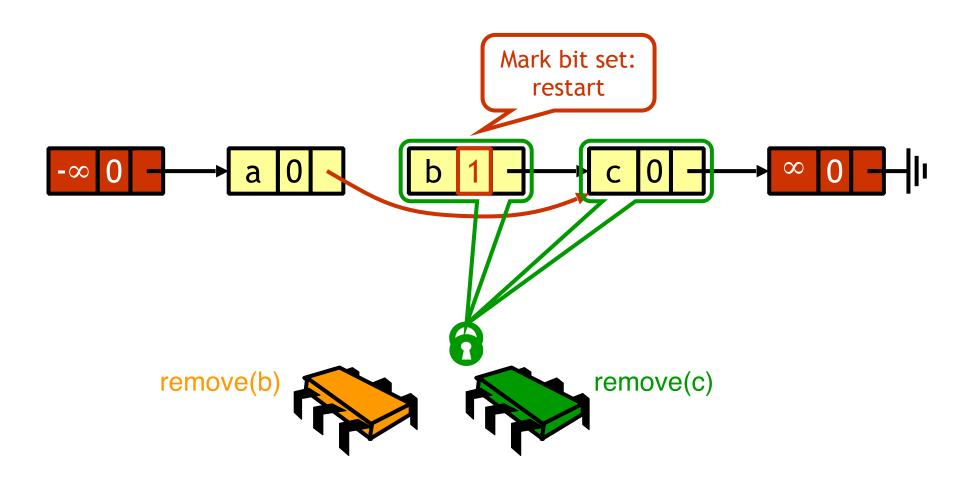








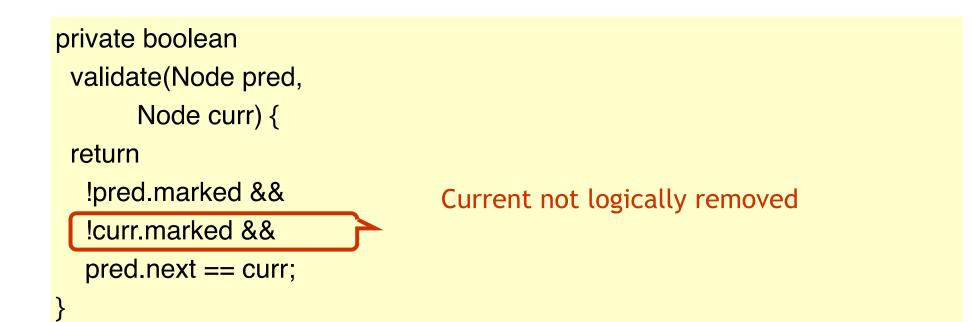




```
private boolean
validate(Node pred,
Node curr) {
return
!pred.marked &&
!curr.marked &&
pred.next == curr;
```

}

private boolean	
validate(Node pred,	
Node curr) {	
return	Predecessor not logically removed
!pred.marked &&	
!curr.marked &&	
pred.next == curr;	
}	



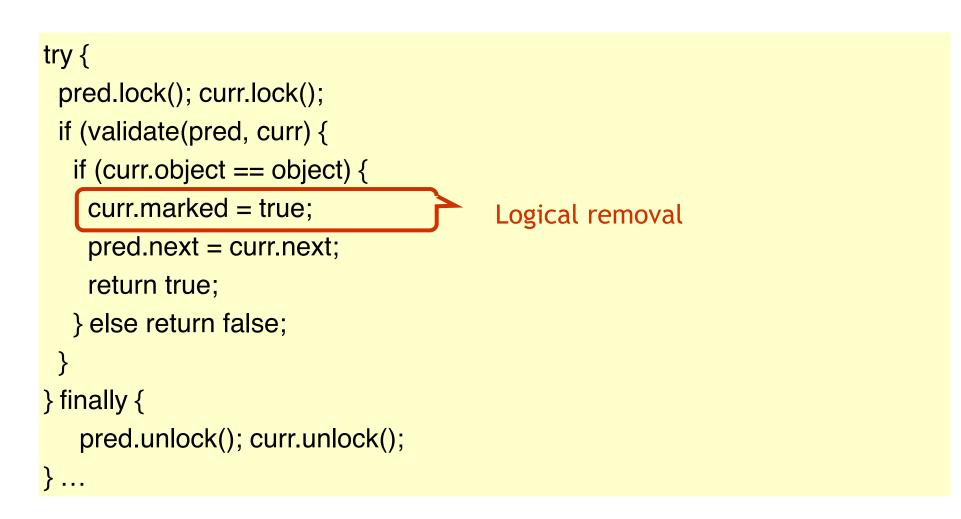
```
private boolean
validate(Node pred,
    Node curr) {
    return
    !pred.marked &&
    !curr.marked &&
    pred.next == curr;
} Predecessor still points to current
```

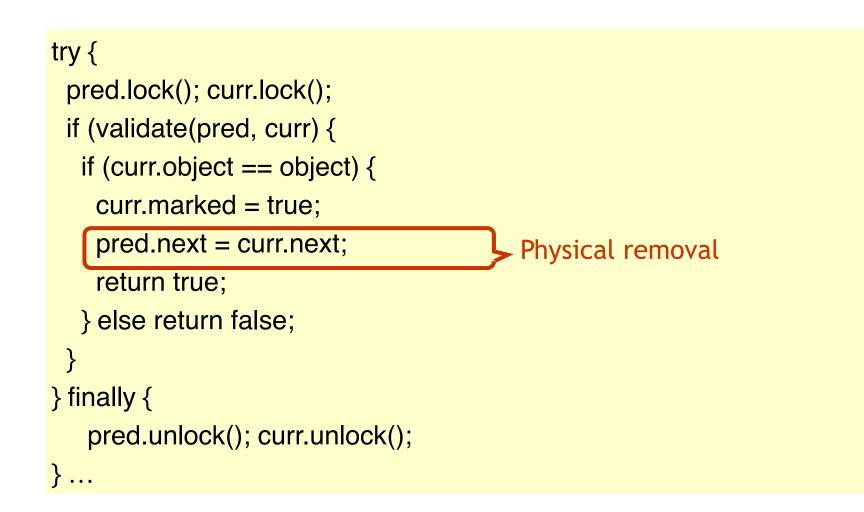
```
try {
 pred.lock(); curr.lock();
 if (validate(pred, curr) {
  if (curr.object == object) {
    curr.marked = true;
    pred.next = curr.next;
    return true;
  } else return false;
 }
} finally {
   pred.unlock(); curr.unlock();
} . . .
```

try {	
pred.lock(); curr.lock();	Valida
if (validate(pred, curr) {	valiua
if (curr.object == object) {	
curr.marked = true;	
pred.next = curr.next;	
return true;	
} else return false;	
}	
<pre>} finally {</pre>	
pred.unlock(); curr.unlock();	
}	

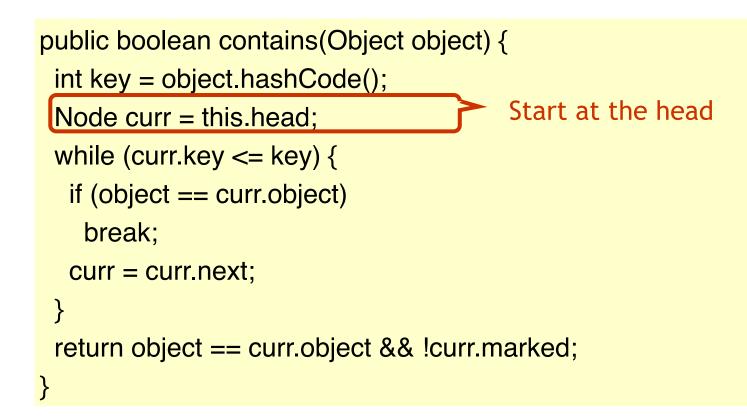
Validate as before

try {	
pred.lock(); curr.lock();	
if (validate(pred, curr) {	
if (curr.object == object) { Object found	
curr.marked = true;	
pred.next = curr.next;	
return true;	
} else return false;	
}	
} finally {	
pred.unlock(); curr.unlock();	
}	





```
public boolean contains(Object object) {
 int key = object.hashCode();
 Node curr = this.head;
 while (curr.key <= key) {</pre>
  if (object == curr.object)
    break;
  curr = curr.next;
 }
 return object == curr.object && !curr.marked;
}
```



```
public boolean contains(Object object) {
    int key = object.hashCode();
    Node curr = this.head;
    while (curr.key <= key) {
        if (object == curr.object)
            break;
        curr = curr.next;
        }
        Traverse without
        locking
        (nodes may have
        been removed)</pre>
```

return object == curr.object && !curr.marked;

}

```
public boolean contains(Object object) {
 int key = object.hashCode();
 Node curr = this.head;
 while (curr.key <= key) {</pre>
  if (object == curr.object)
   break;
  curr = curr.next;
 }
return object == curr.object && !curr.marked;
                                                           Present and undeleted?
```

Summary: Lazy List

- Wait-free traversal uses mark bit + fact that list is ordered
 - ► Not marked \Rightarrow in the set
 - > Marked or missing \Rightarrow not in the set
- > Lazy add()
- > Lazy remove()
- ► Wait-free contains()

Evaluation

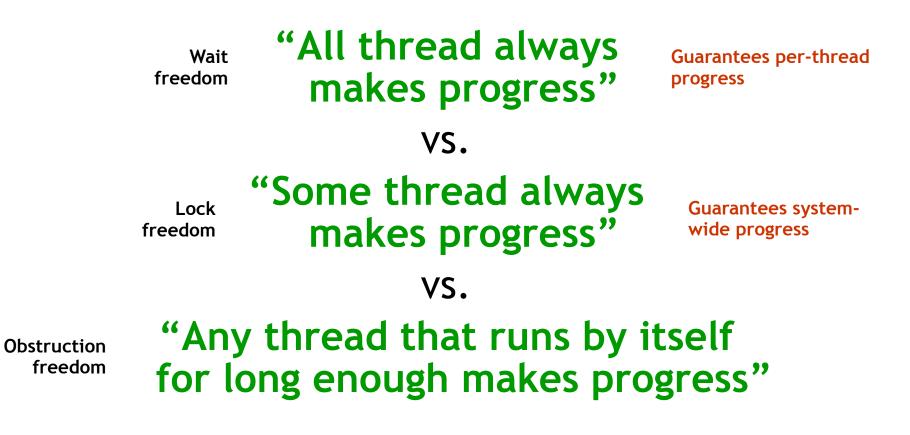
► Good

- contains() does not need to lock
 - ► In fact, it is wait-free!
 - ► Good because it is typically called often
- Uncontended calls do not re-traverse
- ≻ Bad
 - Contended calls do re-traverse
 - ➤ Traffic jam if one thread delays

Traffic Jam

- Any concurrent data structure based on mutual exclusion has a weakness
- ► If one thread
 - Enters critical section
 - And "eats the big muffin" (stops running)
 - ► Cache miss, page fault, de-scheduled...
 - Everyone else using that lock is stuck!

Wait/Lock/Obstruction Freedom



Lock–Free Data Structures

► No matter what...

- Some thread will complete method call
- Even if others halt at malicious times
- ➤ Weaker than wait-free, yet

► Implies that

- ➤ You cannot use locks
- ➤ Um, that is why they call it lock-free

RMW Atomic Operations

► Read-modify-write operation combines...

- ► Read from memory
- ► Modify value
- ► Write to memory
- ► ... atomically
- Supported by modern processors
 - Atomic increment/decrement, test-and-set, compare-and-set, etc.

> In Java: java.util.concurrent.atomic

```
public class AtomicInteger {
    int value;
```

```
public synchronized int
incrementAndGet() {
  value = value + 1;
  return value;
}
public synchronized int
decrementAndGet() {
  return --value;
```

public class AtomicInteger {

int value;

Package java.util.concurrent.atomic

```
public synchronized int
incrementAndGet() {
  value = value + 1;
  return value;
}
public synchronized int
decrementAndGet() {
  return --value;
```

public class AtomicInteger {
 int value;

```
public synchronized int
incrementAndGet() {
  value = value + 1;
  return value;
```

Increment value

public synchronized int
decrementAndGet() {
 return --value;

```
public class AtomicInteger {
    int value;
```

```
public synchronized int
incrementAndGet() {
  value = value + 1;
  return value;
```

```
public synchronized int
decrementAndGet() {
  return --value;
```

Decrement value (pre-decrement operator is not atomic!)

```
public class AtomicInteger {
    int value;
```

```
public synchronized int
incrementAndGet() {
  value = value + 1;
  return value;
```

```
public synchronized int
decrementAndGet() {
  return --value;
```

; x86 LOCK INC ... LOCK DEC ... LOCK XADD ...

Decrement value (pre-decrement operator is not atomic!)

Get-and-Set

```
public class AtomicBoolean {
    boolean value;
```

```
public synchronized boolean
getAndSet(boolean newValue) {
  boolean prior = value;
  value = newValue;
  return prior;
```

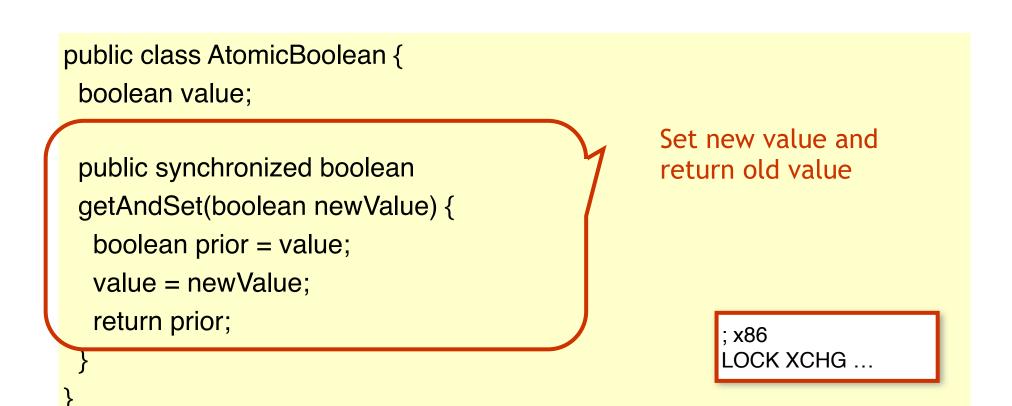
Get-and-Set

public class AtomicBoolean {
 boolean value;

```
public synchronized boolean
getAndSet(boolean newValue) {
  boolean prior = value;
  value = newValue;
  return prior;
```

Set new value and return old value

Get-and-Set



Compare-and-Set

public class AtomicInteger {
 int value;

Compare-and-Set

public class AtomicInteger {

int value;

true if old value matches expected value, return false otherwise

Set new value and return

```
return false;
```

Compare-and-Set

public class AtomicInteger {

int value:

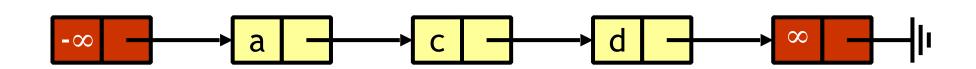
Set new value and return true if old value matches expected value, return false otherwise

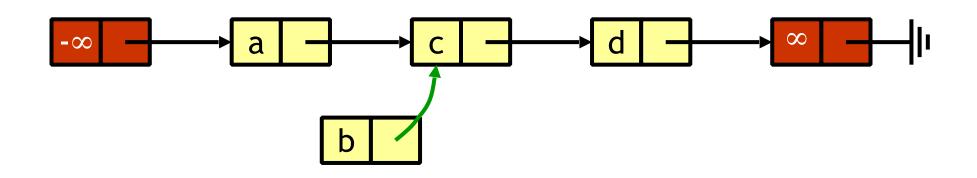
> ; x86 LOCK CMPXCHG …

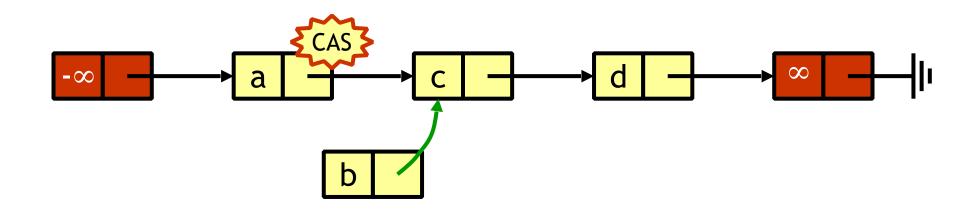
return false;

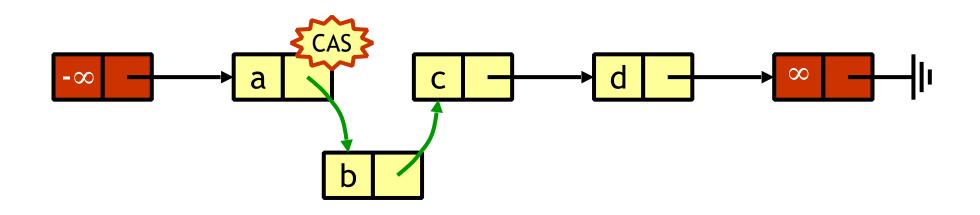
Lock-Free Lists

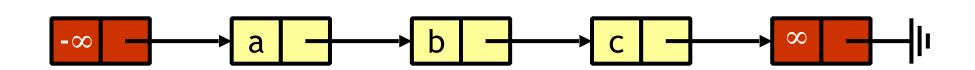
- ► Next logical step
- Eliminate locking entirely
- > contains() wait-free and add() and remove() lock-free
- ► Use only **compareAndSet()** to atomically update links

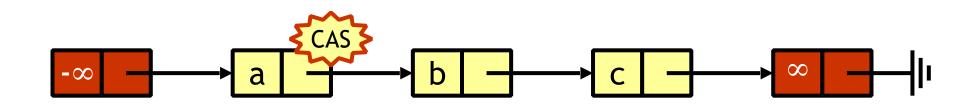


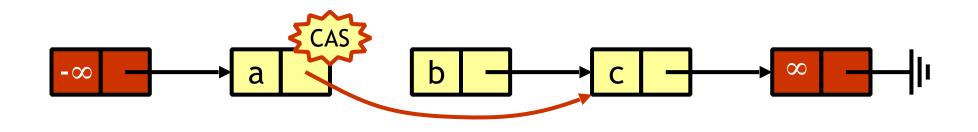


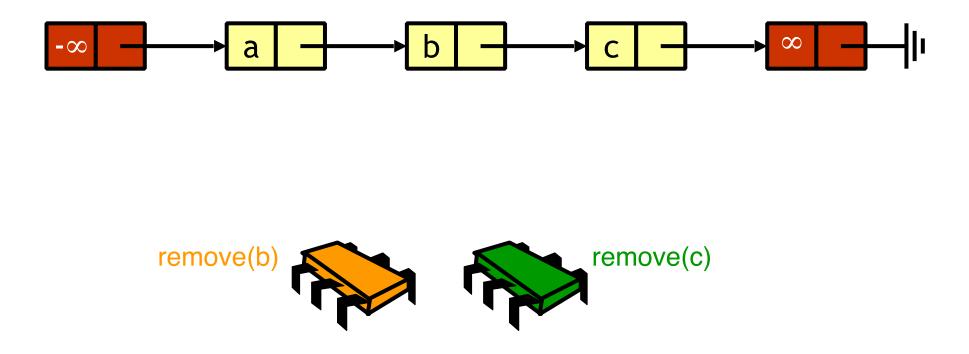


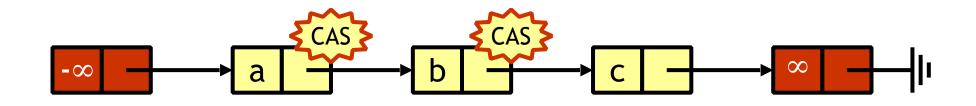


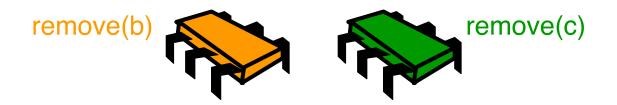


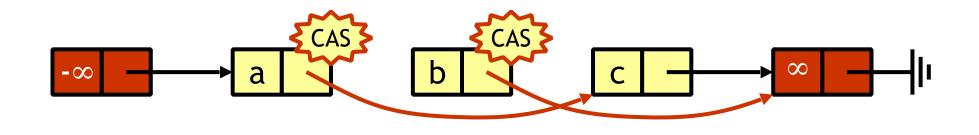




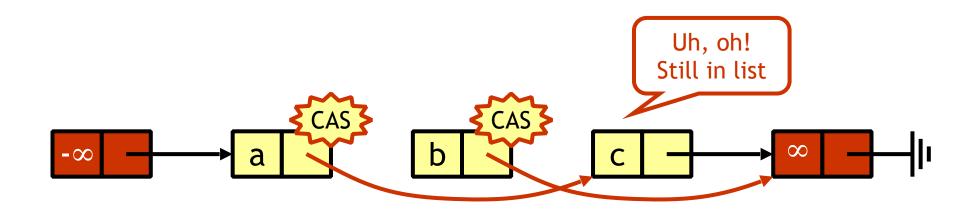


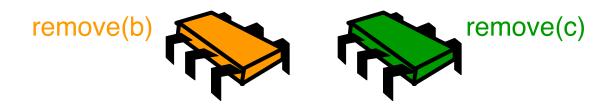












► Problem

Method updates node's next field after node has been removed

► Solution

- > Use AtomicMarkableReference
- ► Atomically
 - Swing reference and update flag
- ► Remove in two steps
 - Set mark bit in next field
 - Redirect predecessor's pointer

Marking a Node

- >AtomicMarkableReference class
 - In package java.util.concurrent.atomic
 - ► Holds a reference and a mark bit



Marking a Node

- >AtomicMarkableReference class
 - In package java.util.concurrent.atomic
 - ► Holds a reference and a mark bit



Marking a Node

- >AtomicMarkableReference class
 - In package java.util.concurrent.atomic
 - ► Holds a reference and a mark bit



public class AtomicMarkableReference <T> { public T get(boolean[] marked); public boolean compareAndSet(T expectedRef, T updateRef, boolean expectedMark, boolean updateMark); public boolean attemptMark(T expectedRef, boolean updateMark);

Data type

public class AtomicMarkableReference <T> { public T get(boolean[] marked); public boolean compareAndSet(T expectedRef, T updateRef, boolean expectedMark, boolean updateMark); public boolean attemptMark(T expectedRef, boolean updateMark);

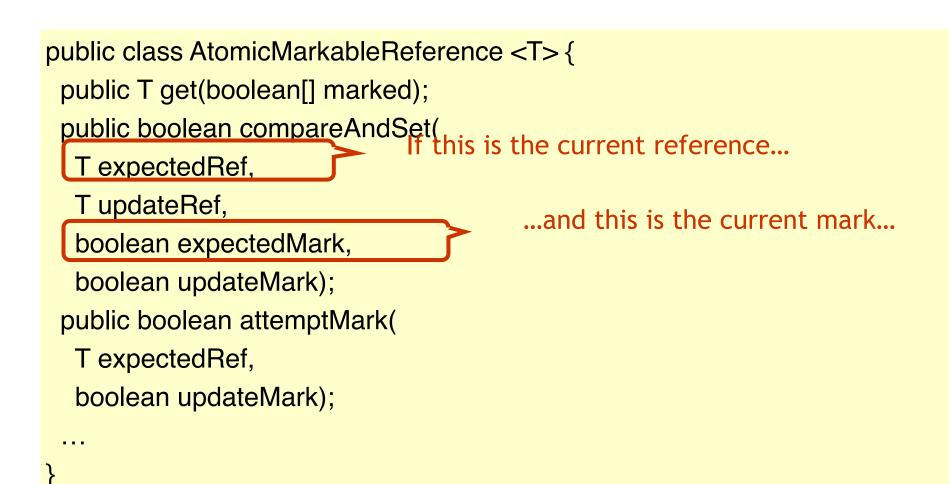
public class AtomicMarkableReference <T> {

public T get(boolean[] marked);

- public boolean compareAndSet(
 - T expectedRef,
 - T updateRef,
 - boolean expectedMark,
- boolean updateMark);
- public boolean attemptMark(
 - T expectedRef,
 - boolean updateMark);

Extract reference and mark (at index 0)

public class AtomicMarkableReference <T> { public T get(boolean[] marked); public boolean compareAndSet(T expectedRef, T updateRef, boolean expectedMark, boolean updateMark); public boolean attemptMark(T expectedRef, boolean updateMark);



public class AtomicMarkableReference <T> {

public T get(boolean[] marked);

public boolean compareAndSet(

T expectedRef,

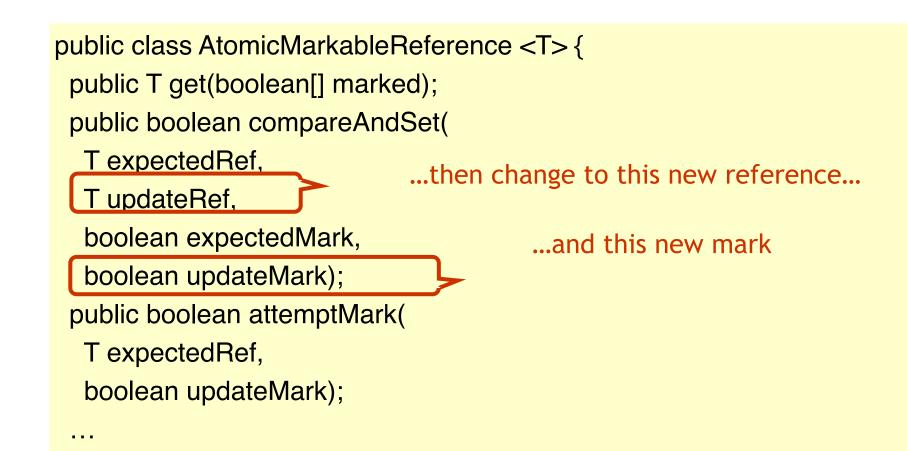
T updateRef,

boolean expectedMark, boolean updateMark); public boolean attemptMark(

T expectedRef,

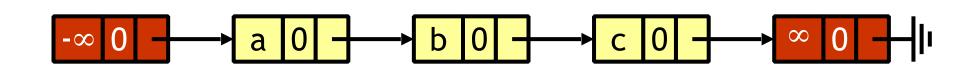
boolean updateMark);

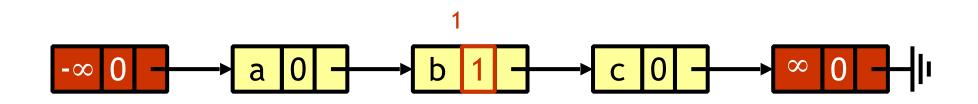
...then change to this new reference...

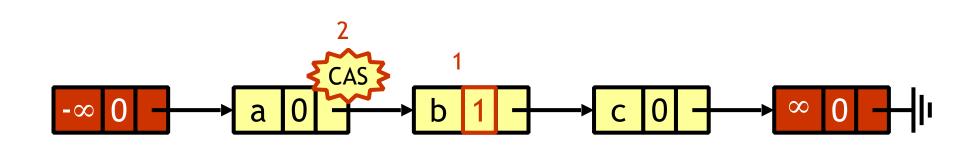


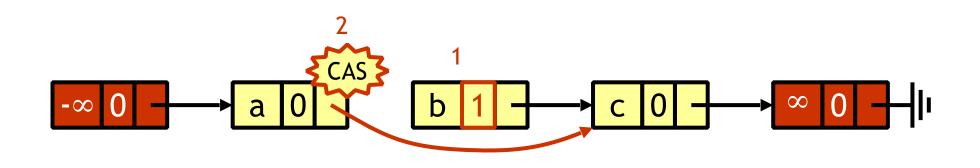
public class AtomicMarkableReference <T> { public T get(boolean[] marked); public boolean compareAndSet(T expectedRef, T updateRef, boolean expectedMark, boolean updateMark); public boolean attemptMark(If this is the current reference... T expectedRef, boolean updateMark);

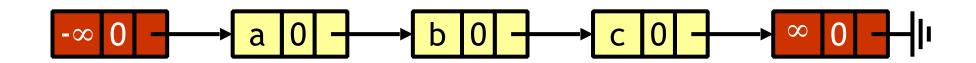
public class AtomicMarkableReference <T> { public T get(boolean[] marked); public boolean compareAndSet(T expectedRef, T updateRef, boolean expectedMark, boolean updateMark); public boolean attemptMark(T expectedRef, boolean updateMark); ...then change to this new mark



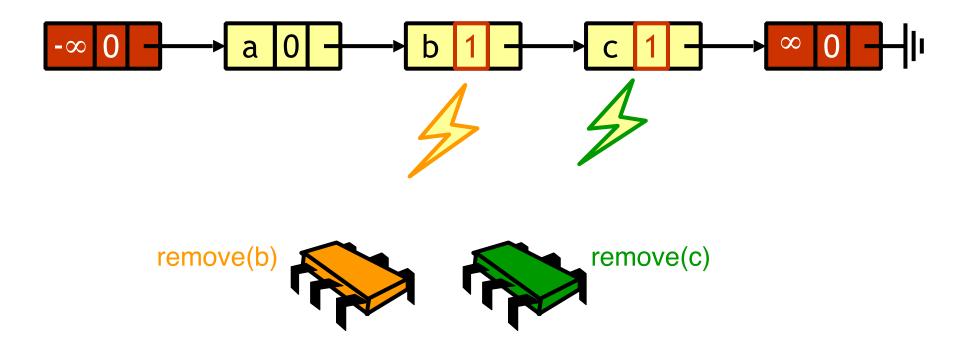


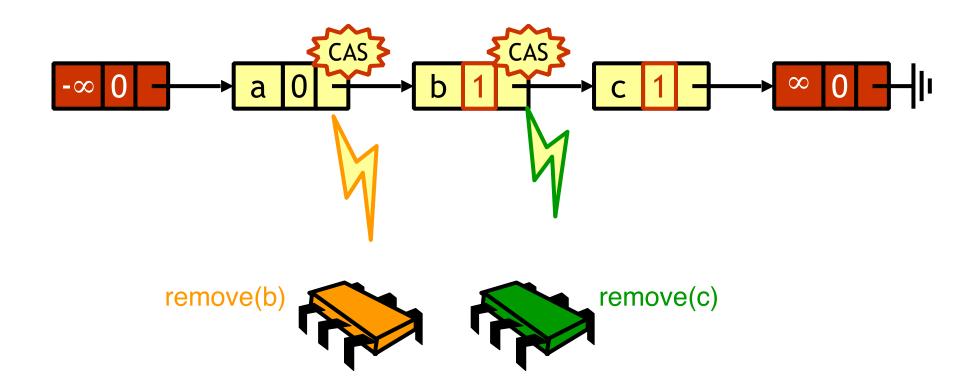


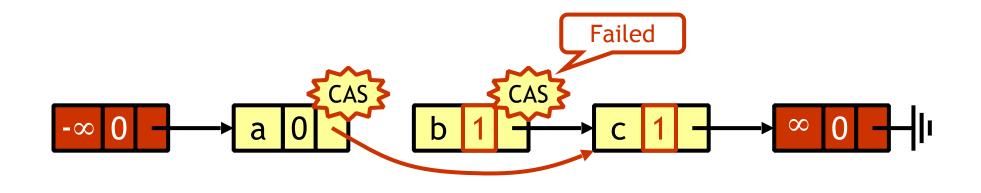






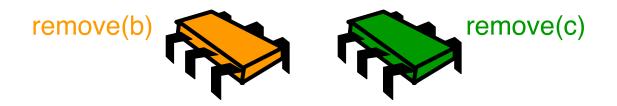










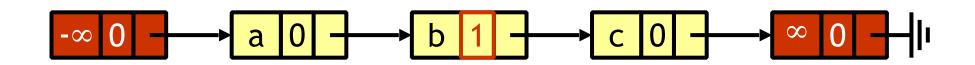




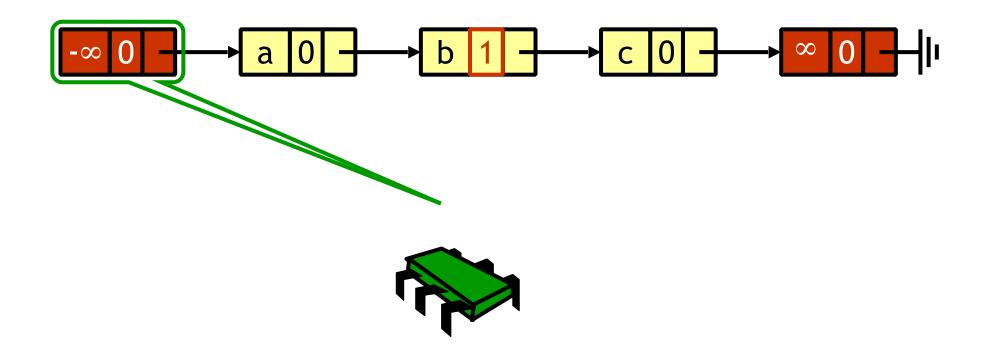


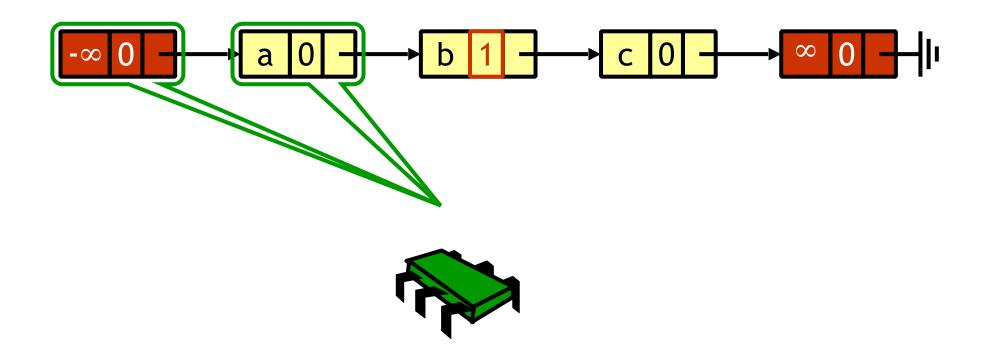
Traversing the List

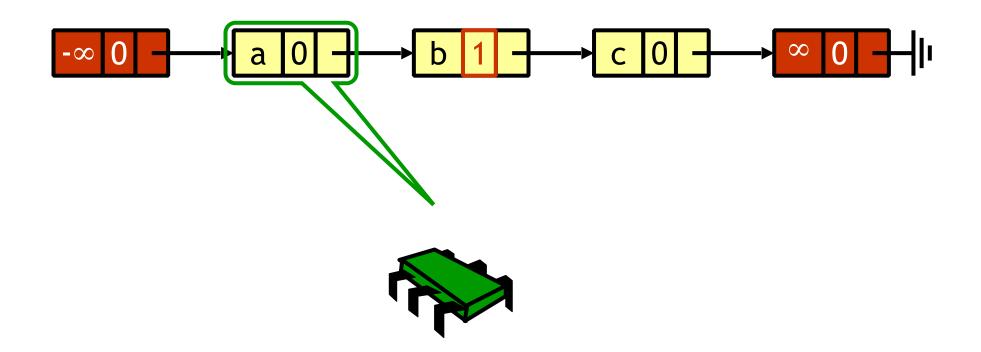
- What do you do when you find a "logically" deleted node in your path?
- ► Finish the job
 - CAS the predecessor's next field
 - Proceed (repeat as needed)

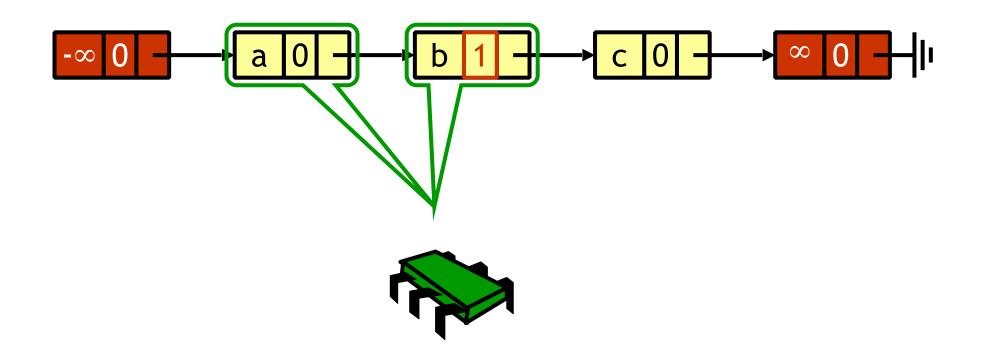


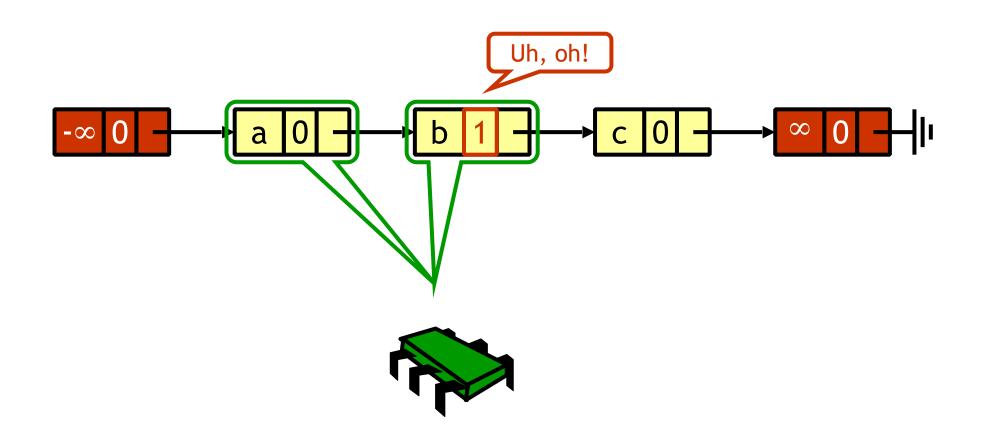


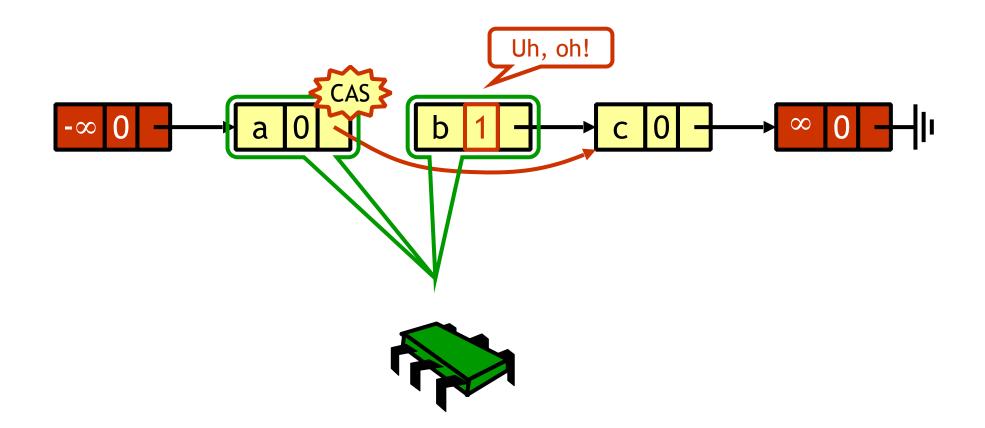


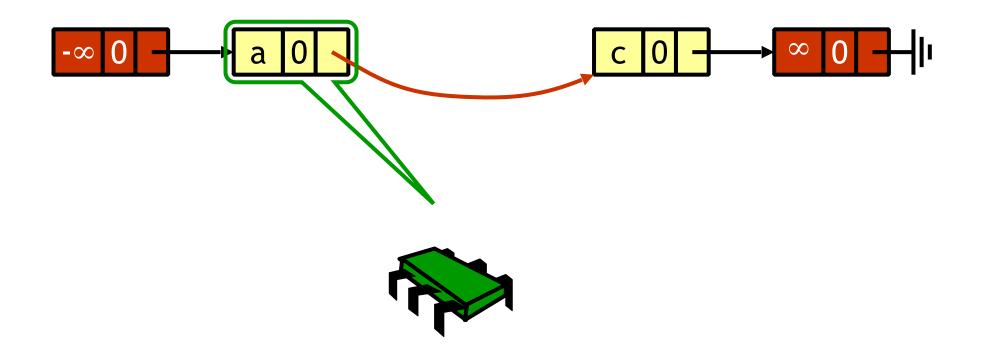


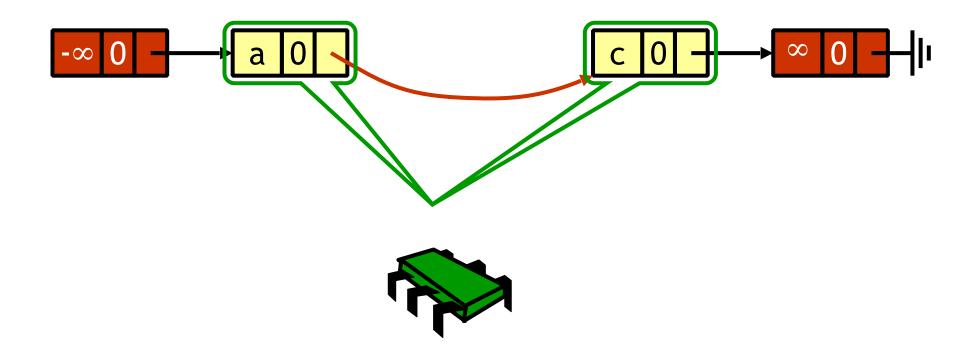








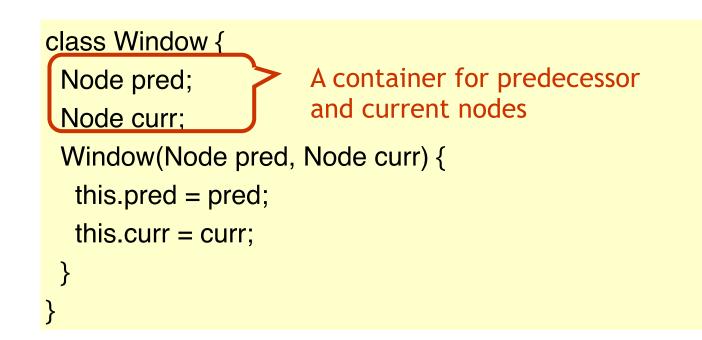




The Window Class

```
class Window {
   Node pred;
   Node curr;
   Window(Node pred, Node curr) {
    this.pred = pred;
    this.curr = curr;
   }
}
```

The Window Class

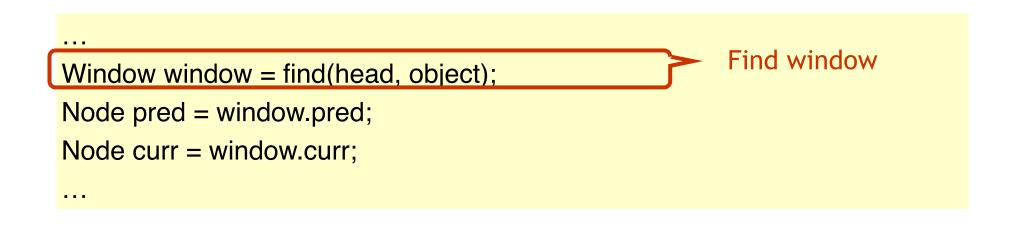


Using the Find Method

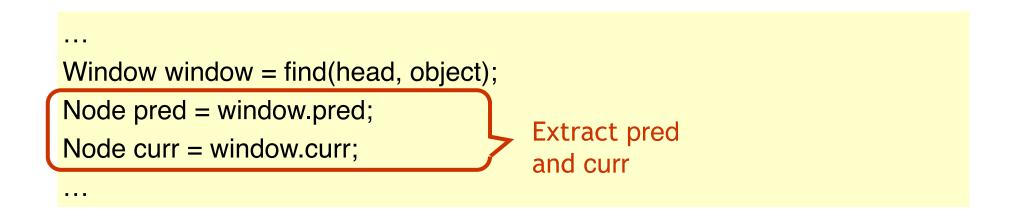
```
...
Window window = find(head, object);
Node pred = window.pred;
Node curr = window.curr;
```

. . .

Using the Find Method

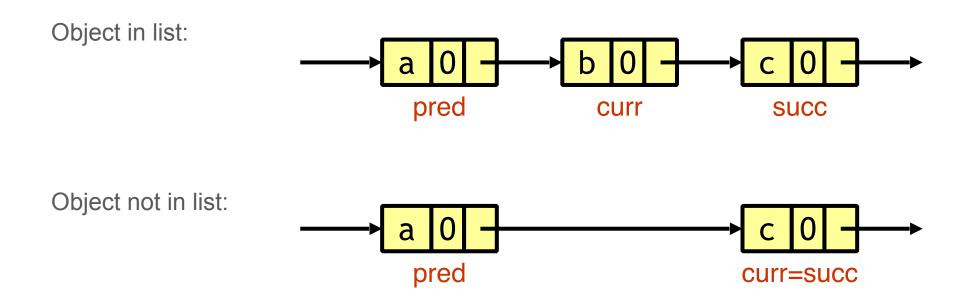


Using the Find Method



The Find Method

Window window = find(head, b); Node pred = window.pred; Node curr = window.curr;



```
public boolean remove(T object) {
 boolean b;
 while (true) {
  Window window = find(head, object);
  Node pred = window.pred, curr = window.curr;
  if (curr.object != object)
   return false;
  Node succ = curr.next.getReference();
  b = curr.next.compareAndSet(succ, succ, false, true);
  if (!b) continue;
  pred.next.compareAndSet(curr, succ, false, false);
  return true;
```

public boolean remove(T object) {		
boolean b;		
while (true) { Keep trying		
Window window = find(head, object);		
Node pred = window.pred, curr = window.curr;		
if (curr.object != object)		
return false;		
Node succ = curr.next.getReference();		
b = curr.next.compareAndSet(succ, succ, false, true);		
if (!b) continue;		
pred.next.compareAndSet(curr, succ, false, false);		
return true;		
}		

}

public boolean remove(T object) {	
boolean b;	Find neighbors
while (true) {	
Window window = find(head, object);	
Node pred = window.pred, curr = window.curr:	
if (curr.object != object)	
return false;	
Node succ = curr.next.getReference();	
b = curr.next.compareAndSet(succ, succ, false, true);	
if (!b) continue;	
pred.next.compareAndSet(curr, succ, false, false);	
return true;	
}	
}	

```
public boolean remove(T object) {
 boolean b;
 while (true) {
  Window window = find(head, object);
  Node pred = window.pred, curr = window.curr;
Not there
  if (curr.object != object)
   return false:
  Node succ = curr.next.getReference();
  b = curr.next.compareAndSet(succ, succ, false, true);
  if (!b) continue;
  pred.next.compareAndSet(curr, succ, false, false);
  return true;
```

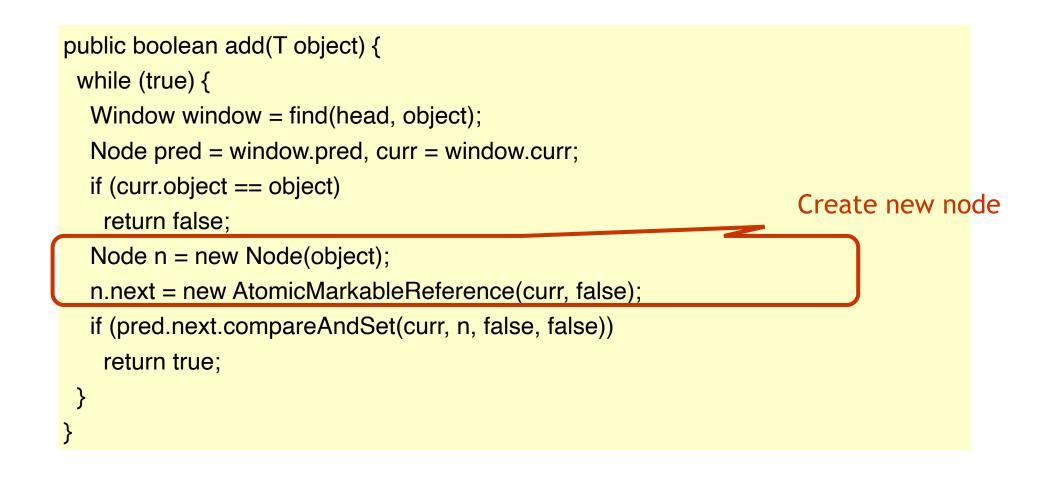
```
public boolean remove(T object) {
 boolean b;
 while (true) {
  Window window = find(head, object);
  Node pred = window.pred, curr = window.curr;
  if (curr.object != object)
                                                                Try to mark node
   return false;
                                                                       as deleted
  Node succ = curr.next.getReference();
  b = curr.next.compareAndSet(succ, succ, false, true);
  if (!b) continue;
  pred.next.compareAndSet(curr, succ, false, false);
  return true;
```

```
public boolean remove(T object) {
 boolean b;
 while (true) {
  Window window = find(head, object);
  Node pred = window.pred, curr = window.curr;
  if (curr.object != object)
   return false;
  Node succ = curr.next.getReference();
  b = curr.next.compareAndSet(succ, succ, false, true);
                                  If it fails, retry, otherwise job done
  if (!b) continue;
  pred.next.compareAndSet(curr, succ, false, false);
  return true;
```

```
public boolean remove(T object) {
 boolean b;
 while (true) {
  Window window = find(head, object);
  Node pred = window.pred, curr = window.curr;
  if (curr.object != object)
   return false;
  Node succ = curr.next.getReference();
  b = curr.next.compareAndSet(succ, succ, false, true);
  if (!b) continue;
  pred.next.compareAndSet(curr, succ, false, false);
  return true;
               Try to advance reference
               (if it fails, someone else did or will advance it)
```

```
public boolean add(T object) {
 while (true) {
  Window window = find(head, object);
  Node pred = window.pred, curr = window.curr;
  if (curr.object == object)
   return false;
  Node n = new Node(object);
  n.next = new AtomicMarkableReference(curr, false);
  if (pred.next.compareAndSet(curr, n, false, false))
   return true;
```

```
public boolean add(T object) {
 while (true) {
  Window window = find(head, object);
  Node pred = window.pred, curr = window.curr;
                                                 Already there
  if (curr.object == object)
   return false;
  Node n = new Node(object);
  n.next = new AtomicMarkableReference(curr, false);
  if (pred.next.compareAndSet(curr, n, false, false))
   return true;
```



```
public boolean add(T object) {
 while (true) {
  Window window = find(head, object);
  Node pred = window.pred, curr = window.curr;
  if (curr.object == object)
   return false;
  Node n = new Node(object);
  n.next = new AtomicMarkableReference(curr, false);
  if (pred.next.compareAndSet(curr, n, false, false))
   return true;
                                    Install new node, else retry loop
```

Wait-Free Contains

```
public boolean contains(T object) {
 boolean marked[] = new boolean[1];
 int key = object.hashCode();
 Node curr = this.head;
 while (curr.key <= key) {</pre>
  if (object == curr.object)
   break;
  curr = curr.next;
 }
 curr.next.get(marked);
 return (object == curr.object && !marked[0]);
}
```

Wait-Free Contains

```
public boolean contains(T object) {
  boolean marked[] = new boolean[1];
  int key = object.hashCode();
  Node curr = this.head;
  while (curr.key <= key) {
    if (object == curr.object)
      break;
    curr = curr.next;
  }
</pre>
```

Only difference from lazy list is that we get and check mark

```
curr.next.get(marked);
```

return (object == curr.object && !marked[0]);

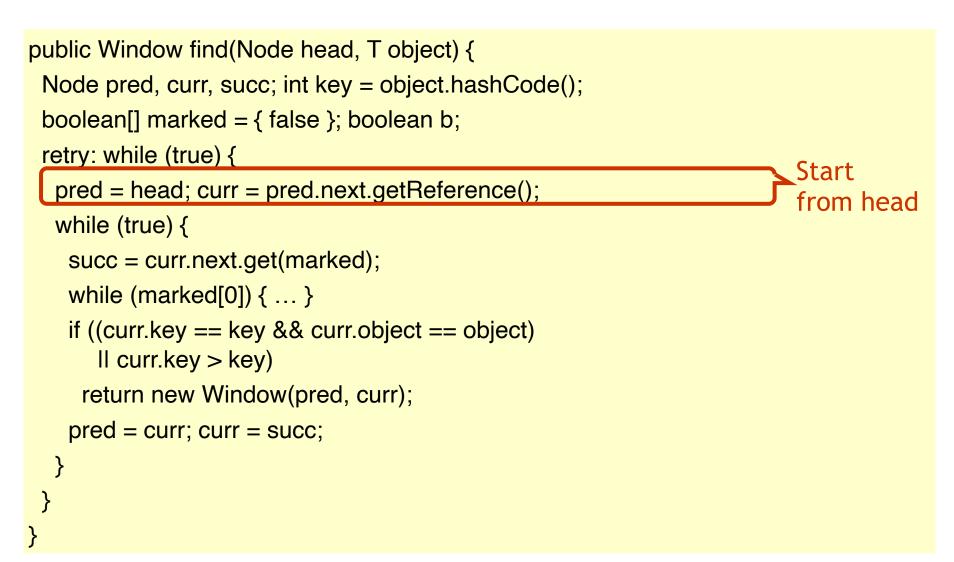
Lock-Free Find

```
public Window find(Node head, T object) {
 Node pred, curr, succ; int key = object.hashCode();
 boolean[] marked = { false }; boolean b;
 retry: while (true) {
  pred = head; curr = pred.next.getReference();
  while (true) {
   succ = curr.next.get(marked);
   while (marked[0]) { ... }
   if ((curr.key == key && curr.object == object)
      Il curr.key > key)
     return new Window(pred, curr);
   pred = curr; curr = succ;
  }
```

Lock-Free Find

```
public Window find(Node head, T object) {
 Node pred, curr, succ; int key = object.hashCode();
 boolean[] marked = { false }; boolean b;
                                     Restart if list changes while traversed
 retry: while (true) {
  pred = head; curr = pred.next.getReference();
  while (true) {
   succ = curr.next.get(marked);
   while (marked[0]) { ... }
   if ((curr.key == key && curr.object == object)
      II curr.key > key)
     return new Window(pred, curr);
   pred = curr; curr = succ;
```

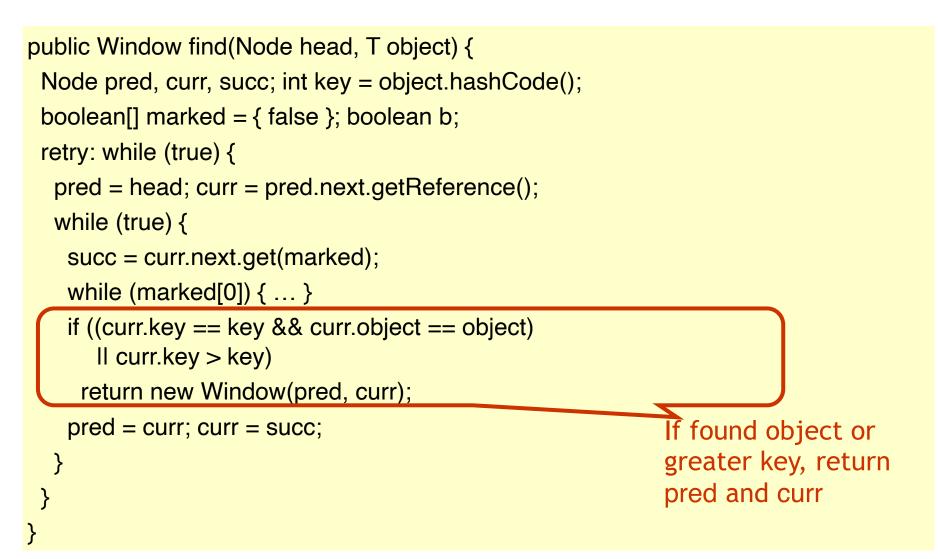
Lock-Free Find



```
public Window find(Node head, T object) {
 Node pred, curr, succ; int key = object.hashCode();
 boolean[] marked = { false }; boolean b;
 retry: while (true) {
  pred = head; curr = pred.next.getReference();
  while (true) {
                                 Move down the list
   succ = curr.next.get(marked);
   while (marked[0]) { ... }
   if ((curr.key == key && curr.object == object)
      II curr.key > key)
     return new Window(pred, curr);
   pred = curr; curr = succ;
  }
```

```
public Window find(Node head, T object) {
 Node pred, curr, succ; int key = object.hashCode();
 boolean[] marked = { false }; boolean b;
 retry: while (true) {
  pred = head; curr = pred.next.getReference();
  while (true) {
                                                 Get successor and mark
   succ = curr.next.get(marked);
   while (marked[0]) { ... }
   if ((curr.key == key && curr.object == object)
      II curr.key > key)
     return new Window(pred, curr);
   pred = curr; curr = succ;
```

```
public Window find(Node head, T object) {
 Node pred, curr, succ; int key = object.hashCode();
 boolean[] marked = { false }; boolean b;
 retry: while (true) {
  pred = head; curr = pred.next.getReference();
  while (true) {
   succ = curr.next.get(marked);
   while (marked[0]) { ... }
                                          Try to remove deleted nodes
   if ((curr.key == key && curr.object == object)
      II curr.key > key)
     return new Window(pred, curr);
   pred = curr; curr = succ;
```



```
public Window find(Node head, T object) {
 Node pred, curr, succ; int key = object.hashCode();
 boolean[] marked = { false }; boolean b;
 retry: while (true) {
  pred = head; curr = pred.next.getReference();
  while (true) {
   succ = curr.next.get(marked);
   while (marked[0]) { ... }
   if ((curr.key == key && curr.object == object)
      II curr.key > key)
     return new Window(pred, curr);
   pred = curr; curr = succ;
            Otherwise advance window
           and loop again
```

```
while (marked[0]) {
    b = pred.next.compareAndSet(curr, succ, false, false);
    if (!b) continue retry;
    curr = succ;
    succ = curr.next.get(marked);
}
```

Try to snip out node

while (marked[0]) {

```
b = pred.next.compareAndSet(curr, succ, false, false);
```

if (!b) continue retry;

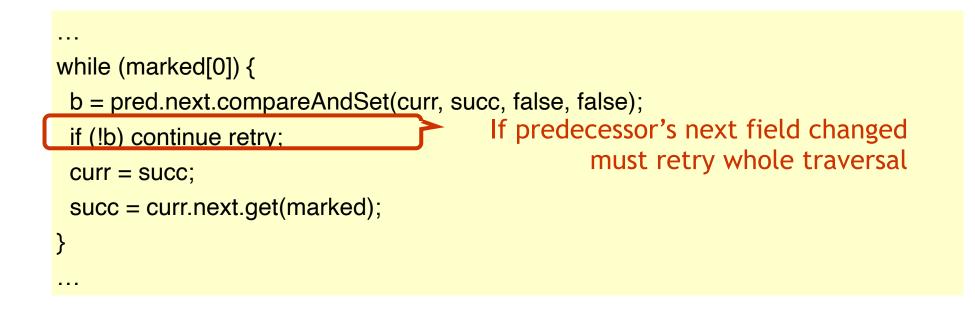
```
curr = succ;
```

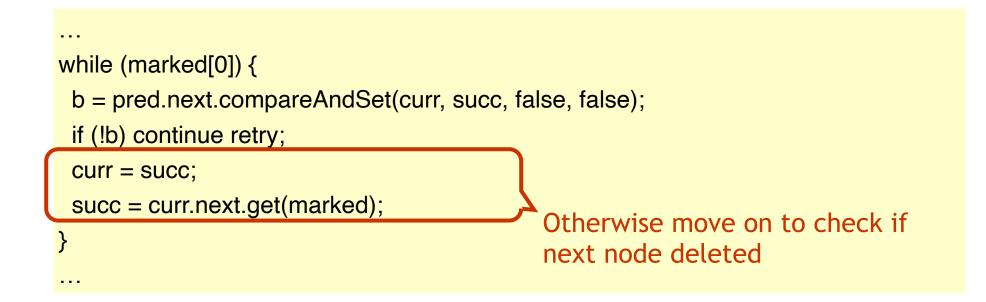
. . .

}

. . .

```
succ = curr.next.get(marked);
```

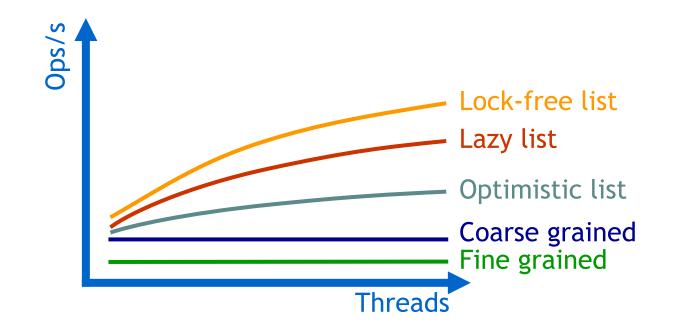




Summary: Lock–Free List

- AtomicMarkableReference atomically updates mark and reference
 - Prevents manipulation of logically-removed next pointer
- > Lock-free add() and remove()
 - Remove performs logical removal, may leave node
- Lock-free find() traverses both marked and removed nodes
 - Physically clean up (remove) marked nodes

Performance

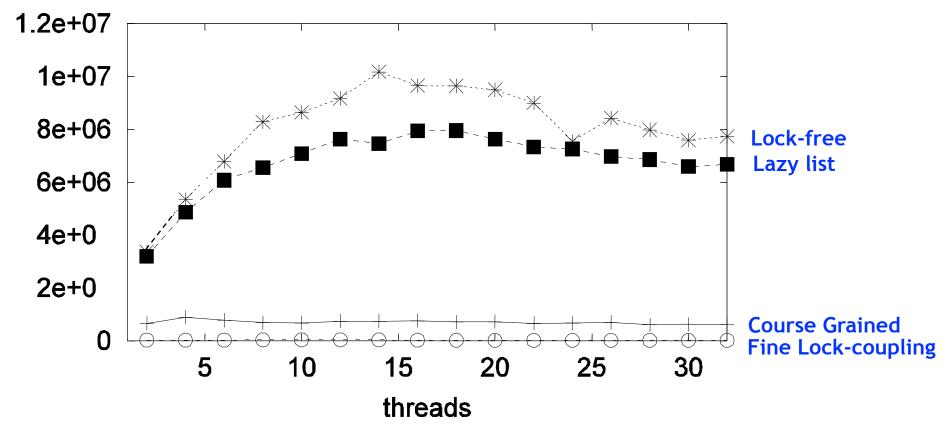


Performance

On 16 node shared memory machine Benchmark throughput of Java List-based Set algs. Vary % of Contains() method Calls.

High Contains Ratio

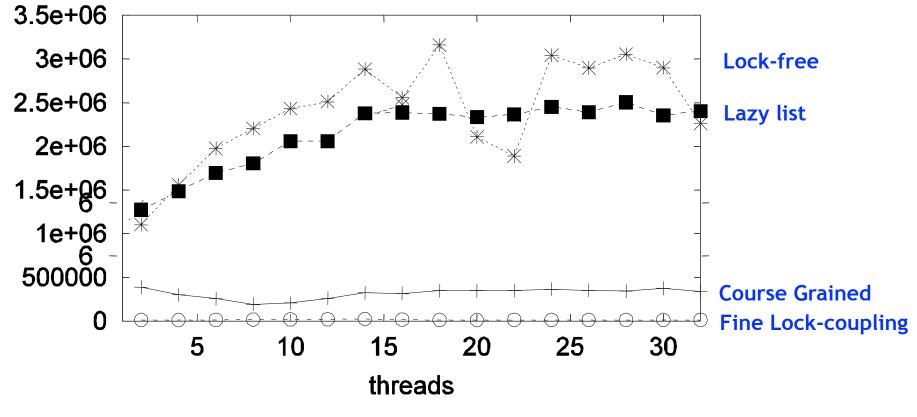
Ops/sec (90% reads/ 10% updates)



© Herlihy-Shavit

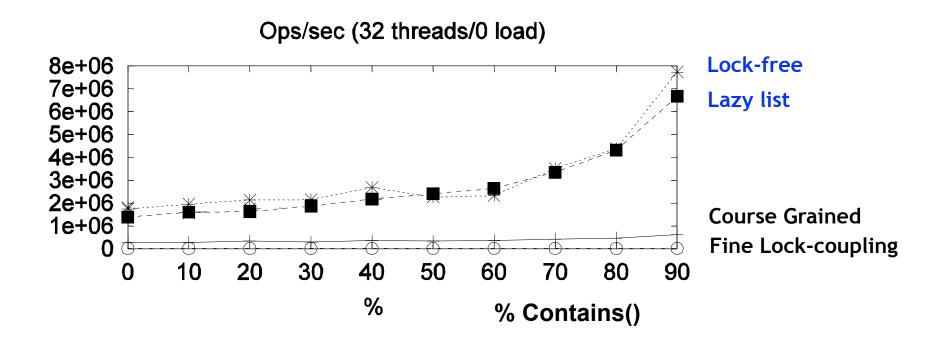
Low Contains Ratio

Ops/sec (50% reads/ 50% updates)



[©] Herlihy-Shavit

As Contains Ratio Increases



Summary

- Four "generic" approaches to concurrent data structure design
 - Fine-grained locking
 - Optimistic synchronization
 - Lazy synchronization
 - Lock-free synchronization

"To Lock or Not to Lock"

- ► Locking vs. non-blocking
 - Extremist views on both sides
- Nobler to compromise, combine locking and nonblocking
 - Example: Lazy list combines blocking add() and remove() and a wait-free contains()
 - Blocking/non-blocking is a property of a method